Simulating infinite vortex lattices in superfluids

Luca Mingarelli, Eric E Keaveny and Ryan Barnett

Department of Mathematics, Imperial College London, London SW7 2AZ, UK
E-mail: l.mingarelli13@ic.ac.uk

Received 29 February 2016, revised 24 April 2016
Accepted for publication 25 April 2016
Published 24 May 2016

Abstract
We present an efficient framework to numerically treat infinite periodic vortex lattices in rotating superfluids described by the Gross–Pitaevskii theory. The commonly used split-step Fourier (SSF) spectral methods are inapplicable to such systems as the standard Fourier transform does not respect the boundary conditions mandated by the magnetic translation group. We present a generalisation of the SSF method which incorporates the correct boundary conditions by employing the so-called magnetic Fourier transform. We test the method and show that it reduces to known results in the lowest-Landau-level regime. While we focus on rotating scalar superfluids for simplicity, the framework can be naturally extended to treat multicomponent systems and systems under more general ‘synthetic’ gauge fields.

Keywords: BEC, cold atoms, synthetic gauge field, vortex lattice, GPE

1. Introduction

Superfluid phases of matter have attracted interest over many years and can occur in diverse physical systems including liquid helium, neutron stars, and ultracold atomic gases [1]. The response of a superfluid to mechanical rotation demonstrates one of the most remarkable features of these systems. Rather than rotate like a classical fluid, a superfluid will instead nucleate quantised vortices [2, 3] which carry angular momentum. In the limit of many vortices, a vortex lattice will form. There exist several thorough review articles and books addressing vortices in superfluids including [4–7].

Bose–Einstein condensates (BECs) of ultracold atomic gases represent a quintessential example of a superfluid. Within Gross–Pitaevskii mean field theory, these systems are described by a macroscopic wave function \( \psi \) and the system’s energy in a rotating frame of reference with a harmonic trapping potential is given by

\[
E[\psi] = \int \mathrm{d}x \mathrm{d}y \left[ \frac{\hbar^2}{2m} \left| \nabla \psi \right|^2 + \frac{1}{2} m \omega^2 r^2 |\psi|^2 + \frac{g}{2} |\psi|^4 - \psi^\dagger \left( \begin{array}{cc} -\omega_x^2 & \omega_y \\ -\omega_y & \omega_x^2 \end{array} \right) \psi \right] + \frac{g}{2} |\psi|^4 - \mu |\psi|^2.
\]

In this equation, \( m \) is the mass of the constituent bosons, \( \omega \) is the frequency of the harmonic trapping potential, \( L = -i\hbar (\partial_x \dot{y} - \dot{y} \partial_x) \) is the angular momentum operator, \( \Omega \) is the rotational frequency, \( g \) is the interaction parameter, and \( \mu \) is the chemical potential. In the second line of (1), the energy functional is rearranged in a convenient way, where the gauge field \( A_i = \Omega m (-y, x) \) and effective harmonic oscillator frequency \( \omega_{\text{eff}} = \sqrt{\omega^2 - \Omega^2} \) are introduced. The dynamics of the condensate is given by the corresponding Gross–Pitaevskii equation (GPE) \( i\hbar \partial_t \psi = \Delta E/\hbar \psi^* \). We will focus on cases where the minimum of (1) is a state with many vortices. While there is little doubt that such ground states correspond to triangular vortex lattices, we note that multi-component systems, including mixtures, spinor condensates [8], and multicomponent systems under more general gauge fields [9] can have much richer vortex lattices.

In order to understand vortex solutions of the GPE, it is helpful to consider a number of length scales naturally
emerging from (1). The healing length defined as $\xi = \sqrt{\frac{\hbar^2}{2m\rho^2}}$, where $\rho$ is the average superfluid density, gives the characteristic core size of the vortices. According to the Feynman relation [3], the density of the vortices is given by $\rho_v = \frac{\pi n}{\frac{\pi}{\xi}} = \frac{1}{2\pi\xi^2}$ where, in analogy with quantum Hall systems, we have introduced the ‘magnetic length’ $\ell_B = \frac{\hbar}{\sqrt{2\pi\epsilon}}$. This length scale provides the characteristic separation between vortices. Finally, $\omega_{\text{eff}}$ sets the effective trapping length scale $\ell_H = \frac{\hbar}{\sqrt{2m\rho^2} \omega_{\text{eff}}}$. For weak interactions such that $\ell_H \ll \xi$, $\ell_H$ gives the spatial extent of the condensate. On the other hand, for stronger interactions where $\ell_H \gg \xi$, the size of the condensate is given by the Thomas–Fermi radius $R_{\text{TF}} \sim \ell_H/\xi$.

Minimisation of (1) and its multi-component extensions for the purpose of investigating vortex lattices typically involves one of two approaches. The first approach involves projecting the wave function $\psi$ onto the lowest Landau level (LLL) and thereby writing $\psi(x, y) = \sum \phi_n \phi_n(x, y)$ where $\phi_n(x, y) \propto (x + iy)^n e^{-[(x^2 + y^2)/2\ell_B]^\alpha}$ are lowest-Landau-level eigenfunctions. The projected wave function is then inserted into (1) and the energy is minimised with respect to the $A_n$-parameters [7]. This method is appropriate for cases of finite as well as zero effective trapping potential $\omega_{\text{eff}}$, where the latter case corresponds to a condensate of infinite spatial extent. Typically, this is the method of choice when investigating infinite periodic crystals of vortices and has been used since the early works of [10, 11] where an ansatz for the vortex lattice configuration was used to greatly restrict the degrees of freedom contained in the $A_n$-parameters. Infinite vortex lattices in multi-component systems have been investigated with this approach in several works including [12–15].

The LLL approach is restricted to cases where the magnetic length is small compared to the healing length: $\ell_B \ll \xi$. Away from this limit, the ground state wave functions will have substantial components in higher Landau levels so the above projection becomes unphysical. On the other hand, most experiments on rotating condensates of atomic gases have $\xi \ll \ell_B$. This is the main restriction of the first method.

In the second approach, one considers $\omega_{\text{eff}} > 0$ so that the condensate will have infinite extent. For this case one can discretise and solve the imaginary-time Gross–Pitaevskii equation. For such calculations, one must choose grids sufficiently large so that the wave function effectively vanishes at the boundary. Due to this, the boundary conditions involving the phase of $\psi$ are unimportant. Direct numerical solution through this means has shown several distinct vortex lattice structures for multi-component systems as described in, for instance, the works of [17–20].

The main drawback of the aforementioned method when investigating lattices of many vortices is that the underlying trap will obscure the configuration of vortices [21]. Therefore to infer the ideal periodic configuration of vortices for the case of a spatially extended condensate, one must require $\ell_H$ to be much smaller than the condensate size. In practice, this means one must numerically investigate systems with at least $\sim 100$ vortices. Additionally, since one must choose system sizes sufficiently large so that the wave function effectively vanishes at the boundary, many computational grid points are devoted to points of limited interest.

In this manuscript, we will describe an efficient numerical scheme to determine ground state solutions of (1) which are periodic in $\psi$. We will focus on the case where $\omega_{\text{eff}} = 0$ so that the condensate is spatially extended and an ideal vortex lattice is expected to form. This scheme does not have either of the drawbacks of the two aforementioned methods for addressing large vortex lattices. In particular, motivated by the magnetic translation group, we first introduce the so-called magnetic Fourier transform and formulate the continuous GPE problem that yields $\psi$ with the correct periodic structure. This correct problem arises since the magnetic Fourier transform naturally incorporates twisted boundary conditions which must be satisfied for rotating condensates (though they are unimportant for spatially localised systems). As a result, unnecessarily large computational domains can be avoided and systems sizes can be chosen on the order of the vortex lattice spacing. We then introduce a discrete lattice model whose energy retains the same gauge symmetries as the continuous energy functional and converges to the energy functional as the lattice spacing decreases. We show how spatial discretisation of this model can be achieved through a discrete version of the magnetic Fourier transform and how to compute it rapidly using standard fast Fourier transforms. Further, we implement it with the well-known split-step time integration scheme routinely applied to propagate the GPE in real and imaginary time [16]. We test the method by showing that it reduces to known results obtained in the lowest-Landau-level regime. While we focus on the single-component case in this manuscript for clarity and to make contact with known regimes, the framework can be naturally extended to the multi-component case.

This work is organised as follows. In section 2, relevant background on the magnetic translation group and gauge symmetries is given. In this section the magnetic Fourier transform is introduced. In section 3, we describe how the spatial components of (1) are discretised. The discretisation method allows one to access irrational aspect ratios of the computational unit cell and leaves the gauge symmetry of (1) intact. In section 4, the split-step magnetic Fourier method is presented, which is the main result of the present work. Finally, in section 5, applications of the method are discussed and comparisons are made with known analytical results in appropriate regimes.

2. Symmetries and boundary conditions for the rotated superfluid

Consider the system of a rotating superfluid in the limit $\omega_{\text{eff}} = 0$ (in the remainder of this work we will focus on this case). In this limit, the superfluid will be spatially extended, and a vortex lattice which is periodic in the density $\rho = |\psi|^2$
is formed. To numerically address such a system, one would like to choose a computational unit cell commensurate with that of the vortex lattice containing a small number of vortices. Though applying periodic boundary conditions to the modulus of \( \psi \) in this context is clearly correct, the appropriate boundary conditions for its phase are less apparent. In the following, we will show that the latter can be deduced through use of the so-called magnetic translation operators (MTOs) \[22, 23\]. Since thorough expositions of the MTOs exist elsewhere (see, for instance, \[24\]), we will only provide a brief treatment of their properties relevant to our problem. In the following we will also describe the so-called magnetic Fourier transform (MTF) which naturally incorporates the appropriate boundary conditions of the problem, and will be utilised in following sections.

2.1. Background: gauge symmetry and magnetic translation group

We start with a few comments about the gauge symmetries of (1). This energy is invariant under the gauge transformation \( \psi \rightarrow e^{iA(x)\psi} \), \( A_{\text{\lambda}} \rightarrow A_{\text{\lambda}} + \nabla x \) where \( \lambda \) is an arbitrary function of the \( xy \)-coordinates. Due to this invariance, one is free to choose a gauge which is best suited for the problem at hand. As defined in the previous section, \( A_{\text{\lambda}} \equiv \Omega m (\cdots, y) \) is referred to as the symmetric gauge. Another common choice is the Landau gauge which is obtained by putting \( \lambda = \Omega m x y \) so that \( A_{\text{\lambda}} \equiv A_{\text{\lambda}} + \nabla x \). In what follows we will write the vector potential in an arbitrary gauge as \( A = A_{\text{\lambda}} + \nabla x \), leaving \( \lambda \) unspecified but noting that we may return to the original symmetric gauge by putting \( \lambda = - \Omega m x y \). This will make apparent which quantities are gauge invariant. For instance, since the effective magnetic field \( B \equiv e_\lambda / \partial_\lambda A_j = 2m \Omega \) (here and after summation is implicit over repeated indices) is independent of \( \lambda \), it is a gauge invariant quantity.

The kinetic momentum operator entering (1) is given by \( p = -i \hbar \nabla \) is the canonical momentum operator. The generators of magnetic translation, defined to be \( \Pi_x = p_x - B_y - \partial_\lambda \lambda \) and \( \Pi_y = p_y - \partial_\lambda \lambda \), commute with the kinetic momentum operators: \( [\Pi_x, \Pi_y] = 0 \). From these, one defines the magnetic translation operators as \( T(R) = e^{i\Pi R} \). When acting on quantities involving only coordinates, one finds \( T(R) f(r) T^{-1}(R) = f(r + R) \), in complete analogy with the standard translation operators: \( T(R) = e^{i p R} \). However, unlike the standard translation operators, different MTOs do not generally commute. In particular, by noting that \( [\Pi_x, \Pi_y] = -i \hbar B \), one finds the commutator

\[ [T(R), T(R')] = 2ie_\lambda^2 \Pi (R + R') \sin \left( \frac{B}{2\hbar} e_\lambda R R' \right). \] (2)

Though the original treatment of the MTG was based on non-interacting systems, the treatment carries over naturally to the non-linear case. Solutions which minimise (1) will satisfy the time-independent GPE: \( \hbar \partial_t \psi / \psi^* = 0 \). When \( \omega_{\text{eff}} = 0 \) this can be written as \( \hbar \bar{\mathcal{H}} \psi = \mu \psi \) where \( \mathcal{H} = -\frac{1}{2} p^2 + g |\psi|^2 \). For periodic vortex lattices, one has the symmetry \( [\mathcal{H}, T(R)] = 0 \) when \( R \) is any lattice vector of the vortex lattice. Note that since the density has the periodicity of the vortex lattice, \( T(R) |\psi(r)|^2 T^{-1}(R) = |\psi(r)|^2 \). Furthermore, for two lattice vectors \( R \) and \( R' \) of the it vortex lattice, using the commutation relation (2) and the Feynman relation giving the density of vortices, one finds that \( [T(R), T(R')] = 0 \).

2.2. Twisted boundary conditions and magnetic Fourier transform

We choose a rectangular computational unit cell of dimensions \( L_x \times L_y \). Through full analogy with the treatment of a particle in a periodic potential in the absence of gauge fields, it is most natural to impose the following boundary conditions on \( \psi \):

\[ \psi(x, y) = T(L_x, \hat{\mathbf{x}}) \psi(x, y) = e^{-\frac{i}{\hbar} \int_0^{L_x} dx} e^{-\frac{1}{\hbar} (x + L_x - x)} \psi(x + L_x, y) \] (3)

\[ \psi(x, y) = T(L_y, \hat{\mathbf{y}}) \psi(x, y) = e^{-\frac{i}{\hbar} \int_0^{L_y} dy} e^{-\frac{1}{\hbar} (y + L_y - y)} \psi(x, y + L_y) \] (4)

These boundary conditions, to be contrasted with the more conventional periodic boundary conditions, reveal the acquisition of a phase ‘twist’ over a period, and were found to be necessary in early work \[25\]. For this reason we will refer to them as twisted boundary conditions (TBC) \[26\].

The above boundary conditions impose an important constraint on the effective magnetic field \( B \). Specifically, by (3) and (4) we must have \( \psi(x, y) = T(L_x, \hat{\mathbf{x}}) T(L_y, \hat{\mathbf{y}}) \psi(x, y) = T(L_x, \hat{\mathbf{x}}) T(L_y, \hat{\mathbf{y}}) \psi(x, y + L_y) = \psi(x, y + L_y) \), and so \( [T(L_x, \hat{\mathbf{x}}), T(L_y, \hat{\mathbf{y}})] \psi(x, y) = 0 \). By comparison with (2), one sees that we have an imposed quantisation condition on the effective magnetic field: \( B = \frac{2\pi n}{L_x} \) where \( n \) is an integer. Further insight can be gained by using the Feynman relation \[3\], which expresses the density of vortices as \( \rho_v = \frac{m \epsilon_\lambda}{\hbar} \). With this, the quantisation condition becomes \( \rho_v L_x L_y = n \). Thus, we see that the integer \( n \) corresponds simply to the number of vortices in the computational unit cell.

The conventional Fourier transform allows us to expand \( \psi \) in a basis of functions which are eigenstates of the canonical momentum operators and which satisfy periodic boundary conditions. Here we instead expand in terms of eigenfunctions of the generators of magnetic translation and require the TBCs to be satisfied. This leads to the following expressions defining the magnetic Fourier transform and its inverse:

\[ \tilde{\psi}(k_x, y) = \frac{1}{\sqrt{L_y}} \int_0^{L_y} dy e^{-i k_x y} \psi(x, y) \]

\[ \tilde{\psi}(k_x, y) = \frac{1}{\sqrt{L_y}} \int_0^{L_y} dy e^{-i k_x y} \psi(x, y) \]

\[ \psi(x, k_y) = \frac{1}{\sqrt{L_x}} \sum_{k_x} e^{i k_x x} \tilde{\psi}(k_x, y) \]

\[ \psi(x, k_y) = \frac{1}{\sqrt{L_x}} \sum_{k_x} e^{i k_x x} \tilde{\psi}(k_x, y) \] (5)
where $k_x$ and $k_y$ are summed over integer multiples of $\frac{2\pi}{L}$ and $\frac{\pi}{L_y}$ respectively. We see that these expressions have the desired properties. In particular, $\Pi_x \tilde{\psi}(k_x,y) = k_x \tilde{\psi}(k_x,y)$, $\Pi_y \tilde{\psi}(x, k_y) = k_y \tilde{\psi}(k_x,y)$, and the boundary conditions (3) and (4) are naturally satisfied.

3. Discrete model

Our aim is to minimise the energy of our system (1) subject to boundary conditions (3) and (4). To do so we will numerically solve the imaginary-time GPE, $-\hbar \partial_\tau \psi = \partial E/b \psi^* \tau$ subject to TBCs. Written out in full, the continuous equation is

$$-\hbar \partial_\tau \psi = \frac{1}{2m} (-i\hbar \nabla - A_\tau - \nabla \lambda) \psi + g |\psi|^2 \psi - \mu \psi \equiv (\mathcal{H} - \mu) \psi.$$

In the long imaginary-time limit, $\psi$ will generically converge to the ground state wave function which minimises (1). In particular one can show that the energy is a monotonically decreasing function of $\tau$ with

$$\hbar \frac{dE}{d\tau} = -2 (\langle \mathcal{H} - \mu \rangle^2) \leq 0$$

where brackets denote the expectation value with respect to $\psi$. As can be seen from (7), the evolution will stop when $\psi$ becomes an eigenstate of $\mathcal{H}$ with eigenvalue $\mu$, i.e. a solution of the time-independent GPE.

We are thus faced with the problem of discretising the spatial components of (6) and note that there are multiple ways of doing so. One approach is to treat (6) by introducing discrete versions of the differential operators appearing in this equation. While this approach is commonly adopted (see for example [16]), an alternative route and the one we use in this work, is to introduce an appropriate energy defined over a lattice and then, by taking its derivative with respect to the complex conjugate of the wave function values at the lattice points, obtain a discretised version of (6). By doing this, we can require that (i) the discrete Hamiltonian matrix is Hermitian and (ii) the discrete model inherits the exact gauge symmetry of the continuum model. The resulting model we find will be an extension of the Hofstadter model [27] which describes a particle on a square lattice under an effective magnetic field. That the resulting generalised model converges to the continuum theory (1) is perhaps not very surprising since it is well known that the long-wavelength theory of the Hofstadter model is that of a continuum particle under the presence of a perpendicular magnetic field. The main technical innovation presented below is the use of anisotropic tunnelling which enables one to treat computational unit cells of irrational aspect ratios $R = L_x/L_y$. Accessing such irrational aspect ratios is necessary to properly describe many important vortex configurations including the triangular lattice.

We introduce a grid of $N_x \times N_y$ points in a rectangular lattice covering the computational unit cell. Points in this grid take on values $r = a_n \hat{x} + a_m \hat{y}$ where $n$ and $m$ are integers satisfying $1 \leq n \leq N_x$ and $1 \leq m \leq N_y$ and $a_n = L_x/N_x$, $a_m = L_y/N_y$ give the spatial discretisation spacing (or lattice constant). We next introduce the discrete wave function $\psi_{n,m}$ defined at each grid point and where convenient we will use the alternative notation $\psi_r = \psi_{n,m}$. We allow tunnelling of particles between nearest-neighbour sites, and further impose an on-site repulsive interaction. Gauge fields are correctly incorporated into lattice models through the so-called Peierls substitution [27, 28] where complex phases are incorporated into the tunnelling matrix elements. In particular to incorporate the gauge field into the tunnelling of particles from site $r$ to site $r'$ we apply the replacement $\psi_r \psi_{r'}^* \rightarrow e^{i\lambda_r L \psi_r^* \psi_{r'}}$.

We note that, importantly, with this replacement the discrete model will inherit the exact gauge symmetry of the continuum model.

With the above considerations, we posit the following discrete expression for the energy

$$E_d = -\sum_{n,m} \left[ w_1 e^{i\lambda_{n,a,n+1,m}} \psi_{n,m}^* \psi_{n+1,m} 
+ w_2 e^{i\lambda_{n,a,n+1,m}} e^{-i\phi_\tau} \psi_{n,m}^* \psi_{n,m+1} + c.c. \right]$$

$$+ \sum_{n,m} \left[ \frac{U}{2} |\psi_{n,m}|^4 - \tilde{\mu} |\psi_{n,m}|^2 \right]$$

(8) where $w_1$, $w_2$, and $U$ are real positive parameters having units of energy, $B$ is the lattice magnetic field giving the net flux per lattice plaquette, $\tilde{\mu}$ is a chemical potential for the discrete model, and the real parameters $\lambda_{n,m}$ reflect the gauge freedom of the problem. When $U = \lambda_{n,m} = 0$ and $w_2 = w_3$, the discrete model reduces to the well-known Hofstadter model [27]. In this sense, the above expression (8) can be viewed as a generalised Hofstadter model.

To make contact with the continuum theory (1), we relate the discrete and continuum wave functions as $\psi_{n,m} = \sqrt{a_n a_m} \psi(a_n, a_m, a, m)$. With this, one can verify that the discrete energy reduces to the continuum energy provided we make the following identifications: $w_1 a_x^2 = w_2 a_y^2 = \frac{\hbar^2}{2m} U = g(a_n, a_m)$, $B = B_n a_n/l_h$, $\lambda_{n,m} = \lambda(a_n, a_m, a, m)/l_h$, and $\tilde{\mu} = \mu - 2w_1 - w_2$. The resulting discretisation error is found to be second order: $E - E_d = O(a_x^2) + O(a_y^2)$. Importantly, we note that the aspect ratio of the computational unit cell is given by $R = L_x/L_y \leq N_x/N_y \sqrt{n_2/n_1}$. Therefore, with anisotropic hopping we may access computational unit cells with irrational aspect ratios which are necessary for addressing the triangular vortex lattice, for instance. In order for the discrete theory to accurately describe the continuum theory, the discretisation lattice constants, $a_x$ and $a_y$, must be the smallest length scales in the problem. Specifically, in what follows we require $a_x, a_y \ll \xi, \xi_b$. On the other hand, we note that the discrete theory remains well-defined and physically relevant away from this limit. Indeed, most investigations of the Hofstadter model are focused on regimes where $a_x$ and $a_y$ are on the order of the magnetic length.

The continuum expressions from the previous section carry over naturally to the discretised case, which we tabulate in the remainder of the present section. The discrete imaginary-time GPE is given by
\[ h \partial_t \psi_{n,m} = - \frac{\partial E_d}{\partial \psi_{n,m}}. \] (9)

The discrete MFT, see (5), is

\[ \psi_{k,m}^\tau = \frac{1}{\sqrt{N_k}} \sum_{n} e^{-i[k_m n + B m m - \lambda_{n,m}]} \psi_{n,m}, \]
\[ \psi_{n,m}^\tau = \frac{1}{\sqrt{N_k}} \sum_{k} e^{-i[k_m n + B m m - \lambda_{n,m}]} \psi_{k,m}, \]
\[ \psi_{n,m}^\tau = \frac{1}{\sqrt{N_k}} \sum_{k} e^{i[k_m n + B m m - \lambda_{n,m}]} \psi_{k,m}. \] (10)

Here, \( n \) and \( m \) take on integer values for which \( 1 \leq n \leq N_n \) and \( 1 \leq m \leq N_m \) respectively. The wave numbers \( k_1 \) and \( k_2 \) take on integer multiple values of \( \frac{2\pi}{N_m} \) and \( \frac{2\pi}{N_n} \) for which \( \frac{2\pi}{N_m} \leq k_1 \leq 2\pi \) and \( \frac{2\pi}{N_n} \leq k_2 \leq 2\pi \) respectively. Finally, the twisted boundary conditions, see (3) and (4), in discretised form are

\[ \psi_{n,M_n + n} = e^{iBn_N e i[\lambda_{n,m} - \lambda_{n,m}]} \psi_{n,m}, \]
\[ \psi_{n,M_n + n} = e^{i[\lambda_{n,m} - \lambda_{n,m}]} \psi_{n,m}. \] (11, 12)

4. The split-step magnetic Fourier method

Split-step spectral methods provide a versatile means to solve a number of linear and non-linear differential equations [29]. As a simplest case, consider a (linear and real-time) Schrödinger equation with Hamiltonian composed of two non-commuting operators \( A \) and \( B \) which each have known spectra: \( i\hbar \partial \psi = (A + B) \psi \). The wave function is advanced by a time step through \( \psi(t + \Delta t) = e^{-\frac{\hbar}{2}(A + B)(\Delta t)} \psi(t) \). For cases where the Hamiltonian operator \( A + B \) is difficult to diagonalise, it is beneficial to employ the Strang splitting [30] to propagate in time:

\[ \psi(t + \Delta t) = e^{-\frac{\hbar}{2}(A + B)\Delta t} \psi(t) = e^{-\frac{\hbar}{2}B\Delta t} e^{-\frac{\hbar}{2}A\Delta t} e^{-\frac{\hbar}{2}B\Delta t} \psi(t) + O(\Delta t^3). \] (13)

One can then efficiently perform the operation on the RHS of (13) by successively transforming \( \psi \) between the eigenbasis of \( A \) and \( B \) and performing Hadamard products. Most often \( A \) is diagonal in the momentum basis while \( B \) is diagonal in the position basis (or vice versa) so the efficiency of the split-step method relies on that of the fast Fourier transform algorithm. Indeed, the split-step Fourier method is now a standard approach for numerically solving the GPE (see [16] and references therein). We show here how this powerful method can also be applied to our problem by instead using the magnetic Fourier transform to capture the twisted boundary conditions given in (3) and (4).

With the above in mind, we wish to write the energy \( E_d \) as a sum of diagonalised components. As stated, this can be achieved with the machinery of the magnetic Fourier transform introduced in the previous sections. In particular, using (10) we can write \( E_d = E_x + E_y + E_{int} \) where

\[ E_x = 4\omega \sum_{k,m} \sin^2 \left( \frac{k_x + B m}{2} \right) |\psi_{k,m}^\tau|^2 \] (14)

\[ E_y = 4\omega \sum_{n,k} \sin^2 \left( \frac{B n - k_y}{2} \right) |\psi_{n,k}^\tau|^2 \] (15)

\[ E_{int} = \sum_{n,m} \left( \frac{U}{2} |\psi_{n,m}^\tau|^4 - |\psi_{n,m}^\tau|^2 \right). \] (16)

Note that the gauge fields \( \lambda_{n,m} \) are absent in the above expressions, making the gauge invariance of each quantity apparent. The main use of the MTG is in obtaining these expressions for \( E_x \) and \( E_y \) presented in the equations above which are associated with it linear terms in the GPE.

Because the above energy is composed of three pieces, the Strang splitting needs to be applied twice. The split-step MFT procedure, to advance the wave function \( \psi(\tau) \) evolving in the imaginary-time GPE by a single time step \( \Delta \tau \), then proceeds with the following computations:

1. \( \psi_1 = e^{-\frac{iH_{mt} \Delta \tau}} \psi(\tau) \)
2. \( \psi_2 = M^FT \left[ e^{\frac{iH_{mt} \Delta \tau}} M^FT \psi(\tau) \right] \)
3. \( \psi_3 = M^FT \left[ e^{\frac{iH_{mt} \Delta \tau}} M^FT \psi(\tau) \right] \)
4. \( \psi_4 = M^FT \left[ e^{\frac{iH_{mt} \Delta \tau}} M^FT \psi(\tau) \right] \)
5. \( \psi(\tau + \Delta \tau) = e^{-\frac{iH_{mt} \rho \Delta \tau}} \psi_4 \)

where \( M^FT \) and \( M^FT \) are the operations defined in (10). The quantities in the exponents directly follow from (14)-(16).

In particular, \( H_x = 4\omega_1 \sin^2 \left( \frac{k_x + B n}{2} \right) \). \( H_y \) and \( H_{int} \) are not specified in the above, denoted by \( \rho \) and \( \rho_0 \) entering in the steps above. For certain choices (e.g. putting \( \rho_0 = \rho_0 = |\psi(\tau)|^2 \)), the method will lose its second-order accuracy. To determine values of \( \rho_0 \) and \( \rho_0 \) for which the method will retain its second-order accuracy (as in the linear case), one can compare \( \psi(\tau + \Delta \tau) \) computed with the above algorithm with the second-order Taylor expansion \( \psi(\tau + \Delta \tau) \approx \psi(\tau) + \partial \psi(\tau) \Delta \tau + \frac{\Delta \tau^2}{2} \partial^2 \psi(\tau) (\Delta \tau)^2 \) where the imaginary-time GPE can be used to evaluate the coefficients in this expansion. Through this comparison, one finds that with the choices

\[ \rho_0 = |e^{-\frac{iH_{mt} \rho \Delta \tau}} \psi |^2, \quad \rho_0 = |\psi_4|^2, \] (17)

the method will be second-order accurate. The determination of the appropriate densities entering the algorithm is akin to
the methods presented in [31]. There, it was determined that, provided the most updated densities were used, the split-step method for the real-time GPE would be second-order accurate. We note, however, that this result does not carry over to the imaginary-time GPE in that if one chooses \( \rho_k = |\psi_\beta|^2 \) and \( \rho_\beta = |\psi|^2 \), the method will only be first-order accurate.

It is often desirable to propagate the imaginary-time GPE for the case where the particle-number normalisation \( \int |\psi|^2 \, dx \, dy = \int \rho \, dx \, dy = N \) is fixed for all times during the evolution. This constraint can be achieved through the use of a time-dependent chemical potential entering the imaginary-time GPE. The above algorithm can be naturally adapted to this scenario by applying normalisations at appropriate places in the above steps. In particular, after computing the densities \( \rho_k \) and \( \rho_\beta \) using the expressions in [17], they should each be normalised to the total particle number \( N \). Additionally, at the end of each time-step propagation, the resulting wavefunction should be normalised. Due to these normalisations, the chemical potential entering the algorithm becomes a free parameter and can be set to zero. The second-order accuracy of this fixed-\( N \) method has been verified with numerical tests.

Note that the extension of the split-step method from linear to non-linear equations, as done above, is of small influence on the computational time. For instance, if we put \( g = 0 \) making the GPE linear, the computational cost of the split-step method at leading order will not be affected. The MFT can be implemented in a straightforward way by using existing fast Fourier transform packages as it can be written in terms of direct multiplications and Fourier transforms as:

\[
\mathcal{MFT}_x [\psi] = \mathcal{F}_x [e^{-i m E \beta} e^{-i A \cdot \nabla} \psi]
\]

\[
\mathcal{MFT}_y [\psi] = \mathcal{F}_y [e^{-i A \cdot \nabla} \psi]
\]

where \( \mathcal{F}_x \) and \( \mathcal{F}_y \) denote the standard Fourier transforms. Thus the MFT algorithm is as fast as the conventional fast Fourier transform to leading order. More specifically, for \( N \) discretisation points, the method has \( N \log N \) computational cost. Finally, we note that the above scheme can be used to simulate the real-time GPE with a Wick rotation where one puts \( \tau \rightarrow it \).

5. Numerical tests and discussion

In this section, we will provide some preliminary applications of the split-step magnetic Fourier method, showing how it can reproduce known results in appropriate regimes and also how these results can be extended. We start by considering the lowest lowest-Landau-level regime, since this case has several known results with which we can compare.

To characterise vortex lattices, following [10], it is helpful to introduce the dimensionless parameter

\[
\beta = A \frac{\int |\psi|^4 \, dx \, dy}{\left( \int |\psi|^2 \, dx \, dy \right)^2}
\]

where \( A = L_x L_y \) is the area of the computational unit cell. This parameter is of particular interest because it can be directly related to the interaction energy of the system as \( \frac{g}{2} \beta N^2 A \), with \( N = \int |\psi|^2 \, dx \, dy \). In the LLL regime the remaining terms in the energy are quenched, thus minimising the energy is equivalent to minimising \( \beta \). When the number of vortices is restricted to two per computational unit cell, one can compute \( \beta \) analytically as a function of the aspect ratio \( \mathcal{R} \)

\[
\beta^4 (\mathcal{R}) = \sqrt{\frac{\mathcal{R}}{2}} (f_0^2 + 2 f_0 f_1 - f_1^2),
\]

with

\[
f_n = \sum_{m=-\infty}^{\infty} e^{-\pi \mathcal{R} (2m + n)^2 / 2}
\]

where the vortices are placed within the unit cell so as to maximise the separation between neighbouring vortices. Recall that a unit cell commensurate with that of the ground state vortex lattice of infinite spatial extent must be chosen to obtain the ground state energy. Unit cell sizes differing from this will introduce frustration. Therefore \( \beta \) should be minimised with respect to \( \mathcal{R} \). One expects minima to occur at aspect ratios which are commensurate with a triangular vortex lattice [11, 32]. Since \( \beta (\mathcal{R}) = \beta (\mathcal{R}^{-1}) \) we will restrict our attention to \( \mathcal{R} \geq 1 \).

We now turn to numerically computing \( \beta \) using the split-step magnetic Fourier method. For fixed values of \( \mathcal{R} \) and \( \ell_0 \), starting with an initial randomised state, the imaginary-time GPE is evolved on a 256 \times 256 grid until a time-independent state is obtained. Convergence as a function of the time step \( \Delta \tau \) is also checked. In figure 1, several curves of \( \beta \) versus the aspect ratio \( \mathcal{R} \) are shown for different values of \( \ell_0 \) for systems containing two vortices per computational unit cell. In the limit \( \ell_0 \ll \xi \) one finds excellent agreement with the LLL analytical expression \( \beta^4 \) as expected. In terms of rotational frequency, the LLL corresponds to the rapid rotation limit \( \Omega 

\]

Because the energy of the system is an extensive quantity, one might expect the energy per particle, \( \tilde{E} = \frac{E + \mu N}{N} \), to be unchanged when the size of the computational cell is increased ceteris paribus (for convenience we have removed the term involving the chemical potential in (1)). This is only true, however, for computational unit cells commensurate with the ground state vortex configuration as increasing the size of the cell while keeping the vortex density fixed allows the system to have more degrees of freedom. In the following, we consider doubling the spatial dimensions of the computational unit cell from one containing two vortices to one containing eight vortices. From general principles one will have \( \tilde{E}_8 \approx \tilde{E}_2 \) where \( \tilde{E}_8 \) and \( \tilde{E}_2 \) are the energies per particle of the systems with smaller and larger computational unit cells respectively. In figure 2 the energy per particle obtained using the split-step
7 Mingarelli et al.

...magnetic Fourier method is shown for systems having two and eight vortices per computational unit cell. As expected, we have $\tilde{E}_2 < \tilde{E}_8$ for all curves. The curves coincide near $\mathcal{R} = \sqrt{3}$ which is commensurate with the triangular vortex lattice in both cases. The system with eight vortices can also achieve a triangular vortex lattice at aspect ratios $\mathcal{R} = 4/\sqrt{3}, 4\sqrt{3}$ and we note that degenerate minima of $\tilde{E}_8$ occur at these values. The computation has been carried out for $\ell_B/\xi = 1$ but the same results—namely $\tilde{E}_2$ being an upper bound for $\tilde{E}_8$, their equivalence close to $\mathcal{R} = \sqrt{3}$ and the existence of the three degenerate minima for $\tilde{E}_8$—hold for any ratio $\ell_B/\xi$.

6. Outlook and conclusions

In conclusion, we have described a computational method which can efficiently find the minimum energy of an infinite vortex lattice within Gross–Pitaevskii mean field theory. We have shown how to extend the conventional split-step Fourier method to include twisted boundary conditions through use of the magnetic translation group. We have tested the method for particular cases, and showed that it reproduces known results in the lowest Landau level regime. The method can be extended naturally to treat multi-component systems such as condensate mixtures and spinor condensates, as well as multicomponent condensates under more general synthetic gauge fields. The dynamics of such multicomponent systems is certainly more complex and can be described in terms of a set of coupled equations. The kinetic terms of these equations can be treated with the MFT, while the nonlinear parts are diagonal in real space. Such systems can have richer vortex lattice structures, and applying the methodology described in this work to them warrants further investigation.
Acknowledgments

This work was supported in part by the European Union’s Seventh Framework Programme for research, technological development, and demonstration under Grant No. PCIG-GA-2013-631002.

References

[28] Peierls R 1933 Z. Phys. 80 763