

MH within Partially Collapsed Gibbs Samplers with Applications in High-Energy Astrophysics

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Outline

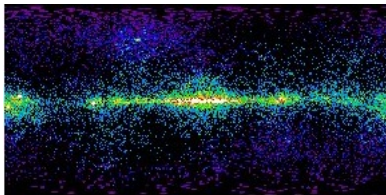
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 - Scientific Goals and Instruments
 - Instrumental Calibration
- 2 Statistical Computation
 - Partially Collapsed Gibbs Samplers
 - MH within Partially Collapsed Gibbs Samplers
- 3 Back to Calibration Uncertainty
 - A Pragmatic Bayesian Solution
 - The Fully Bayesian Solution
- 4 Empirical Illustrations
 - Simulation Study
 - Radio Loud Quasar Spectra

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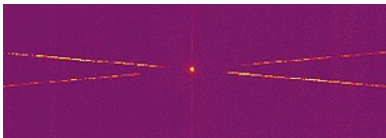
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High-Energy Astrophysics

- Produced by multi-million degree matter, e.g., magnetic fields, extreme gravity, or explosive forces.
- Provide understanding into the hot turbulent regions of the universe.
- X-ray and γ -ray detectors typically count a *small number of photons* in each of a *large number of pixels*.

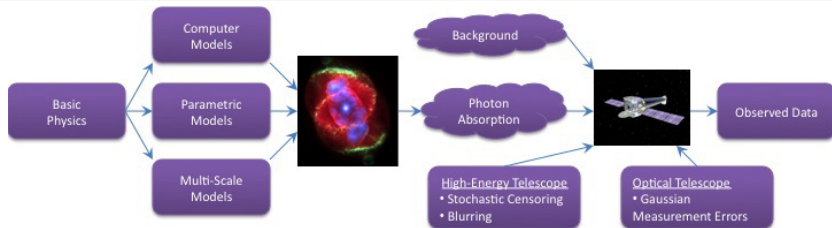


EGERT γ -ray counts $>1\text{GeV}$
(entire sky and mission life).



Dispersion grating spectrum of an Active Galactic Nucleus; emission from matter accreting onto a massive Black Hole.

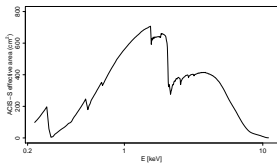
The Basic Statistical Model



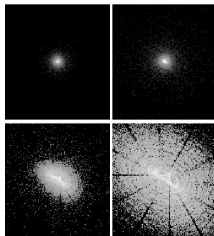
- Aim to formulate models in terms of specific questions of scientific interest.
- Embed complex physics-based models into multi-level statistical models.
- Must account for complexities of data generation.
- State of the art data and computational techniques enable us to fit the resulting complex model.

Calibration Products

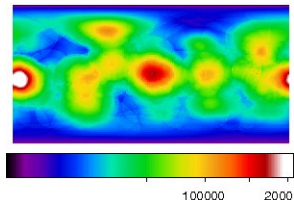
- Analysis is highly dependent on *Calibration Products*:
 - Effective area records sensitivity as a function of energy
 - Energy redistribution matrix can vary with energy/location
 - Point Spread Functions can vary with energy and location
 - Exposure Map shows how effective area varies in an image
- In this talk we focus on uncertainty in the effective area.



A CHANDRA effective area.



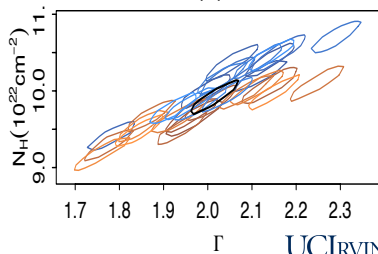
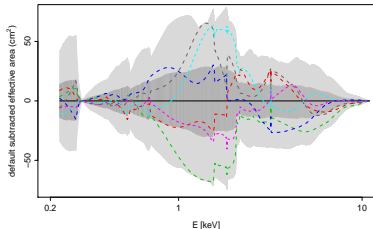
Sample Chandra psf's
(Karovska et al., ADASS X)



EGRET exposure map
(area \times time)

Derivation of Calibration Products

- Prelaunch ground-based and post-launch space-based empirical assessments.
- Aim to capture deterioration of detectors over time.
- Complex computer models of subassembly components.
- Calibration scientists provide a sample representing uncertainty
- Use PCA to formulation a degenerate Gaussian approximate prior on A .



Two Possible Target Distributions

We consider inference under:

A PRAGMATIC BAYESIAN TARGET: $\pi_0(A, \theta) = p(A)p(\theta|A, Y)$.

THE FULLY BAYESIAN POSTERIOR: $\pi(A, \theta) = p(A|Y)p(\theta|A, Y)$.

Concerns:

Statistical Fully Bayesian target is “correct”.

Cultural Astronomers have concerns about letting the current data influence calibration products.

Computational Both targets pose challenges, but pragmatic Bayesian target is easier to sample.

Practical How different are $p(A)$ and $p(A|Y)$?

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The Partially Collapsed Gibbs Sampler

A Gibbs sampler:

STEP 1: $\psi_1 \sim p(\psi_1|\psi_2)$

STEP 2: $\psi_2 \sim p(\psi_2|\psi_1)$

A Partially Collapsed Gibbs (PCG) Sampler:

STEP 1: $\psi_1 \sim p(\psi_1|g(\psi_2))$

STEP 2: $\psi_2 \sim p(\psi_2|h(\psi_1))$

- g and/or h are non-invertible functions.
- Generalizes blocking & collapsing, involves incompatibility.
- Step order can effect stationary distribution.
- Improves convergence rate (van Dyk & Park, 2008, JASA).
- Spectral analysis, time series, and multiple imputation (van Dyk & Park in press; 2009 JCGS; 2008 ApJ).

Metropolis-Hastings within Gibbs & PCG Sampling

An MH within Gibbs sampler:

STEP 1: $\psi_1 \sim \mathcal{K}(\psi_1|\psi)$ via MH with limiting dist. $p(\psi_1|\psi_2)$

STEP 2: $\psi_2 \sim p(\psi_2|\psi_1)$

Using MH within the Partially Collapsed Gibbs Sampler:

STEP 1: $\psi_1 \sim \mathcal{K}(\psi_1|\psi)$ via MH with limiting dist. $p(\psi_1)$

STEP 2: $\psi_2 \sim p(\psi_2|\psi_1)$

- Need only evaluate $p(\psi_1) = p(\psi_1, \psi_2)/p(\psi_2|\psi_1)$.
- If MH were unnecessary, obtain i.i.d. draws from $p(\psi_1, \psi_2)$.
- Improved convergence if ψ_1 and ψ_2 are highly correlated.
- With MH we must verify the stationary distribution.

But... Be Careful!

Another MH within Gibbs Sampler:

STEP 1: $\psi_1 \sim p(\psi_1|\psi_2)$

STEP 2: $\psi_2 \sim \mathcal{K}(\psi_2|\psi_1)$ via MH with limiting dist. $p(\psi_2|\psi_1)$

A *naive* Sampler:

STEP 1: $\psi_1 \sim p(\psi_1)$

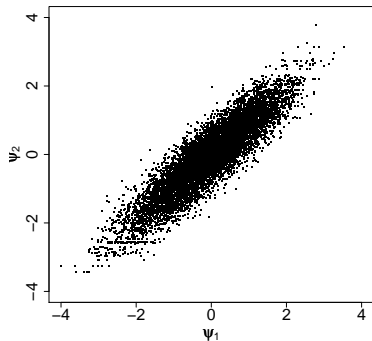
STEP 2: $\psi_2 \sim \mathcal{K}(\psi_2|\psi_1)$ via MH with limiting dist. $p(\psi_2|\psi_1)$

Simulation Study:

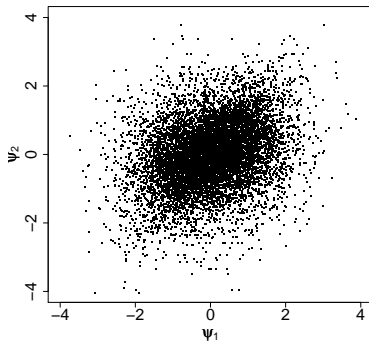
- Suppose $\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \sim \mathbf{N}_2 \left[\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0.9 \\ 0.9 & 1 \end{pmatrix} \right]$
- MH: a Gaussian jumping rule centered at previous draw.

Be Careful When Combining MH and PCG Sampling

MH within Gibbs Sampler



The *naive* Sampler



What Goes Wrong

The *naive* Sampler:

STEP 1: $\psi_1^{(t)} \sim p(\psi_1)$

STEP 2: $\psi_2^{(t)} \sim \mathcal{K}(\psi_2 | \psi_1^{(t)}, \psi_2^{(t-1)})$ via Metropolis Hastings

The update of ψ_2 depends on both $\psi_1^{(t)}$ and $\psi_2^{(t-1)}$:

- The limiting distribution of the MH step is $p(\psi_2 | \psi_1^{(t)})$.
- If the proposal is rejected, ψ_2 is set to $\psi_2^{(t-1)}$.

BUT: $\psi_1^{(t)} \sim p(\psi_1)$ —independent of $\psi_2^{(t-1)}$ *at every iteration.*

STEP 2 *will never produce samples from* $p(\psi_2 | \psi_1)$.

Constructing a Legitimate MH within PCG Sampler

1. Marginalizing

$$\begin{array}{l} p(\psi_1|\psi'_2) \\ \mathcal{K}(\psi_2|\psi') \text{ w/} \\ \text{limit } p(\psi_2|\psi_1) \end{array} \longrightarrow \begin{array}{l} p(\psi_1|\psi'_2) \\ \mathcal{K}(\psi_1, \psi_2|\psi') \text{ w/} \\ \text{limit } p(\psi_1, \psi_2) \end{array}$$

Move quantities from the right to the left of the conditioning sign. This does not alter the stationary dist'n, but improves the rate of convergence.

2. Permuting

$$\longrightarrow \begin{array}{l} \mathcal{K}(\psi_1, \psi_2|\psi') \text{ w/} \\ \text{limit } p(\psi_1, \psi_2) \\ p(\psi_1|\psi'_2) \end{array}$$

Permute the order of the steps. This can have minor effects on the rate of convergence, but does not affect the stationary distribution.

3. Trimming

$$\longrightarrow \begin{array}{l} \mathcal{K}(\psi_2|\psi') \text{ w/} \\ \text{limit } p(\psi_2) \\ p(\psi_1|\psi'_2) \end{array}$$

Remove quantities that are not part of the transition kernel. This does not effect the stochastic mapping or the rate of convergence.

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Back to Calibration Uncertainty

We consider inference under:

A PRAGMATIC BAYESIAN TARGET: $\pi_0(\mathbf{A}, \theta) = p(\mathbf{A})p(\theta|\mathbf{A}, Y)$.

THE FULLY BAYESIAN POSTERIOR: $\pi(\mathbf{A}, \theta) = p(\mathbf{A}|Y)p(\theta|\mathbf{A}, Y)$.

Sampling either $\pi_0(\mathbf{A}|\theta)$ or $\pi(\mathbf{A}|\theta)$ is complicated.

- We only have a computer model generated sample of $p(\mathbf{A})$.
- $\pi(\mathbf{A}|\theta) = p(\mathbf{A}|\theta, Y)$ can easily be evaluated.
- $\pi_0(\mathbf{A}|\theta) \propto p(\mathbf{A}, \theta|Y)p(Y)/p(Y|\mathbf{A})$ is difficult to evaluate.

Have a sample of $\pi_0(\mathbf{A}) = p(\mathbf{A})$, suggesting PCG sampler.

A Pragmatic Bayesian Solution

A simple Markov Chain Monte Carlo Procedure

- Sample effective area uniformly from calibration sample:
 $A \sim p(A)$.
- Sample model parameters in the usual way, conditioning on the current sample of the effective area:
 $\theta \sim p(\theta|A, Y)$.

To obtain independent draws from $\pi_0(A, \theta)$.

This strategy in effect replaces a posterior draw with a prior draw when updating the effective area.

A Pragmatic Bayesian Solution

Unfortunately, update of θ uses MH (pyBLoCXS in Sherpa) with limiting distribution $p(\theta|A, Y)$.

The *naive* Sampler Revisited:

STEP 1: $A^{(t)} \sim p(A)$

STEP 2: $\theta^{(t)} \sim \mathcal{K}(\theta|A^{(t)}, \theta^{(t-1)})$ via Metropolis Hastings.

A simple solution is a PCG (Simple Collapsed) Gibbs Sampler:

STEP 1: $A^{(t)} \sim p(A)$

STEP 2: Iteratively sample $\theta^{(t-1+k/K)} \sim \mathcal{K}(\theta|A^{(t)}, \theta^{(t-1)})$
via MH to obtain $\theta^{(t)} \sim p(\theta|A^{(t)})$.

In practice a moderate value of K (<10) is sufficient.

Sampling the Full Posterior Distribution

THE FULLY BAYESIAN POSTERIOR: $\pi(A, \theta) = p(A|Y)p(\theta|A, Y)$.

- Sampling $\pi(A, \theta) = p(A, \theta|Y)$ is complicated because we only have a computer-model generated sample of $p(A)$ rather than an analytic form.
- But PCA gives a *degenerate normal* approximation, representing A (high dimensional) as deterministic function of e (low dimensional).
- We can construct an MCMC sampler of $p(e, \theta|Y)$.

A Prototype Fully Bayesian Sampler

An MH within Gibbs Sampler:

STEP 1: $e \sim \mathcal{K}(e|e', \theta')$ via MH with limiting dist'n $p(e|\theta, Y)$

STEP 2: $\theta \sim \mathcal{K}(\theta|e', \theta')$ via MH with limiting dist'n $p(\theta|e, Y)$

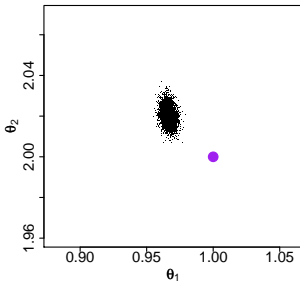
- STEP 1: Gaussian Metropolis jumping rule centered at e' .
- STEP 2: Simplified pyBLoCXS (no rmf or background).

A Simulation.

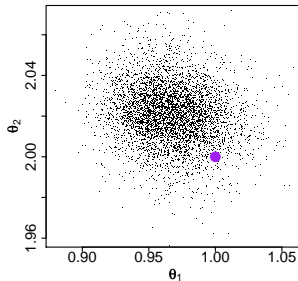
- Sampled 10^5 counts from a power law spectrum: e^{-2E} .
- A_{true} is 1.5σ from the center of the calibration sample.

Sampling From the Full Posterior

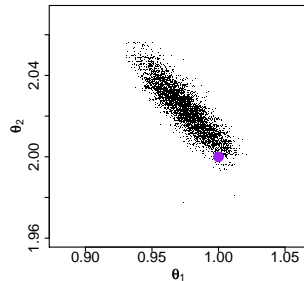
Default Effective Area



Pragmatic Bayes



Fully Bayes



θ_1 = normalization, θ_2 = power law parameter
purple bullet = truth

*Pragmatic Bayes is clearly better than current practice,
but a Fully Bayesian Method is the ultimate goal.*

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The Simulation Studies

Simulated Spectra

- Spectra were sampled using an absorbed power law,

$$f(E_j) = \alpha e^{-N_H \chi(E_j)} E_j^{-\Gamma},$$

accounting for instrumental effects; E_j is the energy of bin j .

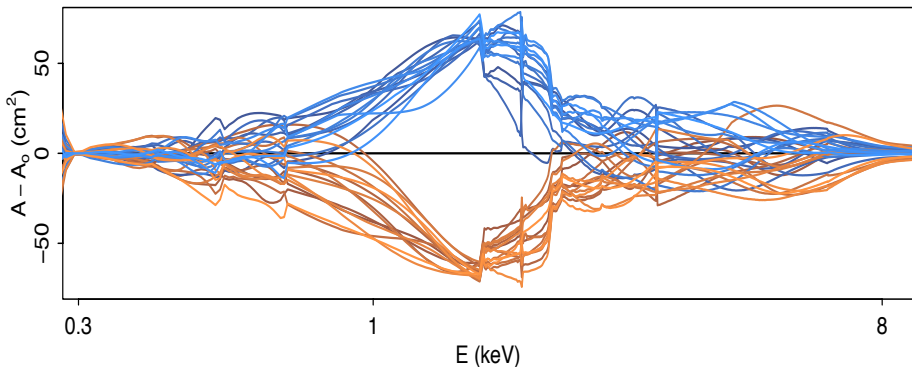
- Parameters (Γ and N_H) and sample size/exposure times:

	Effective Area		Nominal Counts		Spectral Model	
	Default	Extreme	10^5	10^4	Hard [†]	Soft [‡]
SIM 1	X		X		X	
SIM 2	X		X			X
SIM 3	X			X	X	

[†]An absorbed powerlaw with $\Gamma = 2$, $N_H = 10^{23}/\text{cm}^2$

[‡]An absorbed powerlaw with $\Gamma = 1$, $N_H = 10^{21}/\text{cm}^2$

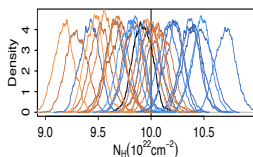
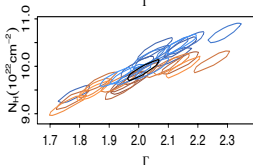
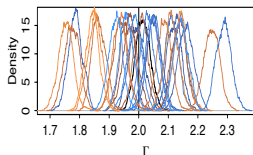
30 Most Extreme Effective Areas in Calibration Sample



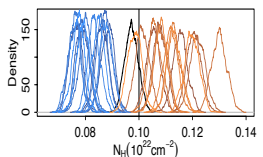
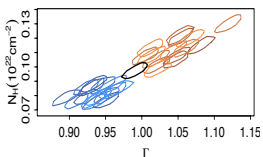
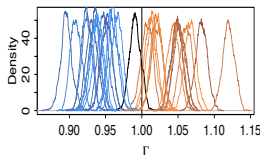
15 largest and 15 smallest determined by maximum value

The Effect of Calibration Uncertainty

SIMULATION 1

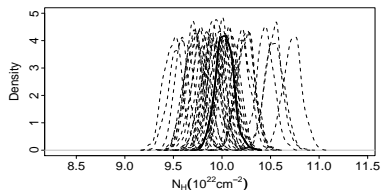
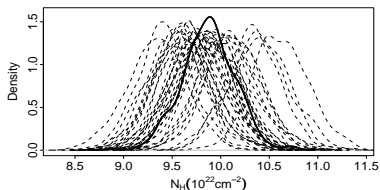
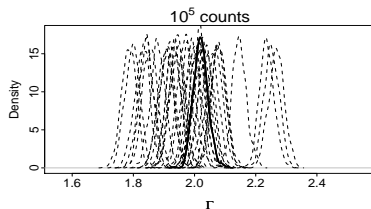
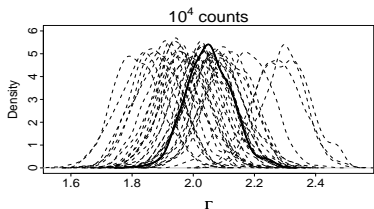


SIMULATION 2



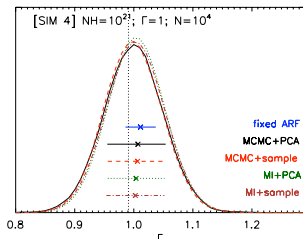
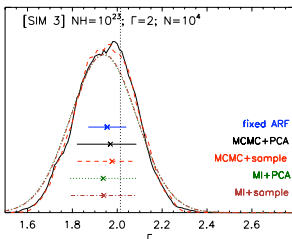
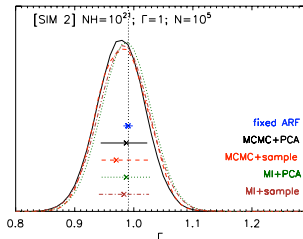
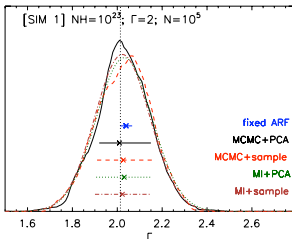
- Columns represent two simulated spectra.
- True parameters are horizontal lines.
- Posterior under default calibration is plotted in black.
- The posterior is highly sensitive to the choice of effective area!

The Effect of Sample Size

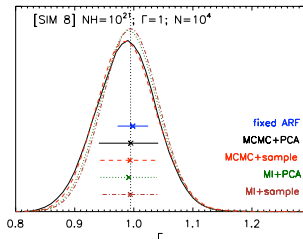
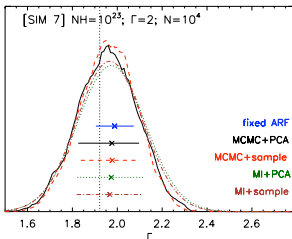
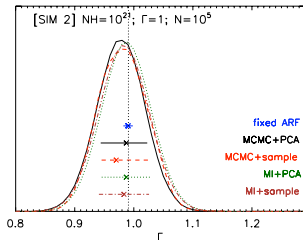
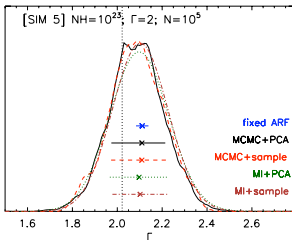


*The effect of Calibration Uncertainty is more pronounced
with larger sample sizes.*

Use of Default May Underestimate Errors



Use of Default May Bias Results

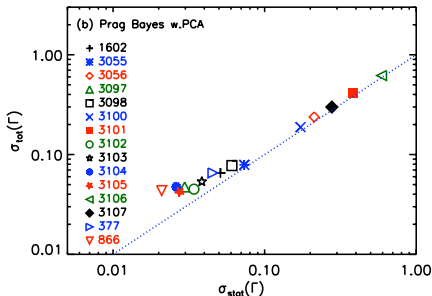
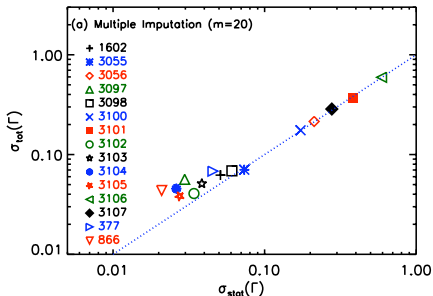


The Effect of Sample Size Redux

A Set of Radio Loud Quasar Spectra

- MI and the pragmatic Bayesian Method with PCA approximation to the calibration sample was applied to a set of Quasars.
- Quasars are among the most distant distinguishable astronomical objects.
- The sixteen Quasar observations varied in size from 20 to over 10,000 photon counts.

Results



*For large spectra calibration uncertainty swamps statistical error.
 Eventually there is no gain for increased exposure time.*

Simple Summaries of Complex Variability

We use Principal Component Analysis to represent uncertainty:

$$A \sim A_0 + \bar{\delta} + \sum_{j=1}^m e_j r_j \mathbf{v}_j,$$

A_0 : default effective area,

$\bar{\delta}$: mean deviation from A_0 ,

r_j and \mathbf{v}_j : first m principle component eigenvalues & vectors,

e_j : independent standard normal deviations.

Capture 95% of variability with $m = 6 - 9$.

For Further Reading I



Lee, H., Kashyap, V., van Dyk, D., Connors, A., Drake, J., Izem, R., Min, S., Park, T., Ratzlaff, P., Siemiginowska, A., and Zezas, A.

Accounting for Calibration Uncertainties in X-ray Analysis: Effective Area in Spectral Fitting.
In preparation.



van Dyk, D. A. and Park, T.

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Park, T. and van Dyk, D. A.

Partially Collapsed Gibbs Samplers: Illustrations and Applications.
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Searching for Narrow Emission Lines in X-ray Spectra: Computation and Methods.
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