



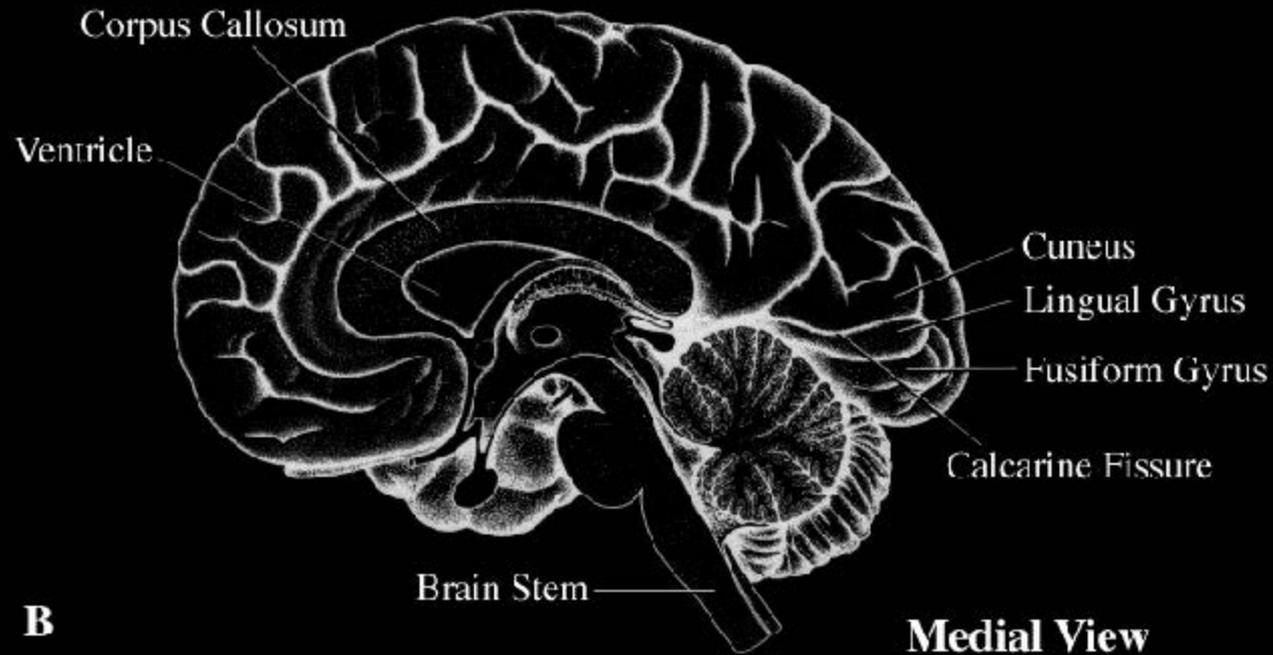
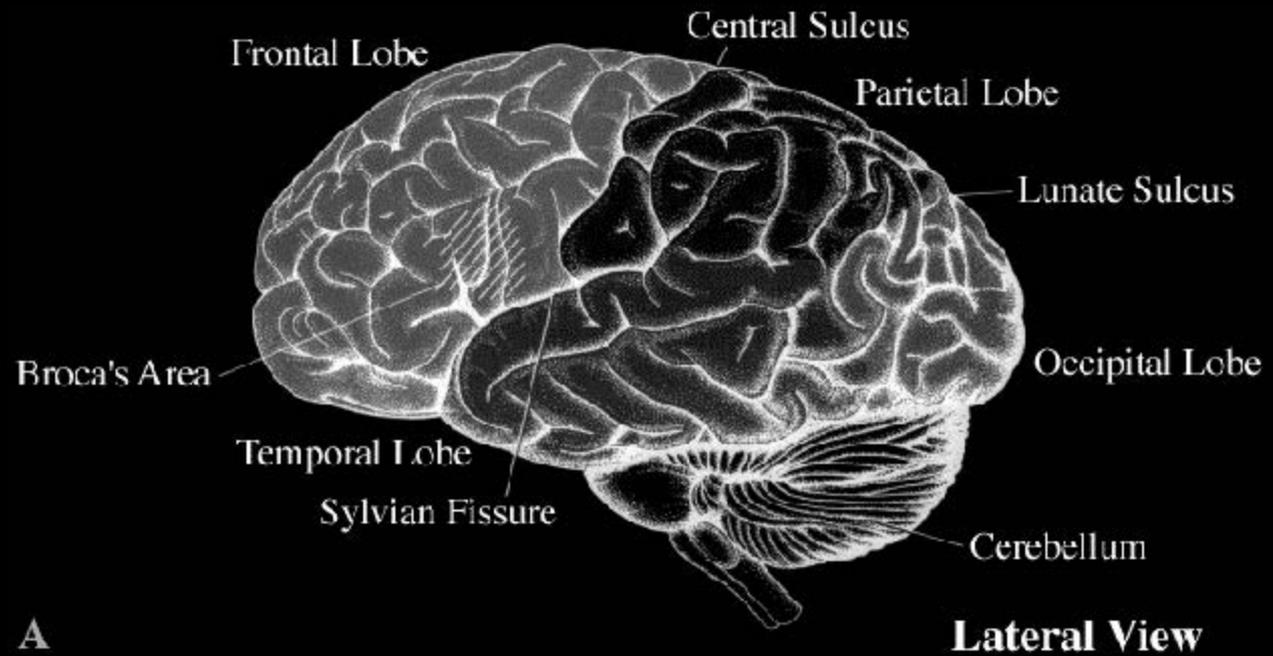
AMMP Workshop: Conformal Geometry in  
Mapping, Imaging and Sensing  
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South Kensington Campus, London  
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# Investigating Disease in the Human Brain with Conformal Maps and Conformal Invariants

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# The Human Brain



# Cortical Flat Maps of the Brain

- Functional processing mainly on cortical surface
- 2D analysis methods desired: **Cortical Flat Maps**
- Metric-based approaches (i.e. area or length preserving maps) will always have distortion
- Conformal maps offer a number of useful properties including:
  - mathematically unique
  - different geometries available
  - canonical coordinate system

# Potential Advantages of Brain Flat Maps

- Cortical flat maps facilitate the determination and analysis of spatial relationships between different cortical regions
- Definition of coordinate system on cortical surface
- Comparison of individual differences in cortical organization or in functional foci
  - identify/quantify specific regions where diseases occur
  - analysis of regions buried within sulci
- Visualization of cortical folding patterns

# “Flattening” Surfaces and Conformal Mapping

- By a “flat” surface, we mean a surface of constant curvature:
  - Euclidean plane (identified with the complex plane),  
 $R^2 = C = \{z = x + iy: x, y \in R\}$
  - the unit disc in  $C = D = \{(x,y): x^2 + y^2 < 1\}$
  - the unit sphere  $S = \{(x,y,z): x^2 + y^2 + z^2 = 1\} \subset R^3$
- **Why Conformal?** Impossible to flatten a surface with intrinsic curvature without introducing metric or areal distortions: “Map Maker’s Problem”  
BUT we can preserve angles  $\Rightarrow$  *Conformal Maps*

# Riemann Mapping Theorem

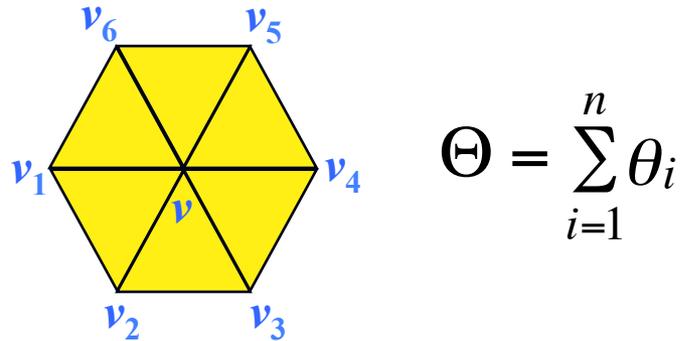
## 1850' s

There exists a unique conformal mapping (up to conformal automorphisms) from a Riemann surface to the Euclidean plane, hyperbolic disc or sphere.

*Conformal Maps Exist  
and are  
Mathematically Unique!*

# Discrete Conformal Mapping

Given a triangulated mesh: angle sum  $\Theta$  at a vertex  $v$  is sum of angles from triangles emanating out of  $v$ .



$$\Theta = \sum_{i=1}^n \theta_i$$

*The angle at a vertex in original surface maps such that it is the Euclidean measure rescaled so the total angle sum measure is  $2\pi$ .*

In the discrete setting, this corresponds to preserving angle proportion: an angle  $\theta_i$  at a vertex  $v$  in original surface has angle  $2\pi\theta_i / \Theta$  in mapping to the Euclidean plane.

# Conformal Mapping Methods

## *Numerical Methods*

- PDE methods for solving Cauchy-Riemann equations
- Harmonic energy minimization for solving Laplace-Beltrami equation
- Differential geometric methods based on approximation of holomorphic differentials

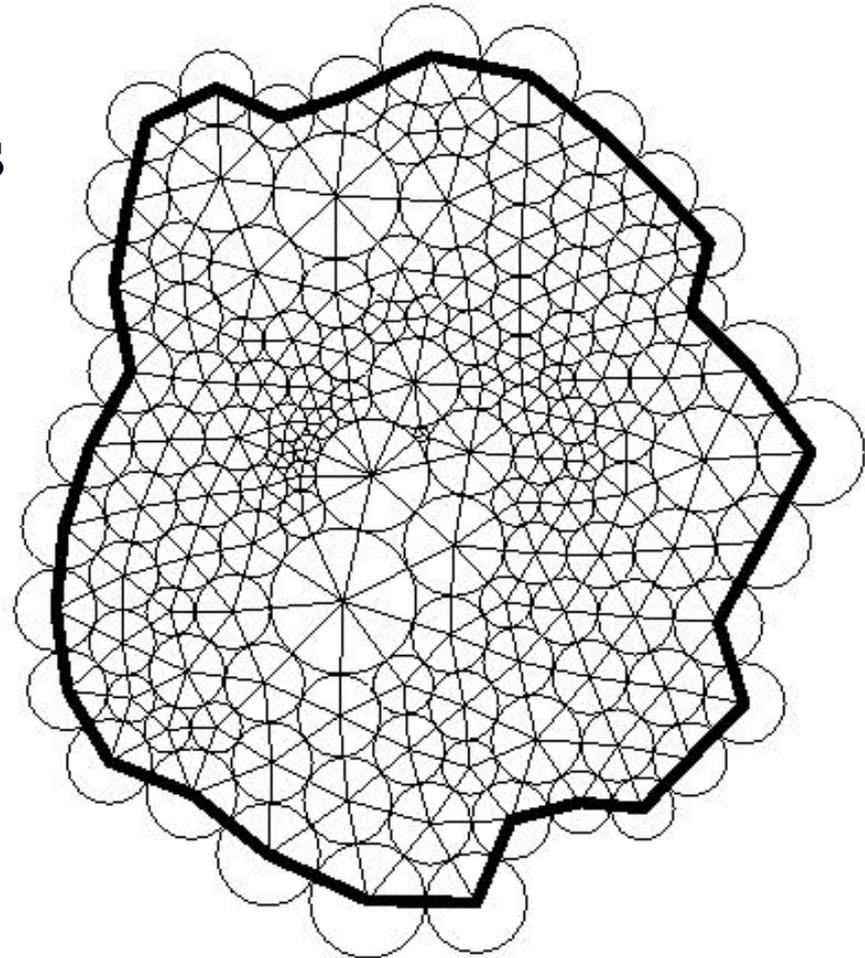
## *Circle Packing Method*

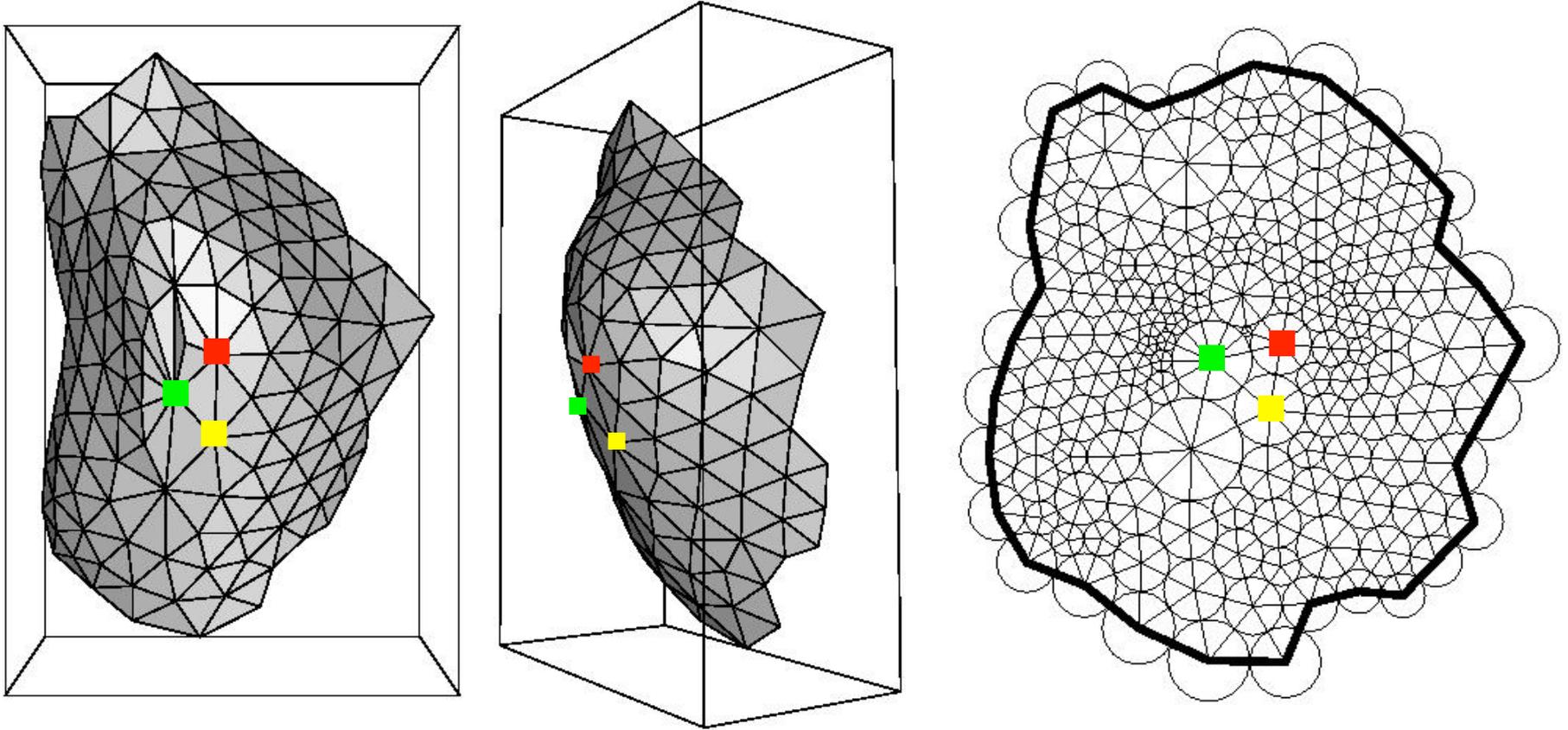
- Circle packing computed to find conformal map

# Discrete Conformal Mapping with Circle Packings

Collaboration with Ken Stephenson, Mathematics, U. Tennessee, Knoxville

- A circle packing is a configuration of circles with a specified pattern of tangencies
- Theoretical, computational developments use circle packings to approximate a conformal mapping
- Circle Packing Theorem & Ring Lemma guarantee **this circle packing is unique and quasi-conformal**





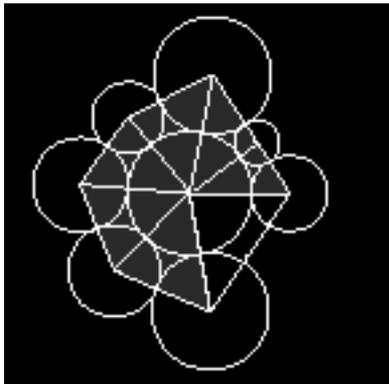
Given a simply-connected triangulated surface:

- represent each vertex by a circle such that each vertex is located at the center of its circle
- if two vertices form an edge in the triangulation, then require their corresponding circles must be tangent in the final packing
- assign a positive number to each boundary vertex

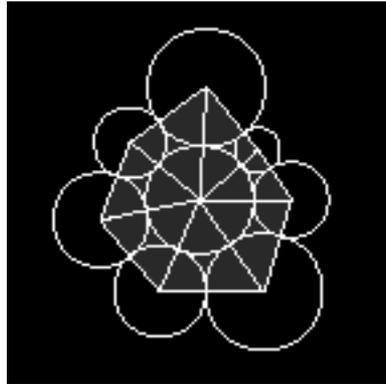
# The (Euclidean) Algorithm

- Iterative algorithm has been proven to converge
- Surface curvature is concentrated at the vertices
- A set of circles can be “flattened” in the plane if the angle sum around a vertex is  $2\pi$
- To “flatten” a surface at the interior vertices:

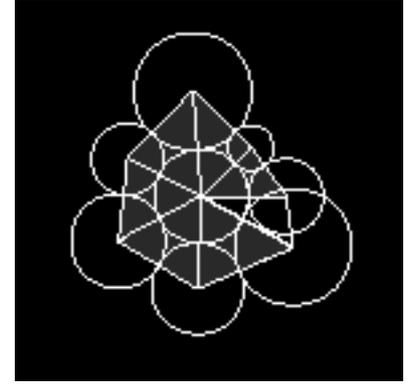
Positive curvature  
or cone point  
(angle sum  $< 2\pi$ )



Zero curvature  
(angle sum =  $2\pi$ )

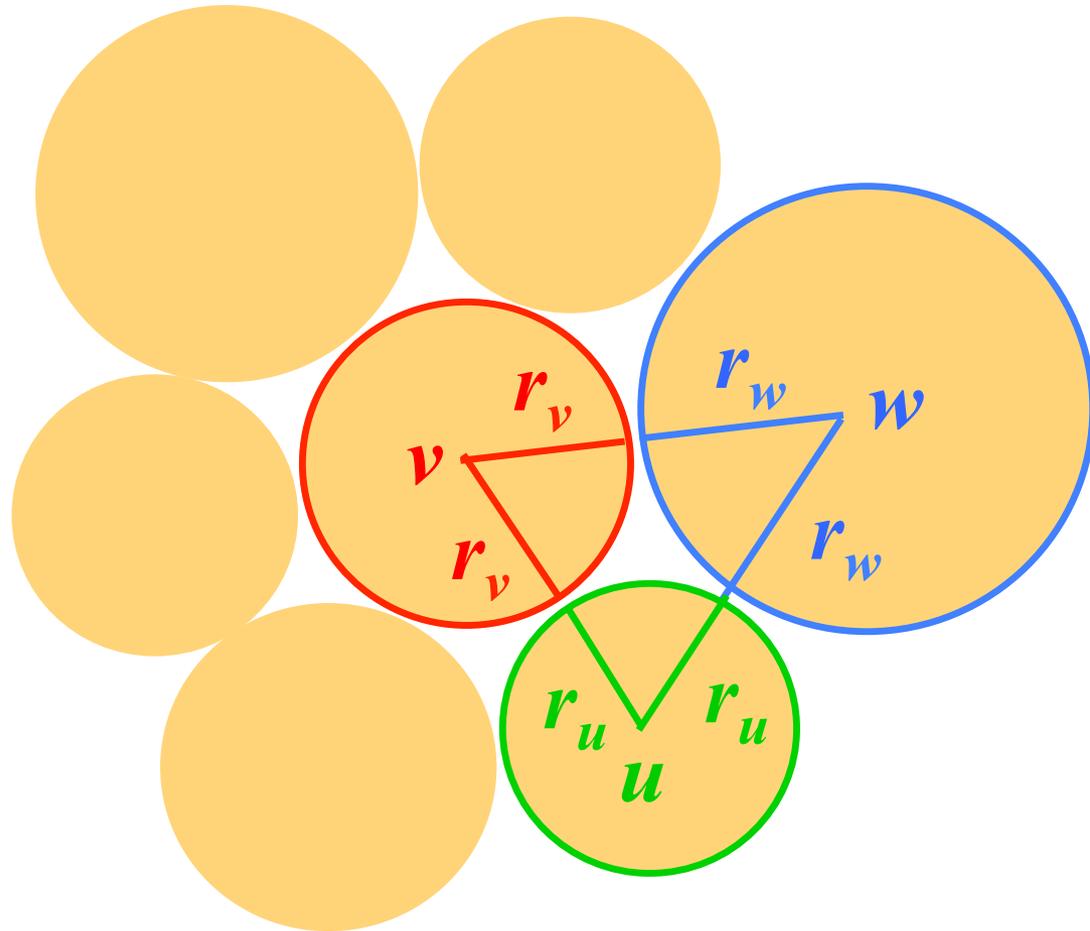


Negative curvature  
or saddle point  
(angle sum  $> 2\pi$ )



For all faces  $\langle v, u, w \rangle$  containing vertex  $v$ :

$$\sum_{\langle v, u, w \rangle} \arccos \left\{ \frac{(r_v + r_u)^2 + (r_v + r_w)^2 - (r_u + r_w)^2}{2(r_v + r_u)(r_v + r_w)} \right\} = 2\pi$$



# The Algorithm (Continued)

- This collection of tangent circles is a circle packing and gives a new surface in  $R^2$  which is our quasi-conformal flat mapping
- Easy to compute the location of the circle centers in  $R^2$  once the first 2 tangent circles are laid out
- Each circle in the flat map corresponds to a vertex in the original 3D surface
- Similar algorithm exists for hyperbolic geometry
- No known spherical algorithm: use stereographic projection to generate spherical map
- **NOTE:** A packing only exists once all the radii have been computed!
- Theorem (Bowers-Stephenson): This scheme converges to a conformal picture of the triangulation with repeated hexagonal refinement of the triangulation and repacking

# Mapping The Human Brain

- MRI volume stripped of extraneous regions (i.e. scalp, skull, csf) to leave the region of interest (ROI)
- Resulting volume smoothed and a surface reconstruction algorithm, such as marching cubes applied to produce a triangulated mesh representing the surface of the brain
- The human brain is topologically equivalent to an orientable, 2-manifold (ie. a sphere)
- A boundary may be introduced by introducing cuts to make the brain topologically equivalent to a closed disc
- Many surface reconstruction algorithms produce a surface with topological problems - these must be fixed
- If a surface is topologically correct, then it is a topological sphere if and only if Euler characteristic  $= v - e + f = 2$

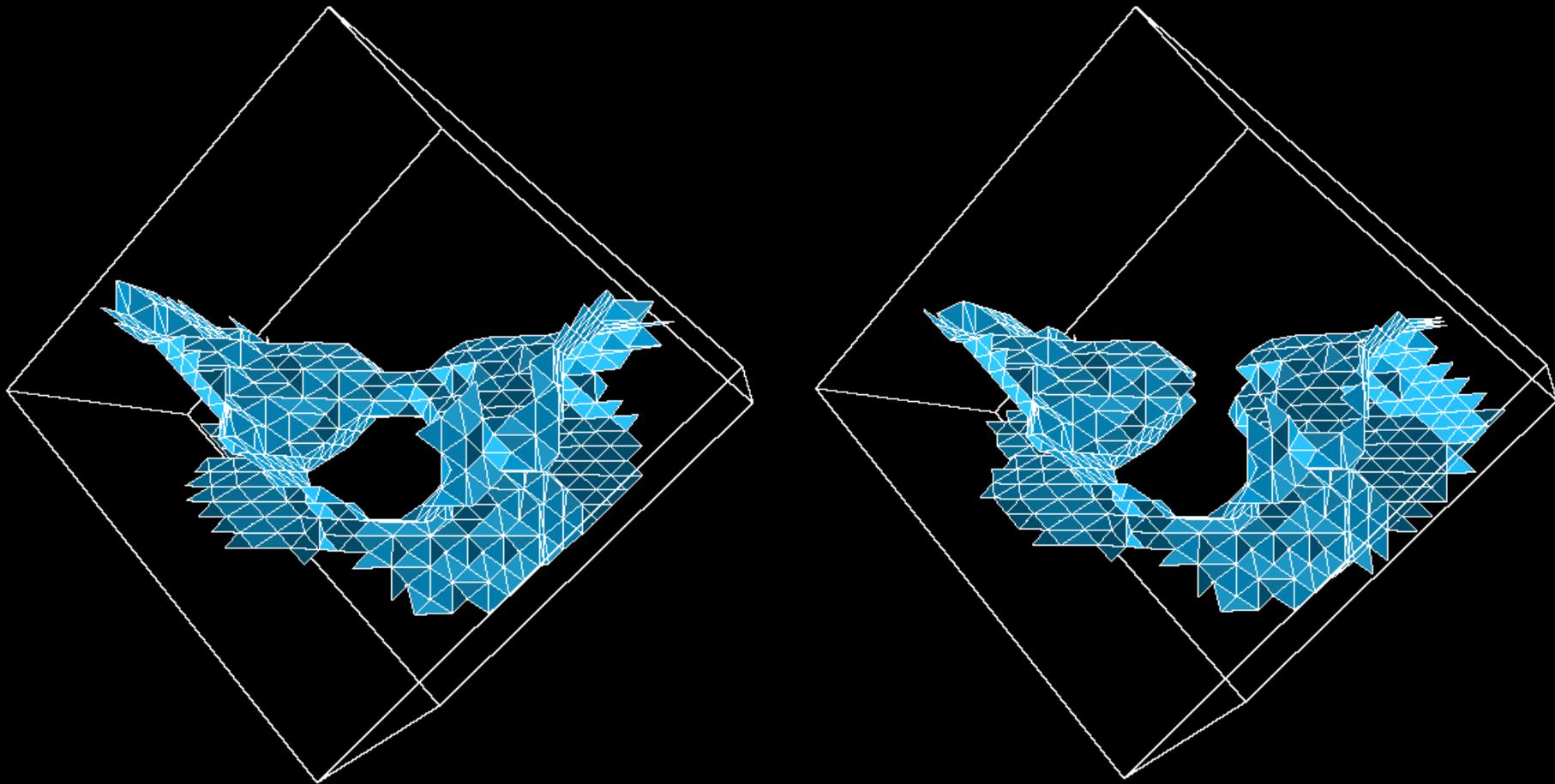
# Creating a Cortical Surface

- Extract region of interest from MRI volume
- Cortical regions defined by various lobes and fissures color coded for identification purposes
- Create triangulated isosurface of neural tissue from MRI volume - **PROBLEM:** many algorithms can yield surfaces with topological problems (holes, handles)
- Surface topology corrected to yield a surface topologically equivalent to a sphere
- A single closed boundary cut is introduced to act as a map boundary under flattening

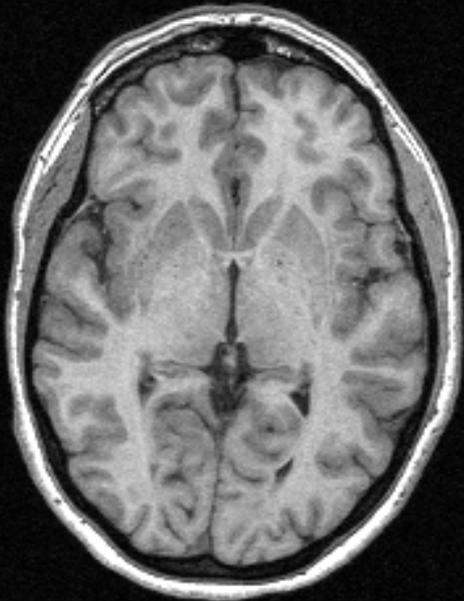
# Handles (or Tunnels)

- Each handle contributes  $-2$  to the Euler characteristic
- Number of handles can only be determined after all other topological problems have been corrected
- A handle can be corrected in 2 possible ways:
  - cut handle and then “cap” off ends or
  - fill in handle “tunnel”
- Unless *a priori* information about handles are known or assumed, then handle correction should be guided by volumetric data used to create the surface

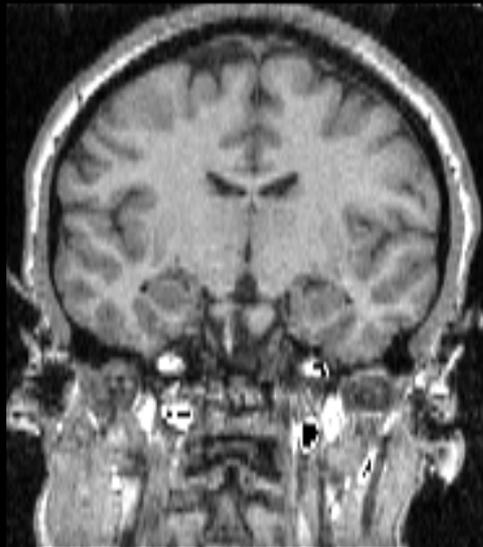
# Fixing Handles



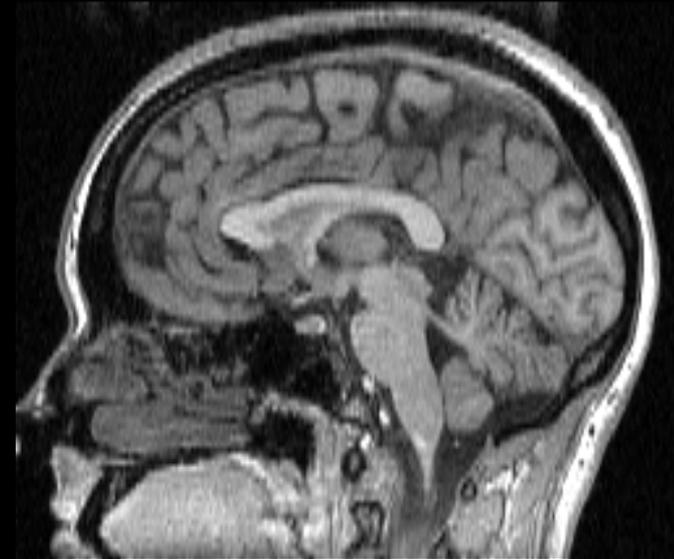
# Magnetic Resonance Imaging (MRI)



Axial Slice

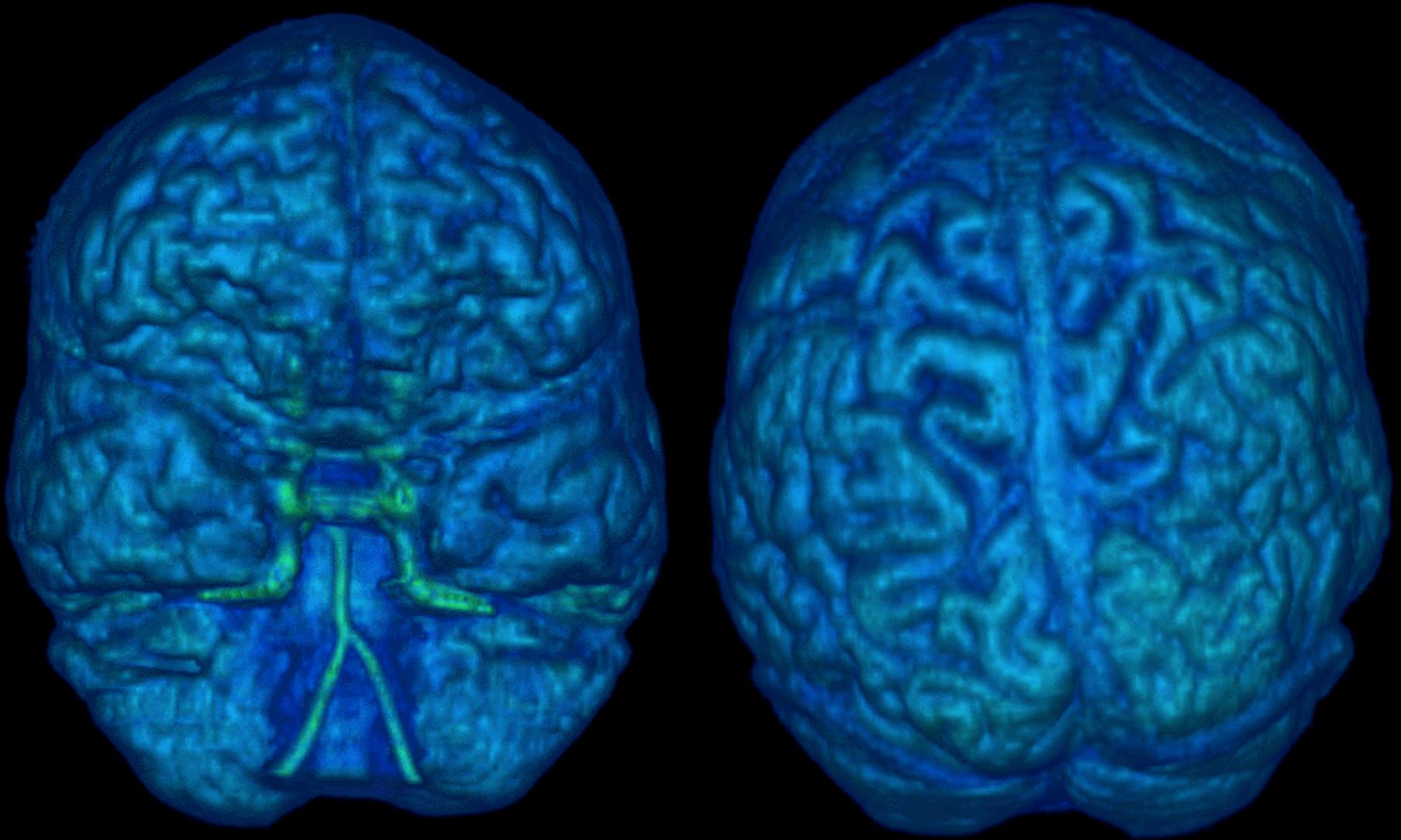


Coronal Slice

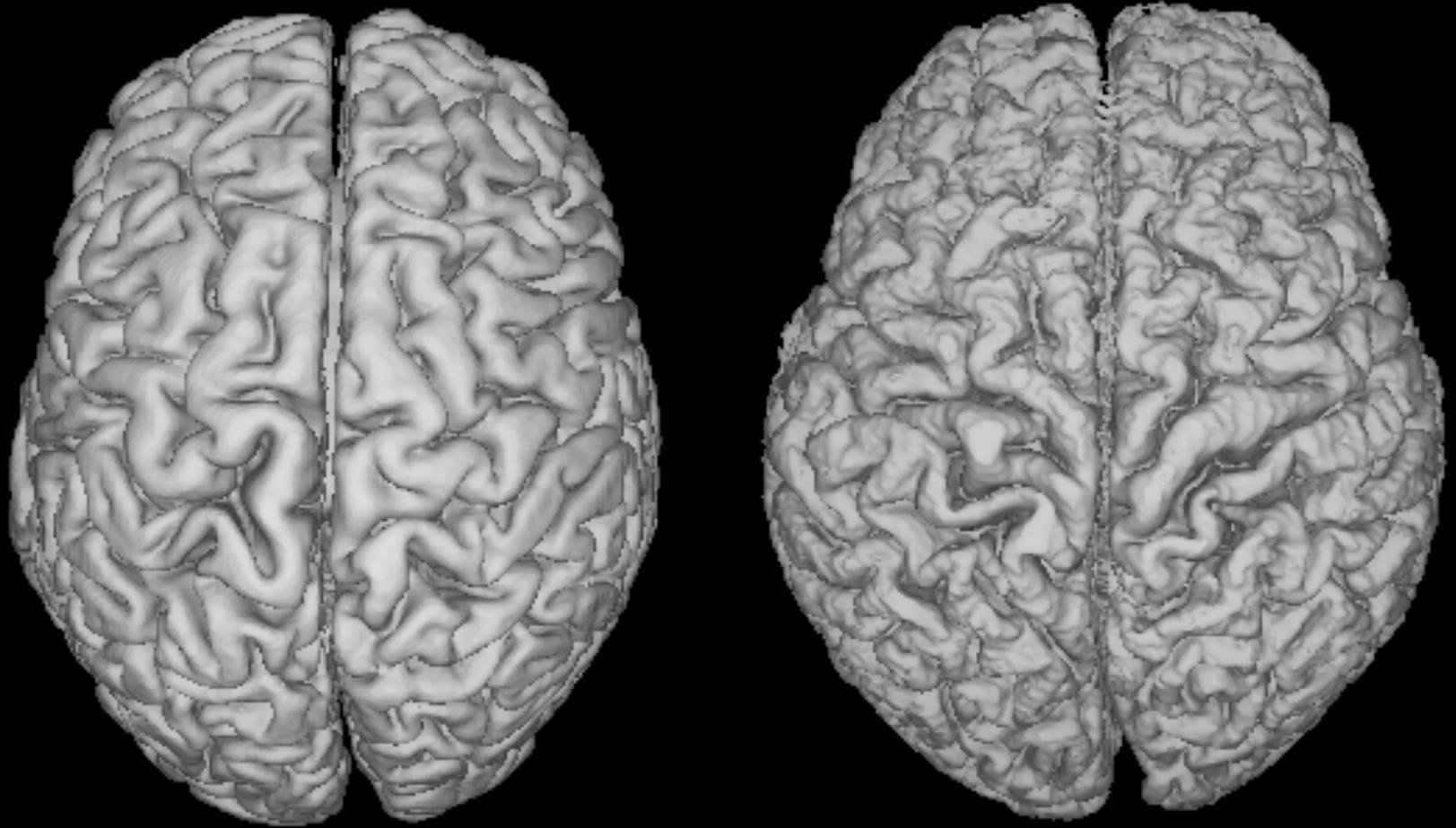


Sagittal Slice

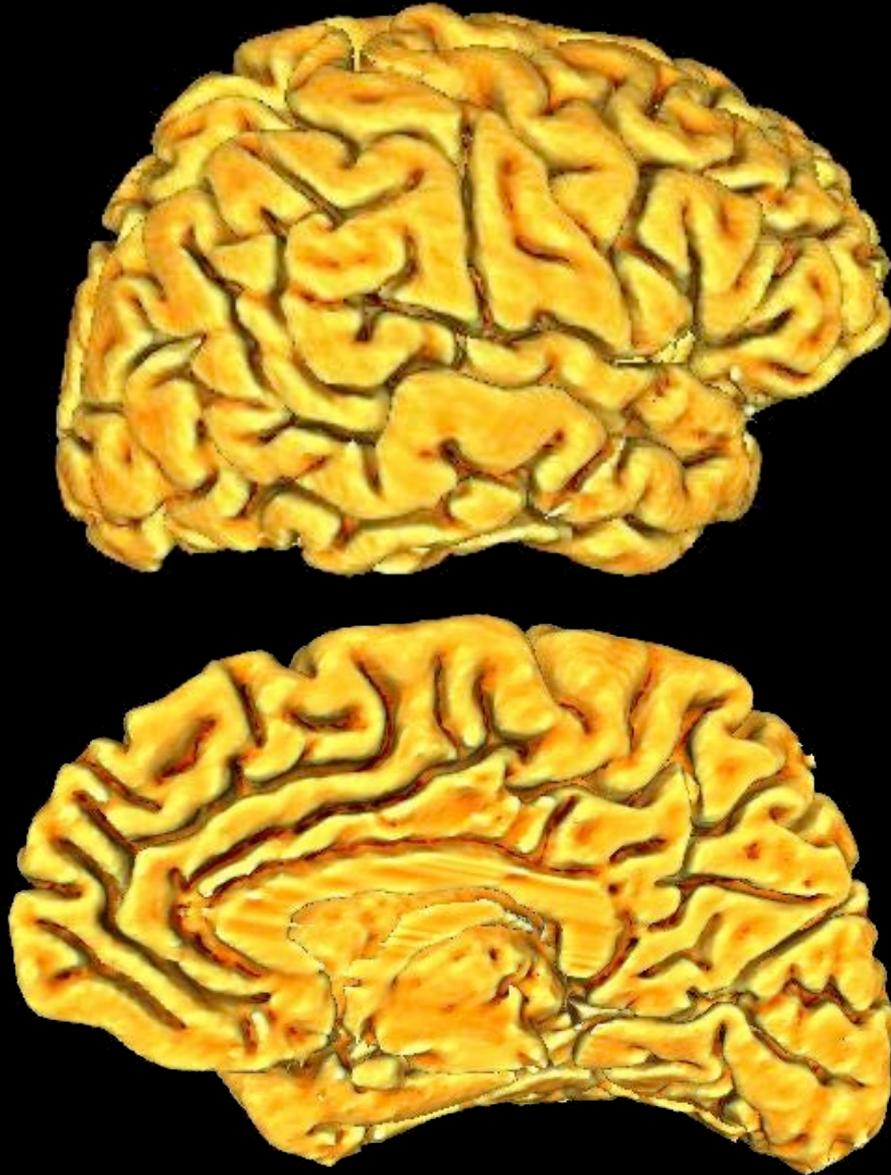
# Neural Tissue Reconstruction



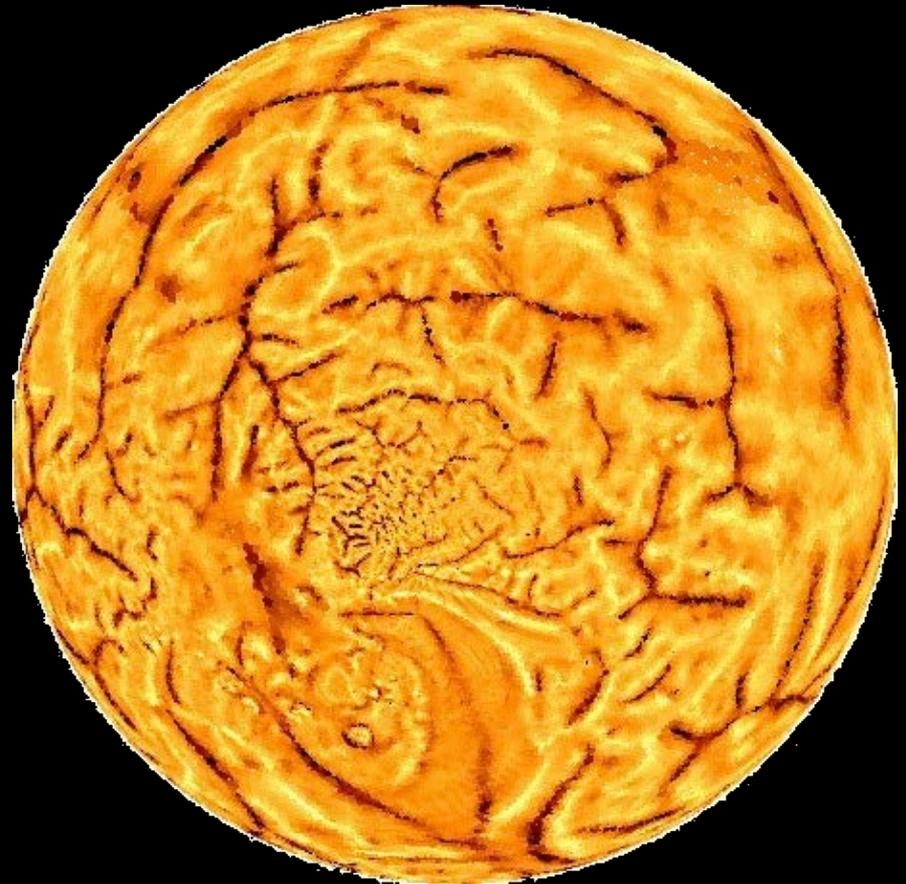
# Individual Variability



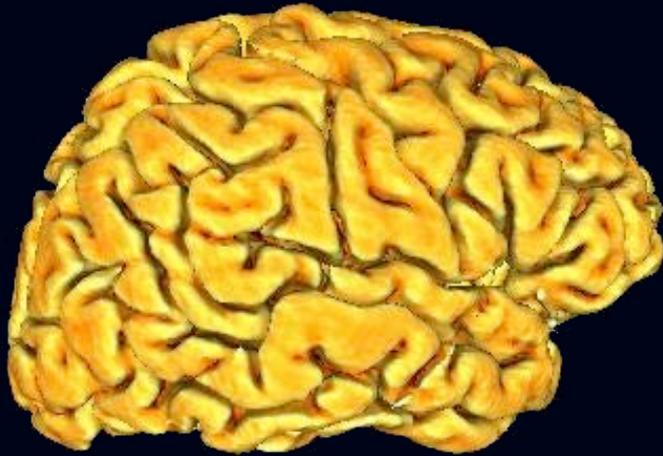
# Mapping a Cortical Hemisphere



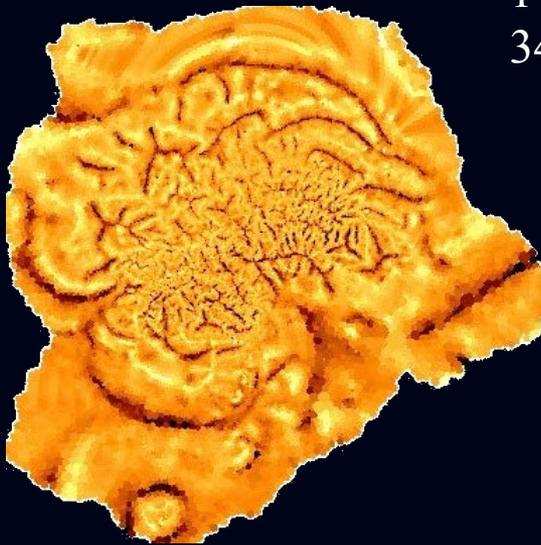
181,154 vertices  
362,304 triangles



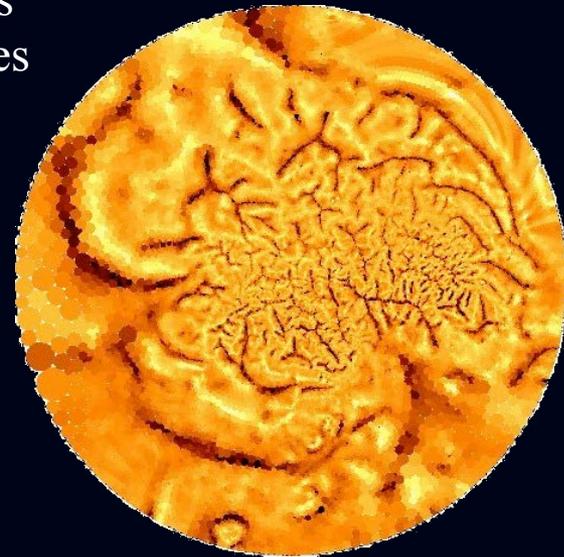
# Mapping to the Plane



170,909 vertices  
341,463 triangles



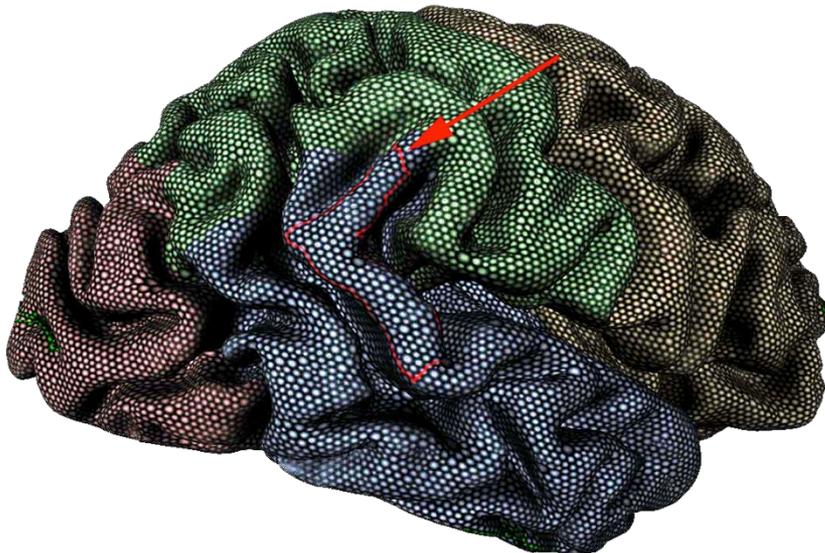
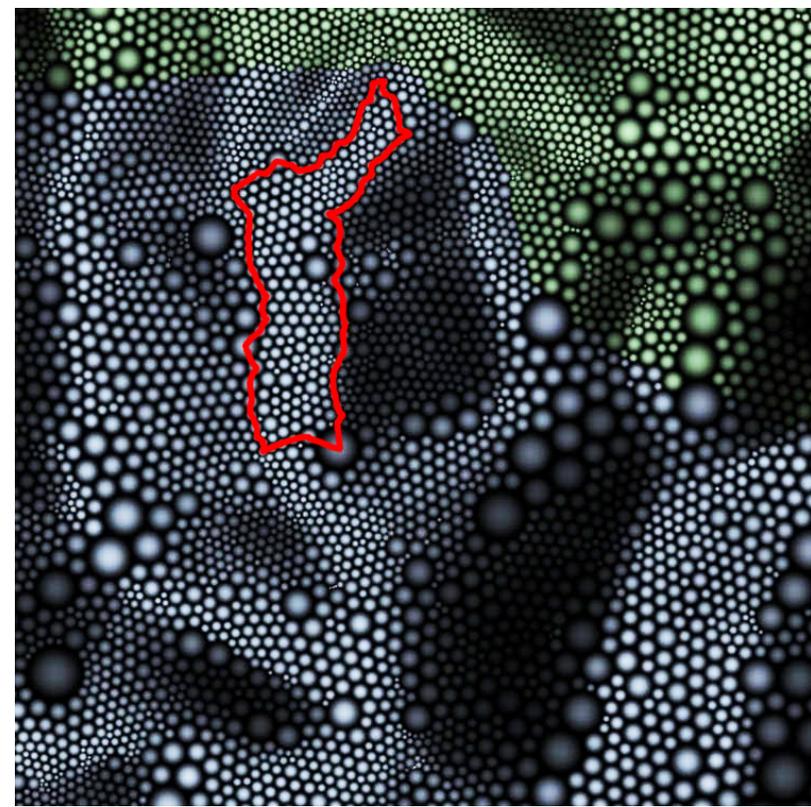
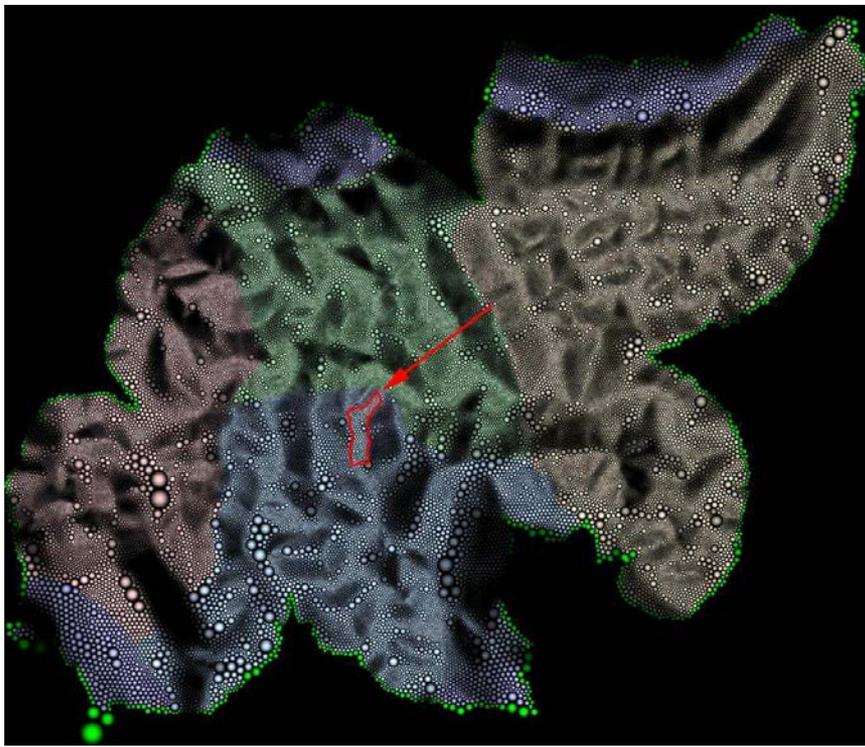
Euclidean Map



Hyperbolic Map

# Visualizing Flat Maps



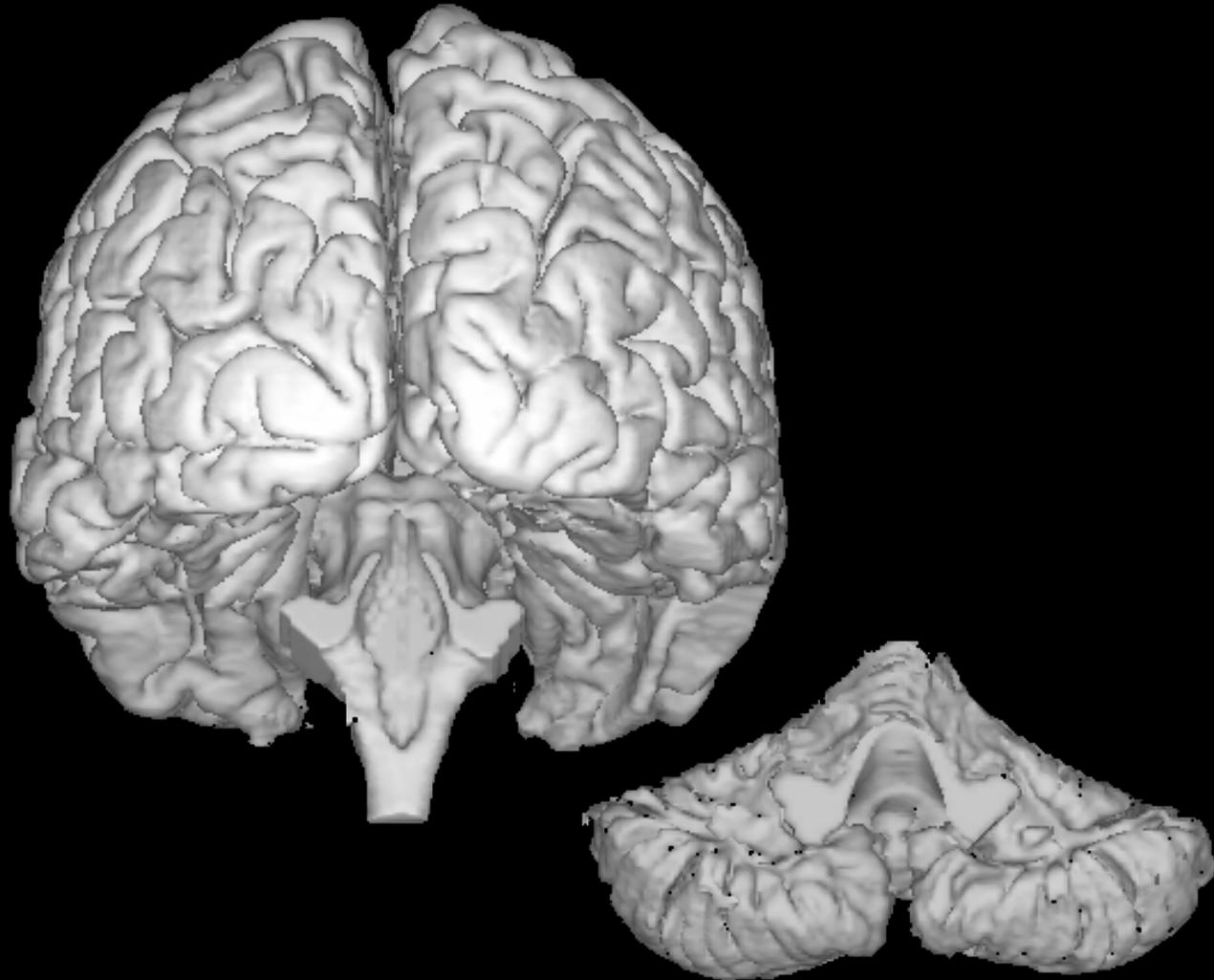


Area on flat map =  $121.82 \text{ mm}^2$   
Area on 3D surface =  $338.89 \text{ mm}^2$

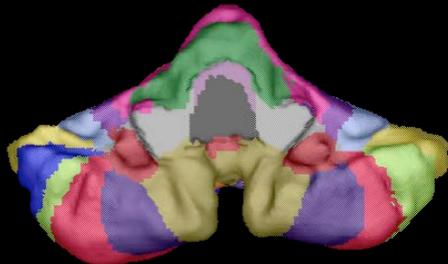
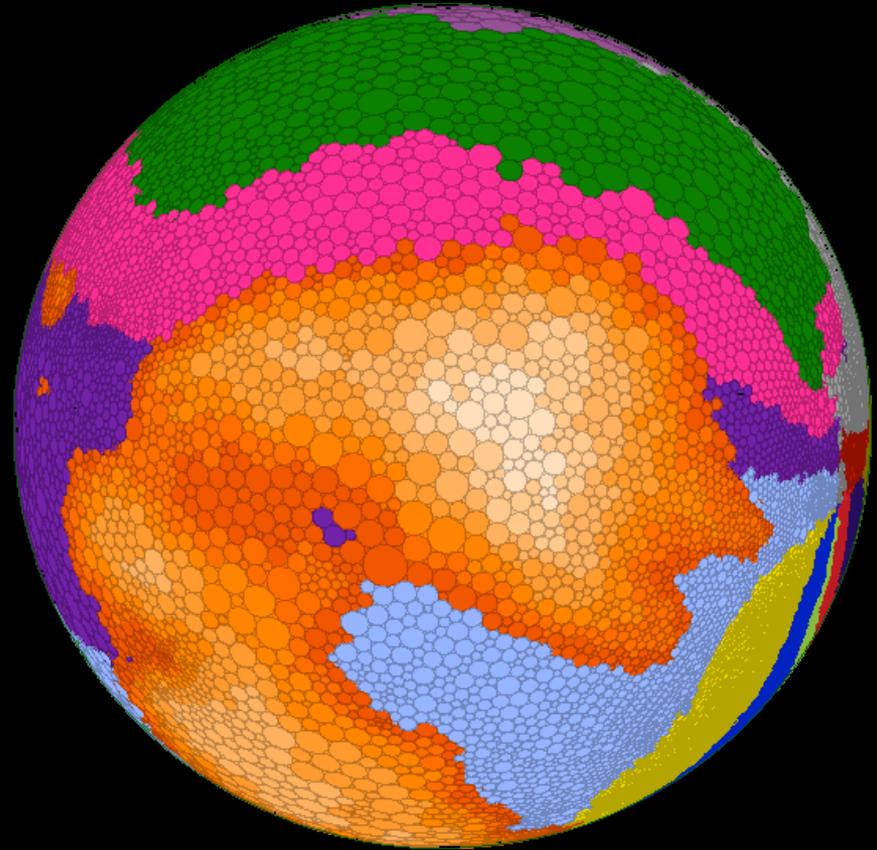
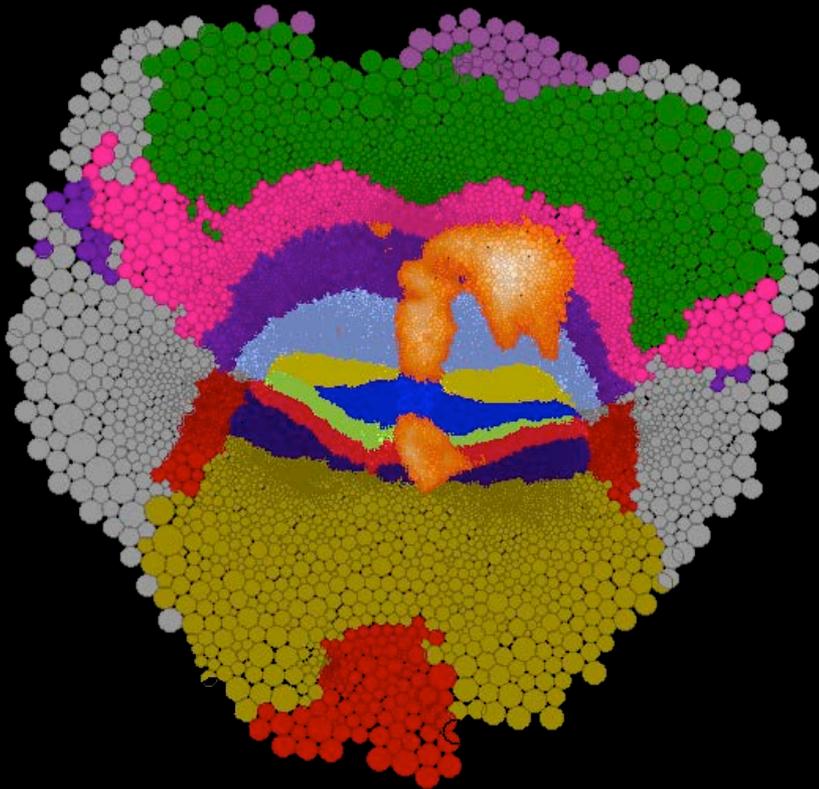
Note the shape of the region is similar on the cortical surface and flat map. This is one of the advantages of conformal mapping.

# Mapping a Cerebellum

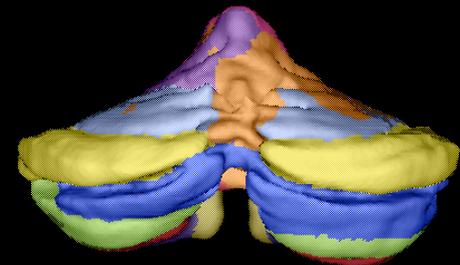
Data courtesy of D. Rottenberg, U. Minnesota



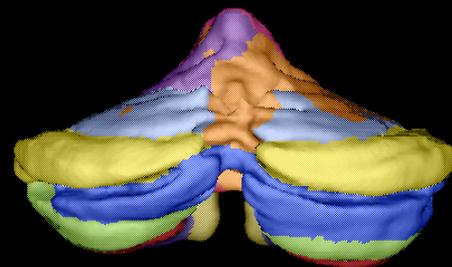
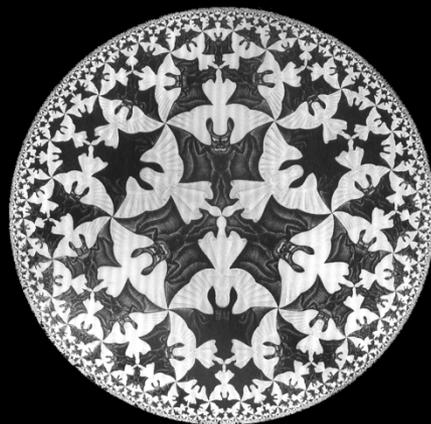
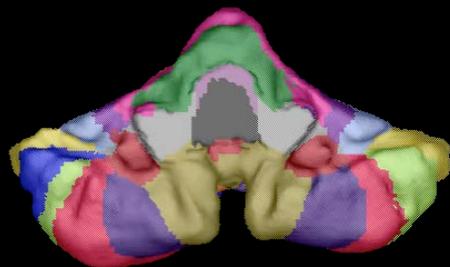
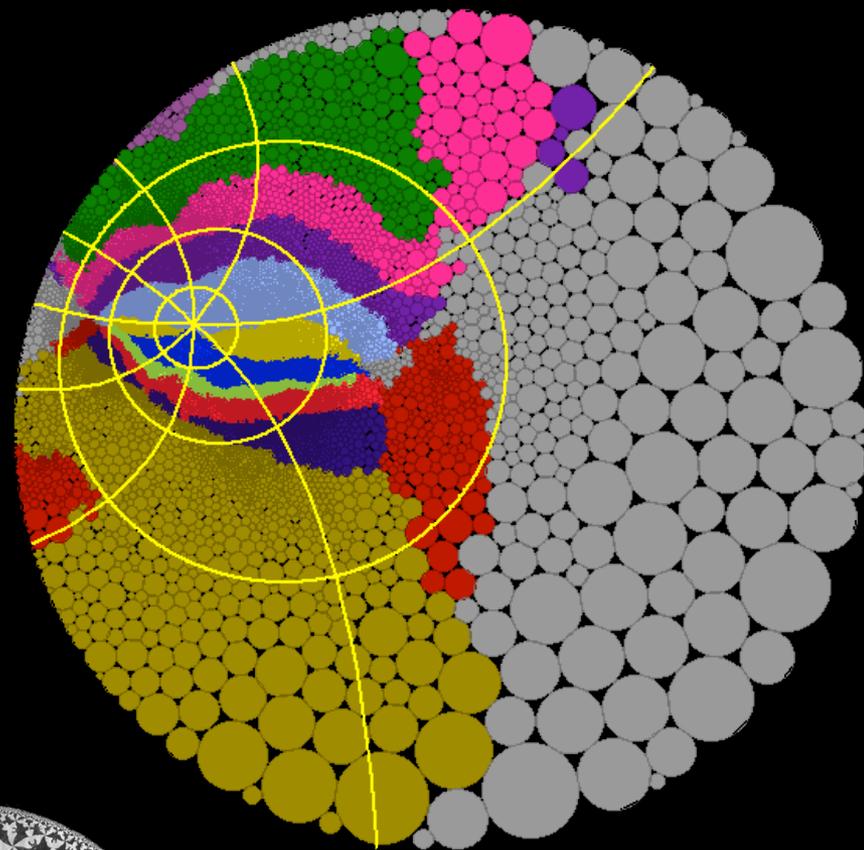
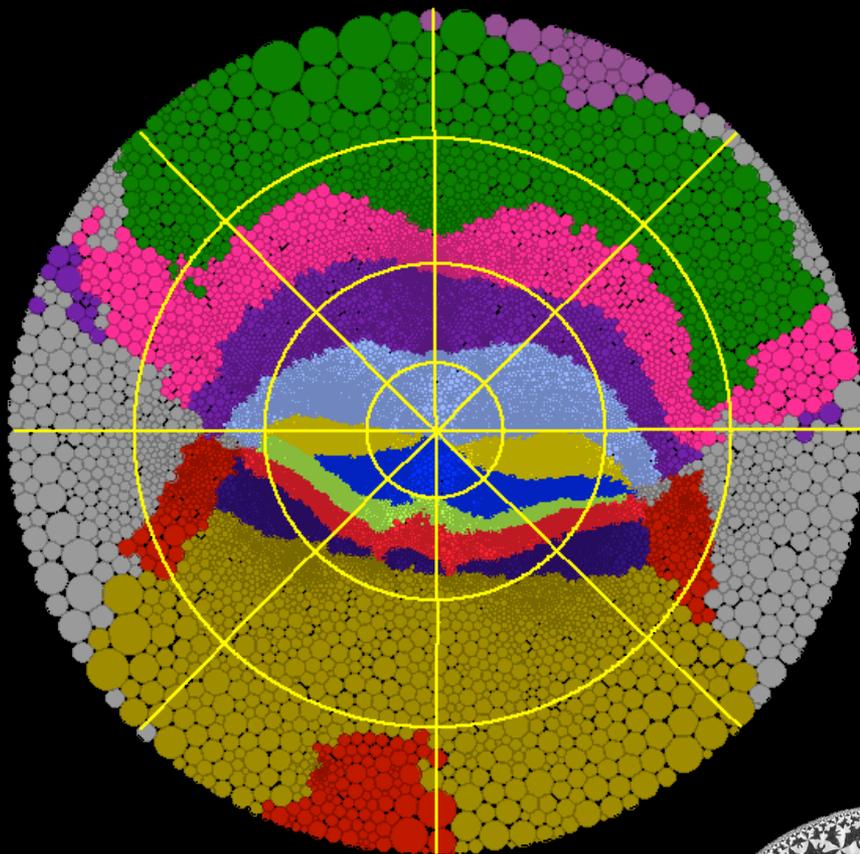
# Euclidean & Spherical Maps



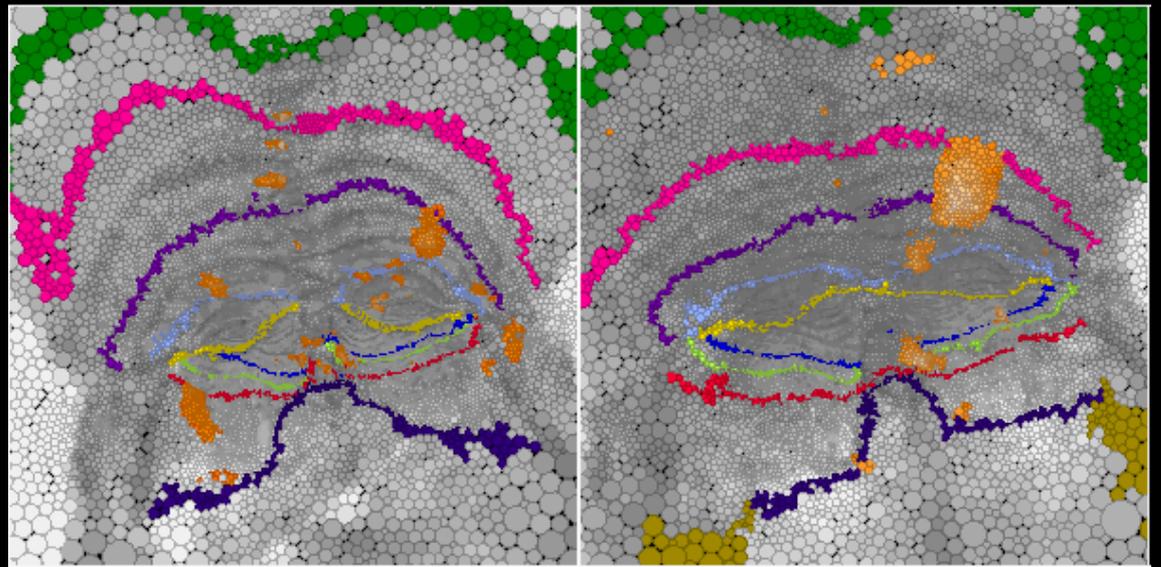
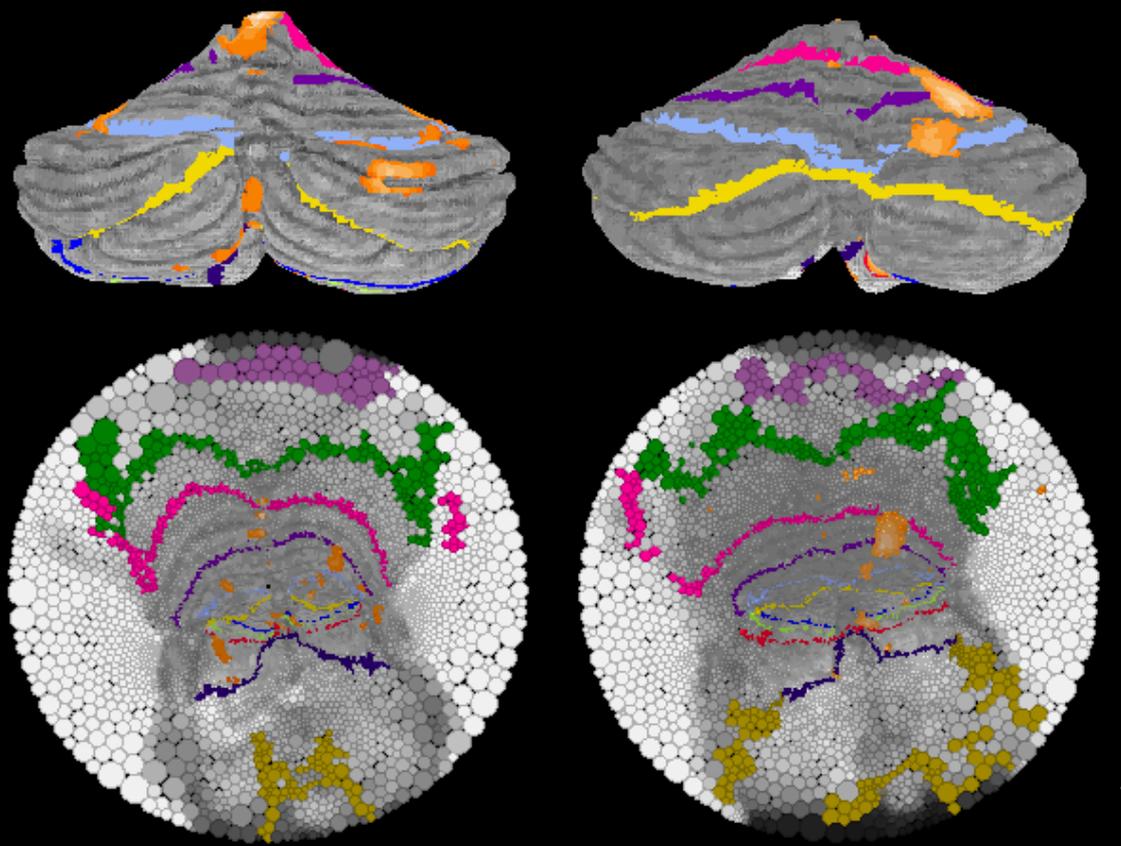
Surface:  
28,340 vertices  
56,676 triangles



# Hyperbolic Maps



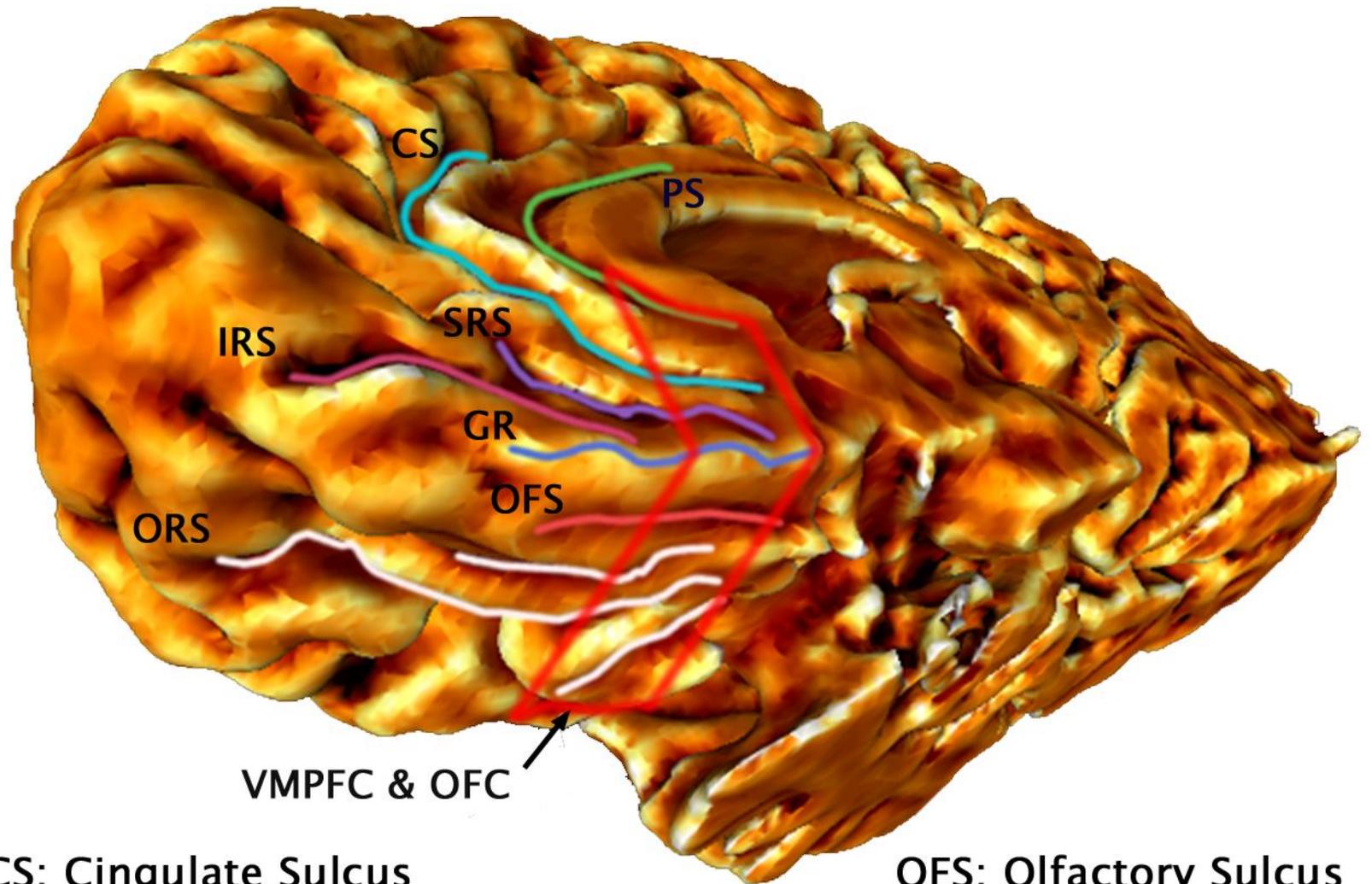
# Flat Maps of Different Subjects



# Twin Study

Collaboration with Center for Imaging Science (Biomed. Eng.), Johns Hopkins U. & Psychiatry and Radiology Departments, Washington U. School of Medicine

- As with non-twin brains, identical twin brains have individual variability i.e. brains are **NOT** identical in the location, size and extent of folds
- Aim: determine if twin brains more similar than non-twin brains
  - if so, this can be used to help identify where a disease manifests itself if one twin has a disease/condition that the other does not
- Flat maps can help identify similarities and differences in the curvature and folding patterns
- Examining ventral medial prefrontal cortex (VMPFC)

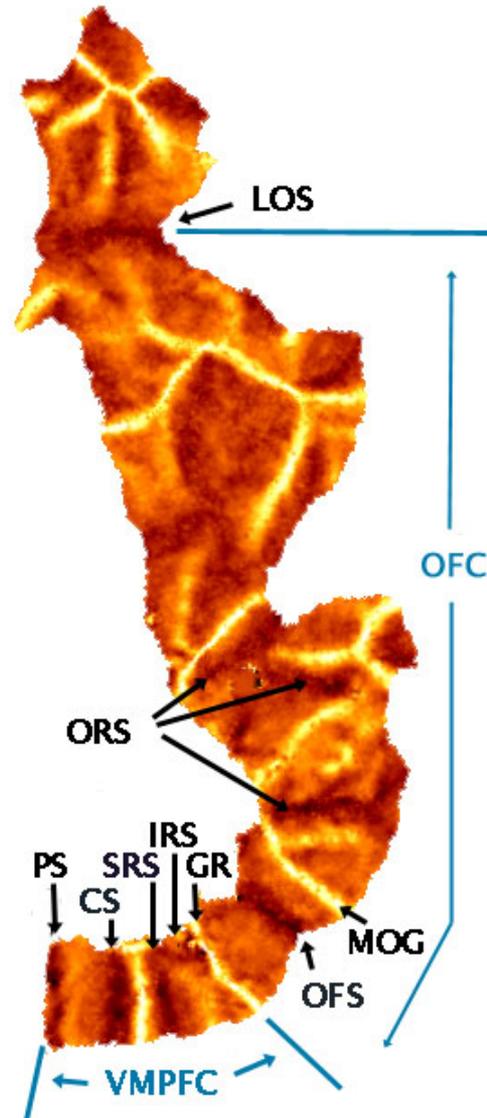
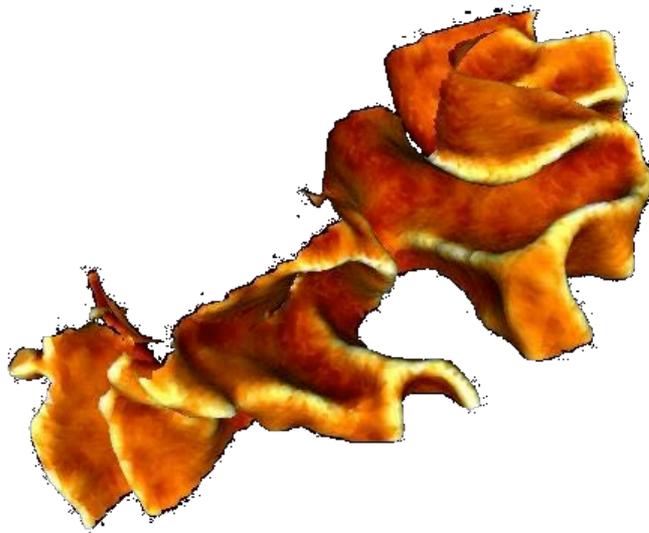


CS: Cingulate Sulcus  
GR: Gyrus Rectus  
IRS: Inferior Rostral Sulcus  
OFC: Olfactory Cortex  
VMPFC: Ventral Medial Prefrontal Cortex

OFS: Olfactory Sulcus  
ORS: Orbital Sulcus  
PS: Pericallosal Sulcus  
SRS: Superior Rostral Sulcus

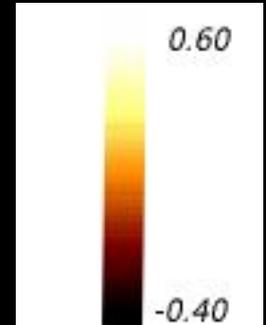
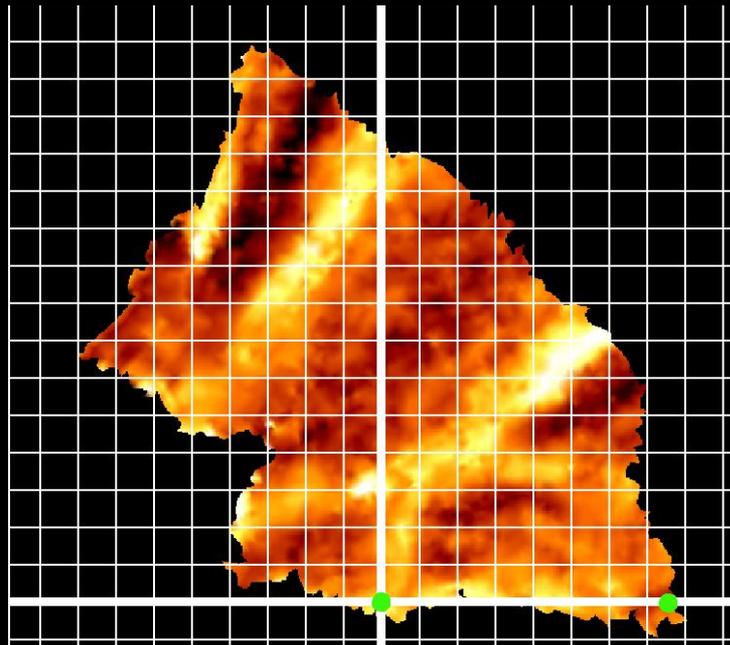
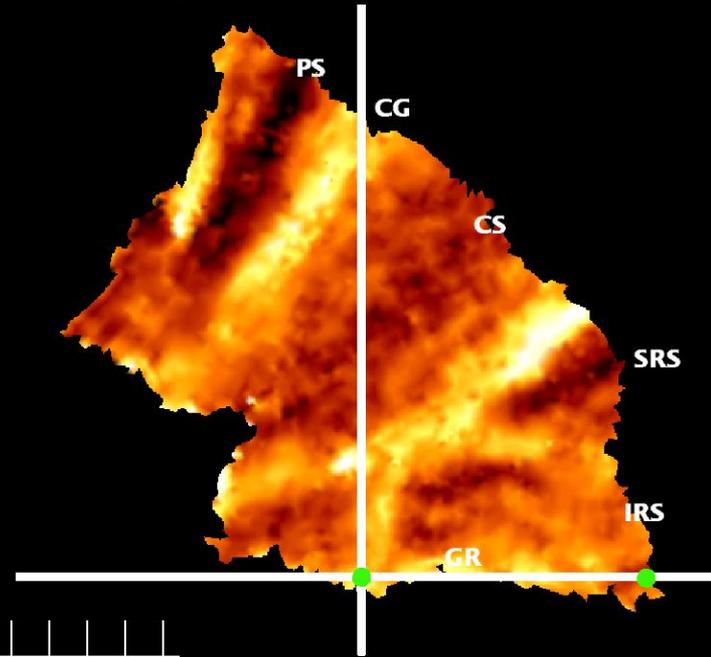
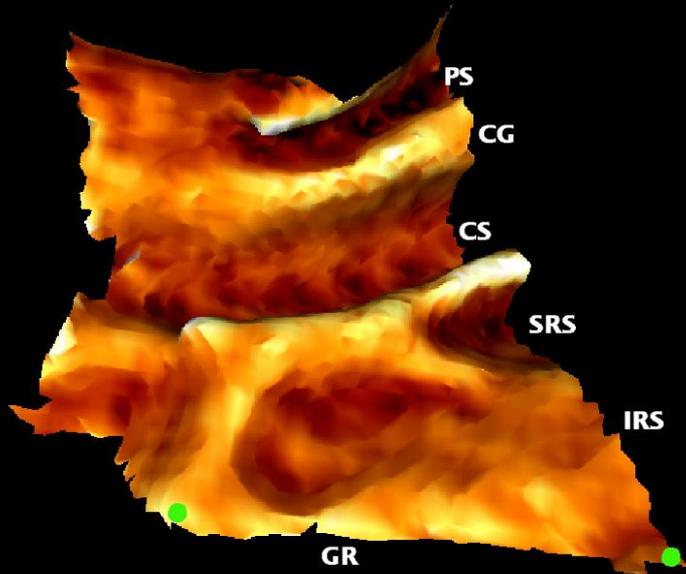
# Mapping a Cortical Region

Data courtesy of K. Botteron, Washington U. School of Medicine



- CG = cingulate gyrus
- CS = cingulate sulcus
- GR = gyrus rectus
- IRS = inferior rostral sulcus
- LOS = lateral orbital sulcus
- MOG = medial orbital gyrus
- OFC = orbital frontal cortex
- OFS = olfactory sulcus
- ORS = orbital sulci
- PS = pericallosal sulcus
- SRS = superior rostral sulcus

# VMPFC Coordinate System



Mean  
Curvature

# Circle Packing Flexibility: Rectangular Discrete Conformal Maps

- An advantage of conformal mapping via circle packing is the flexibility to map a region to a desired shape
- Boundary angles, rather than boundary radii are preserved
- For a rectangle: 4 boundary vertices are nominated to act as the corners of the rectangle
- Aspect ratio (width/height) is a *conformal invariant* of the surface (relative to the 4 corners) and is called the *extremal length*.
- Conformal extremal length represents one measure of shape
- Two surfaces are conformally equivalent if and only if their conformal modulus is the same

# Euclidean Maps: Specify Boundary Radius or Angle

Twin A

Twin B

Left

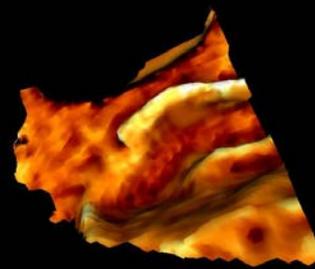
Right

Left

Right



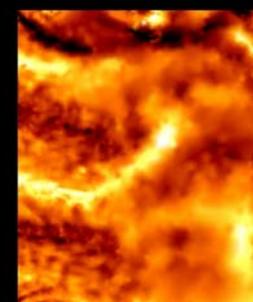
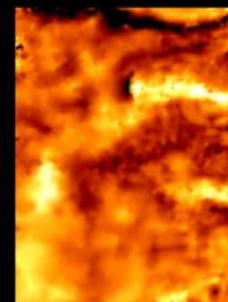
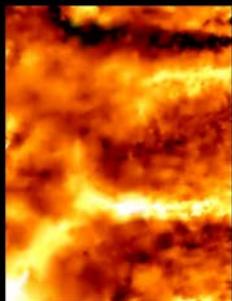
3D  
Surface



Euclidean Map:  
Boundary Radius



Euclidean Map:  
Boundary Angle



0.750

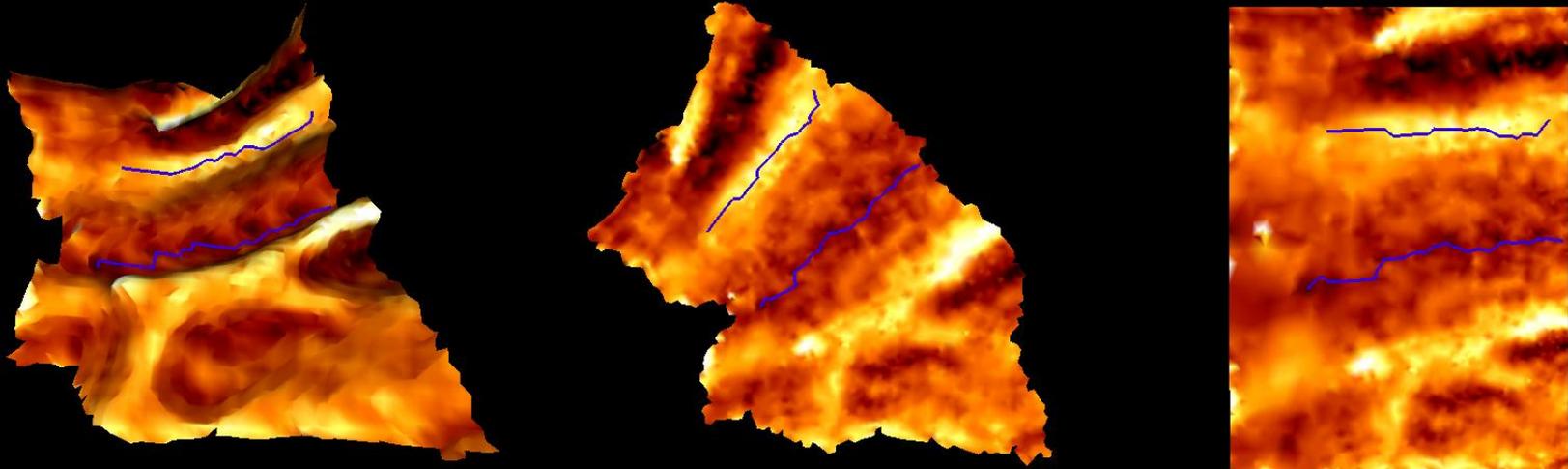
0.802

Conformal Modulus

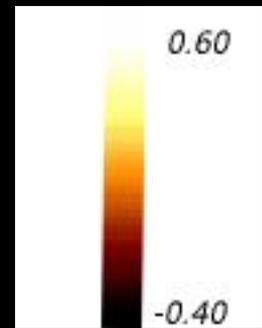
0.731

0.806

# Tracking Lines of Principal Curvature

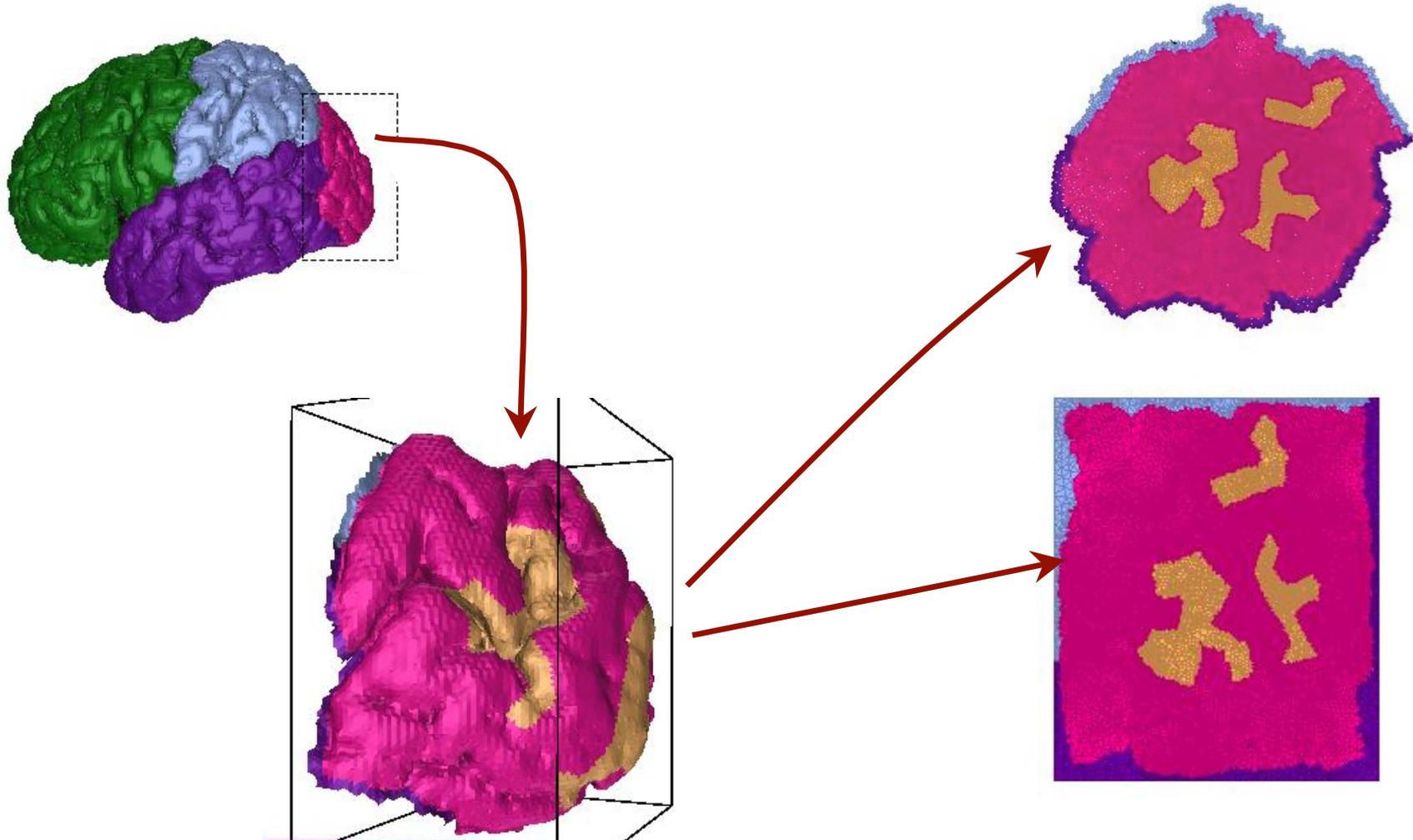


- Path of maximal curvature tracks along a gyrus / fold (top line).
- Path of minimal curvature tracks along a sulcus / fissure (bottom line).



Mean  
Curvature

# Euclidean Maps: Specify Boundary Radius or Angle



# Circle Packing Flexibility: Preserve Inversive Distance Rather than Circle Tangency

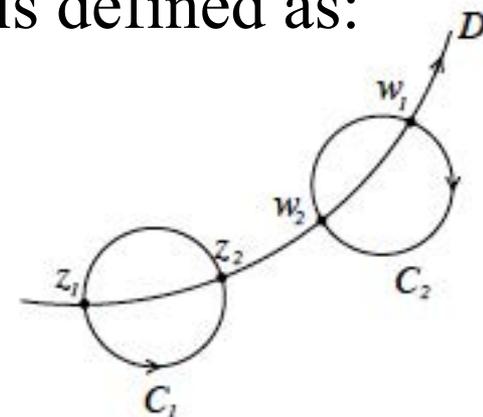
- Inversive distance between two oriented circles in the Riemann sphere is a conformal invariant of the location of the circles and their relative orientations
- As with tangency packings, inversive distance packings require radii of boundary circles or angle sums at boundary vertices to be specified

# Inversive Distance

Let oriented circle  $D$  be mutually orthogonal to oriented circles  $C_1$  and  $C_2$ . Denote  $z_1, z_2$  as the points of intersection of  $D$  with  $C_1$  and  $w_1, w_2$  as the points of intersection of  $D$  with  $C_2$ . The inversive distance between  $C_1$  and  $C_2$  is defined as:

- $$\text{InvDist}(C_1, C_2) = 2[ z_1, z_2 ; w_1, w_2 ] - 1$$

$$= 2 \frac{(z_1 - w_1)(z_2 - w_2)}{(z_1 - z_2)(w_1 - w_2)} - 1$$



- $\text{InvDist}(C_1, C_2) = 1$  if  $C_1$  and  $C_2$  are tangent
- $\text{InvDist}(C_1, C_2) = \cos \alpha$ , if  $C_1$  and  $C_2$  intersect with angle  $\alpha$   
 $\Rightarrow 0 \leq \text{InvDist}(C_1, C_2) < 1$
- $\text{InvDist}(C_1, C_2) = \cosh \delta$ , where  $\delta$  is the hyperbolic distance between the hyperbolic planes bounded by disjoint circles  $C_1$  and  $C_2$   
 $\Rightarrow 1 < \text{InvDist}(C_1, C_2) < \infty$

# Computing Inversive Distance

## Circle Patterns

- $K$  = triangulation of a disk with four distinguished boundary vertices with edge set  $E$  and vertex set  $V$
- $\Phi: E \rightarrow [0, \infty)$  an inversive distance edge labeling

### *Euclidean Formulation*

- For oriented circles  $C_1$  and  $C_2$  with radii  $R_1$  and  $R_2$  and centered at  $a_1$  and  $a_2$  respectively:

$$\text{InvDist}(C_1, C_2) = (|a_1 - a_2|^2 - R_1^2 - R_2^2)/2R_1R_2$$

Notes: observe  $|a_1 - a_2| = \text{edge length } e_{1,2} = \langle v_1, v_2 \rangle$

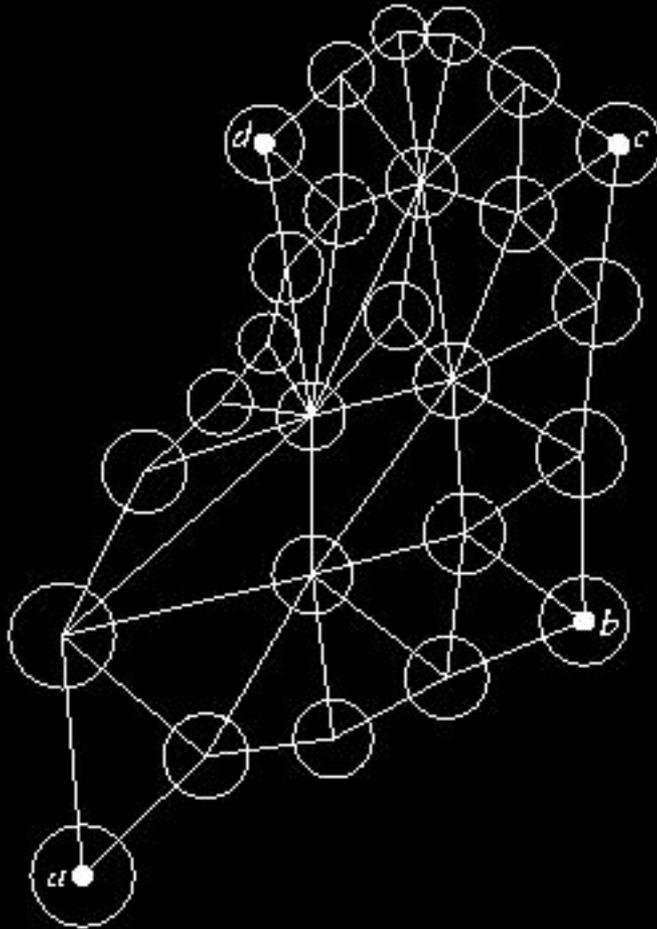
For convergence, require  $R_i$  to be a constant function. Thus:

$$\text{InvDist}(C_1, C_2) = \Phi(e_{1,2}, R) = e^2/(2R^2) - 1$$

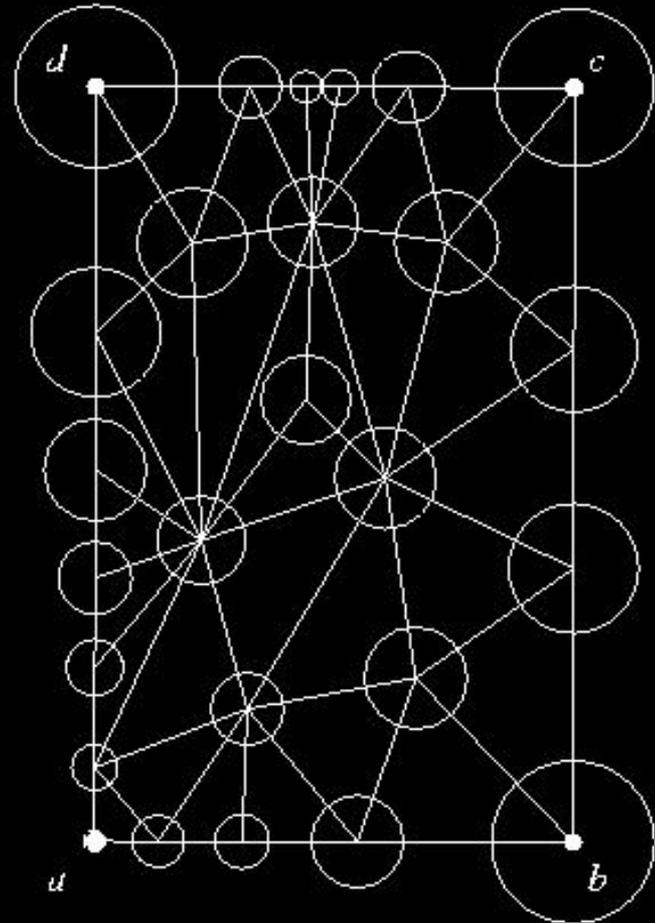
**Existence/uniqueness questions???**

# Two Circle Packings for the Same Data ( $K, \Phi$ )

Specifying Boundary Edge



Specifying Boundary Angle



$$\Phi(e, R=\min(e/2))$$

# Inversive Distance Algorithm: Hexagonal Refinement

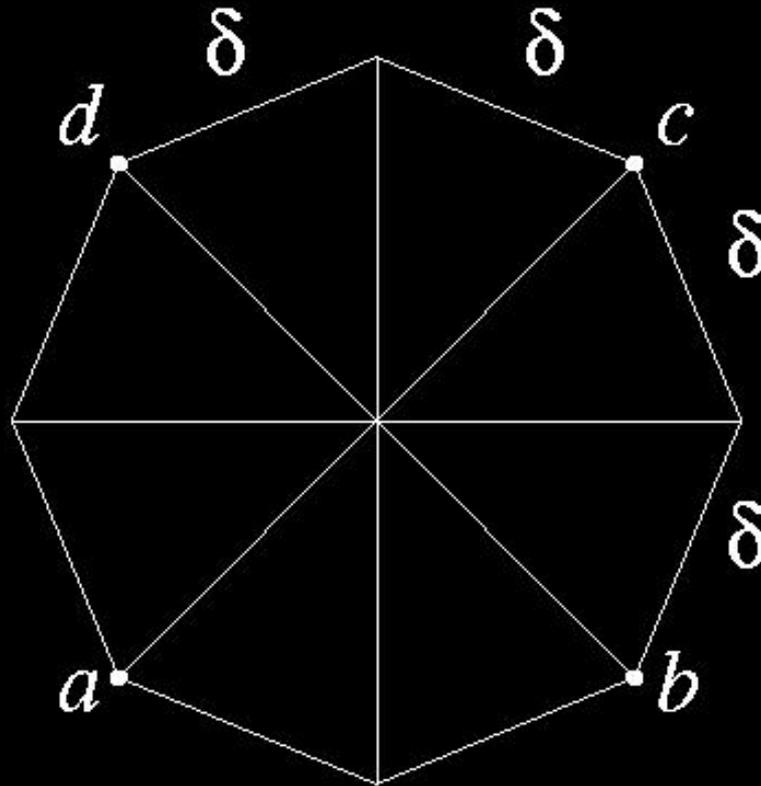


- $K' = \text{hex}(K)$  (hex refine complex  $K$ )
- $R' = R/2$  (compute new radius constant)
- $\Phi' = \Phi_{R'}$  (compute new inversive distance)
- Iterate hexagonal refinement:  
 $(K_{n+1}, R_{n+1}, \Phi_{n+1}, C_{n+1}) = (K'_n, R'_n, \Phi'_n, C'_n)$
- **Conjecture:**  $C_n$  converges to the conformal image of  $K$  where  $C = \text{circle pattern}$  (simulations show this is true)

# Example: Converging to Conformality

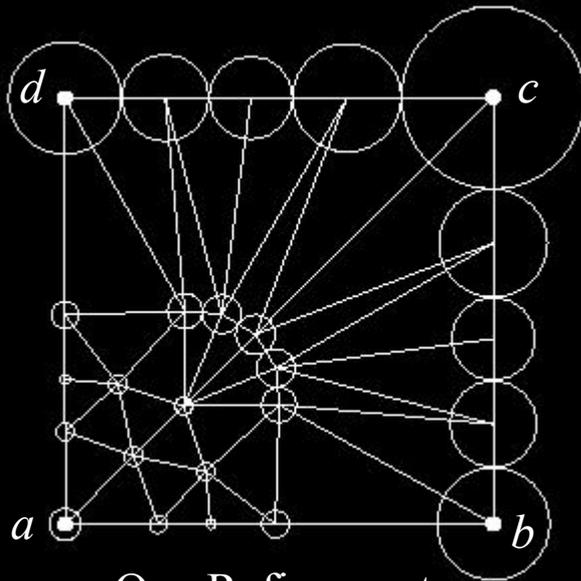
$$\delta = 2 \sin(\pi / 24) \approx 0.26105$$

Other edges have unit length

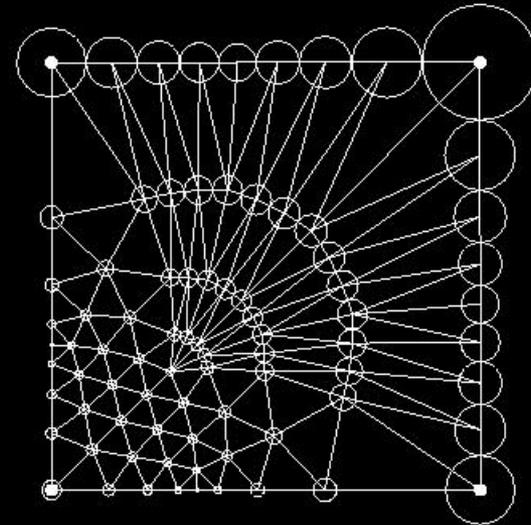


Angles opposite  $\delta = 15^\circ$

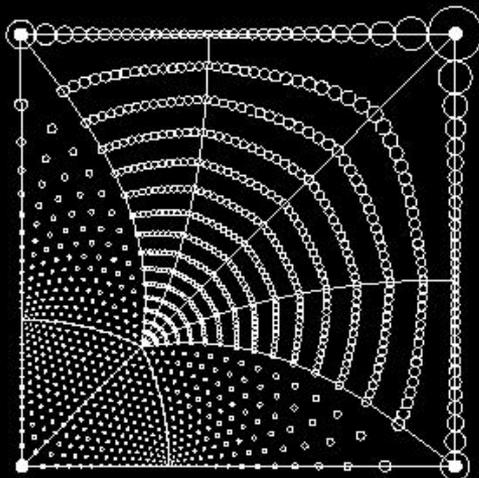
# Four Stages of Refinement



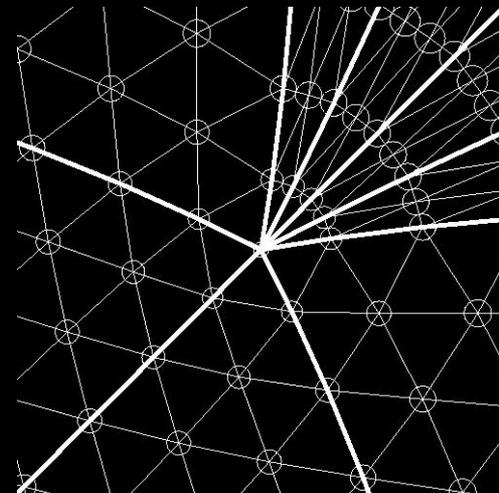
One Refinement



Two Refinements

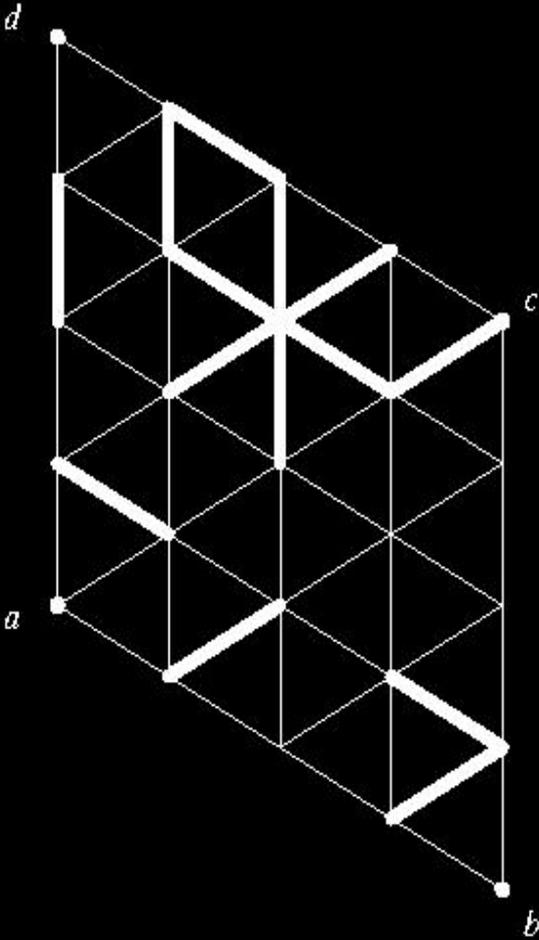


Four Refinements



Close-up

# Example: Hexagonal Grid



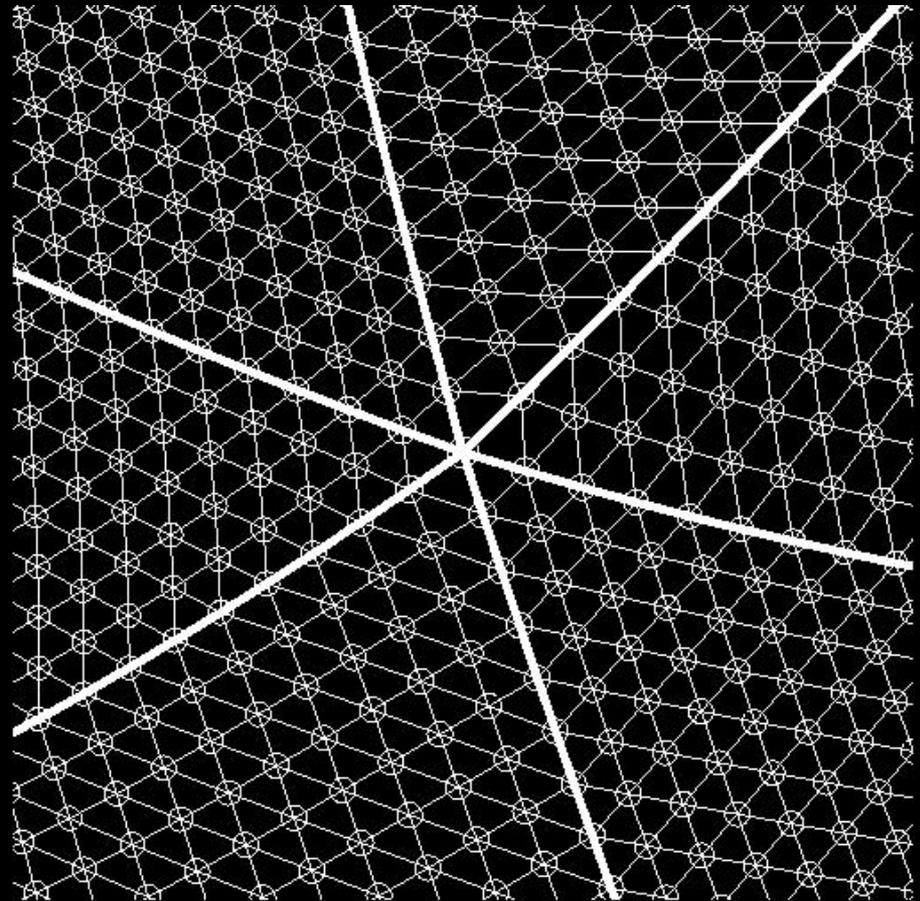
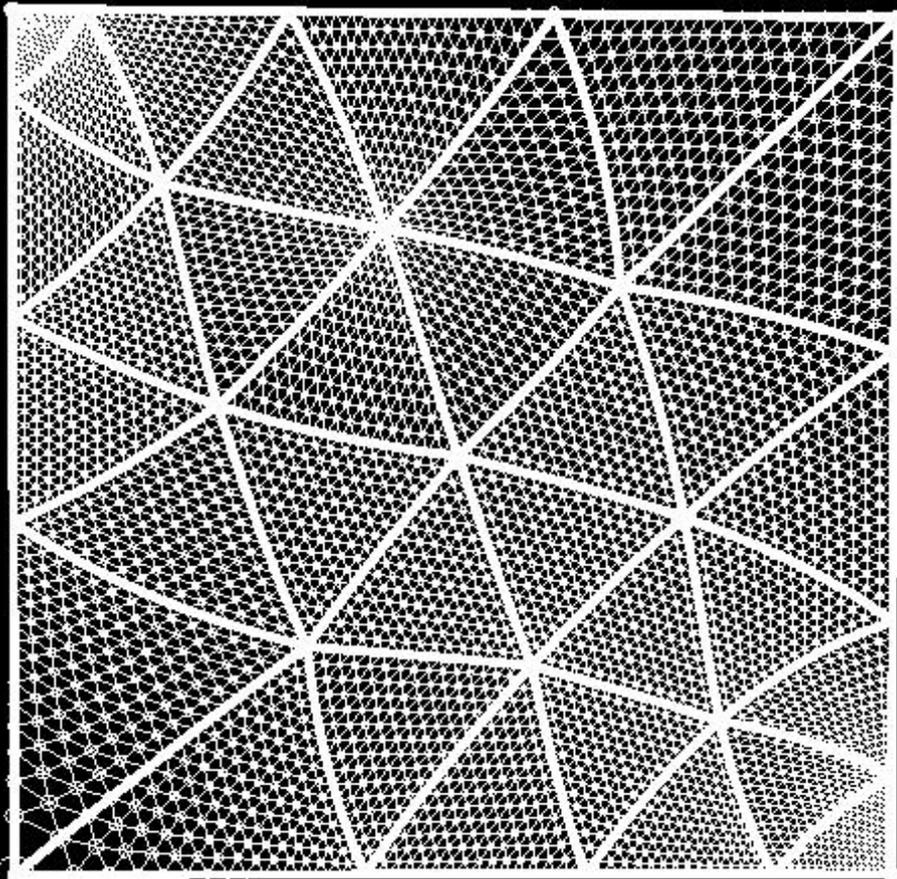
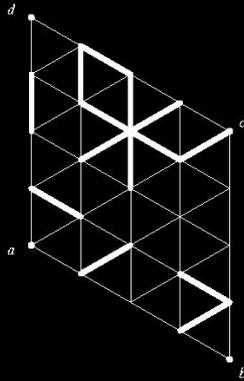
- Lengths of bold edges are 1.1
- Other edge lengths are 1.4
  
- Now: adjust  $R$  to construct a variety of overlapping, tangent, and disjoint circle packings using inversive distance

# Disjoint Circles:

$$R = 1/4$$

$$\Phi(e\_bold = 1.1, R = 1/4) = 8.6800$$

$$\Phi(e\_other = 1.4, R = 1/4) = 14.6800$$

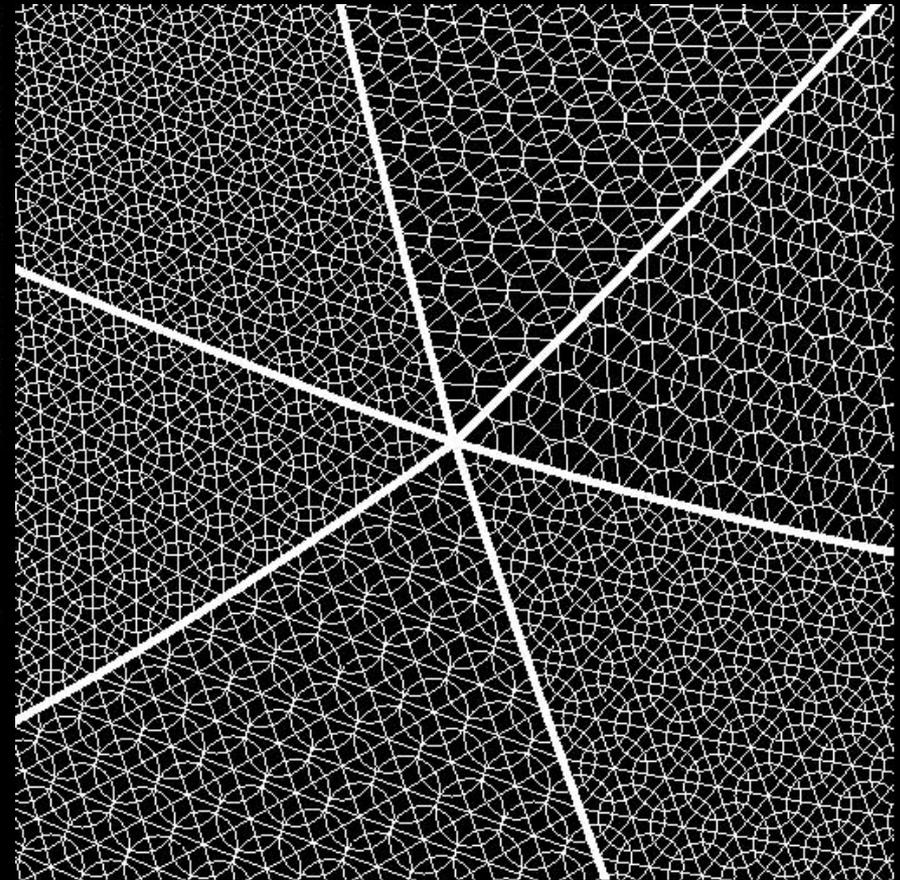
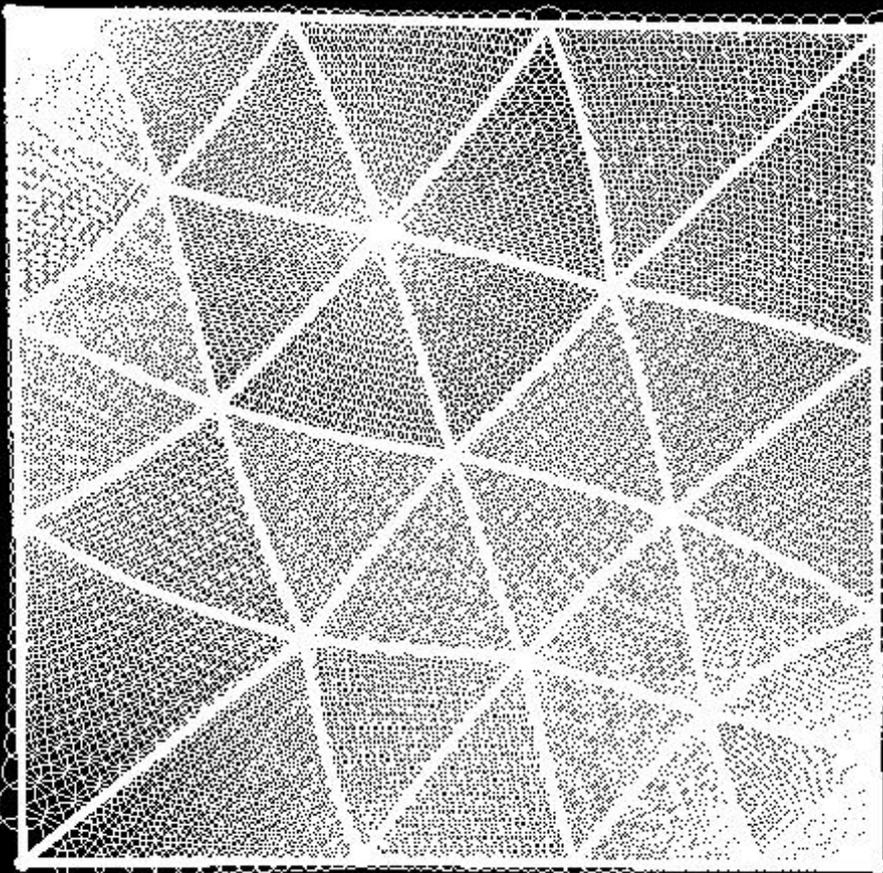
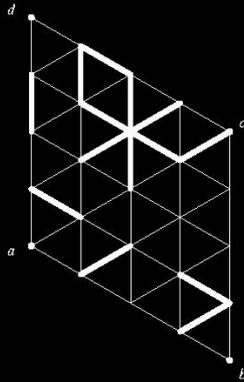


# Overlapping Circles:

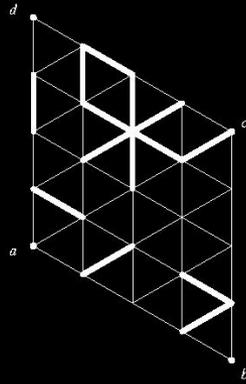
$$R = 1/\sqrt{2}$$

$$\Phi(e_{\text{bold}} = 1.1, R = 1/\sqrt{2}) = 0.2100$$

$$\Phi(e_{\text{other}} = 1.4, R = 1/\sqrt{2}) = 0.9600$$

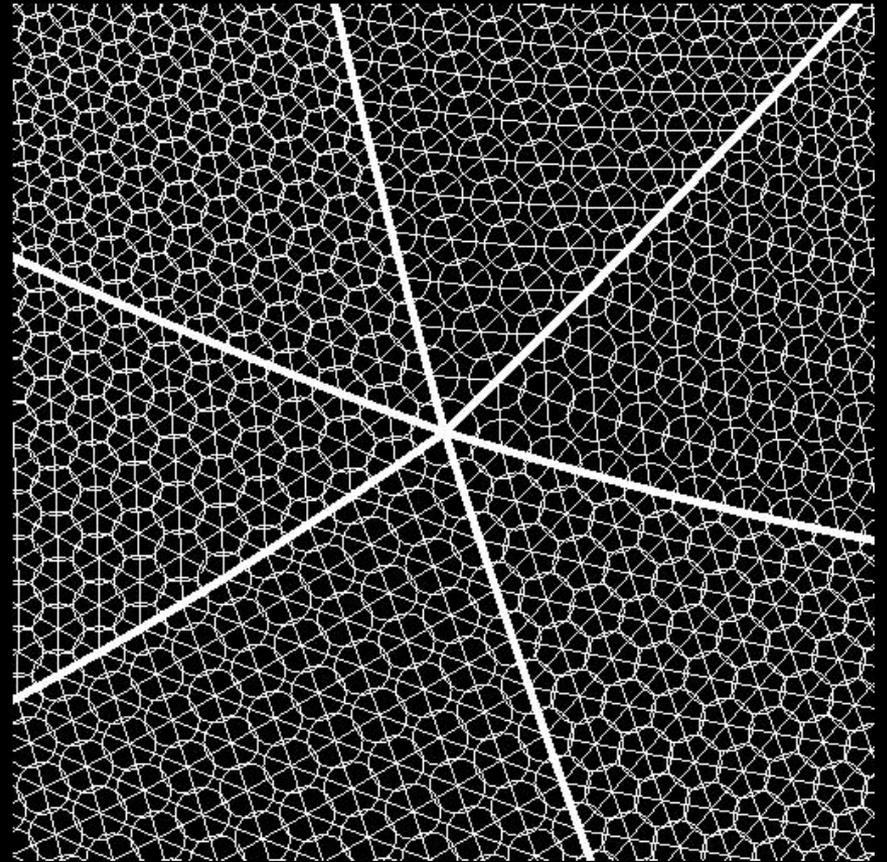
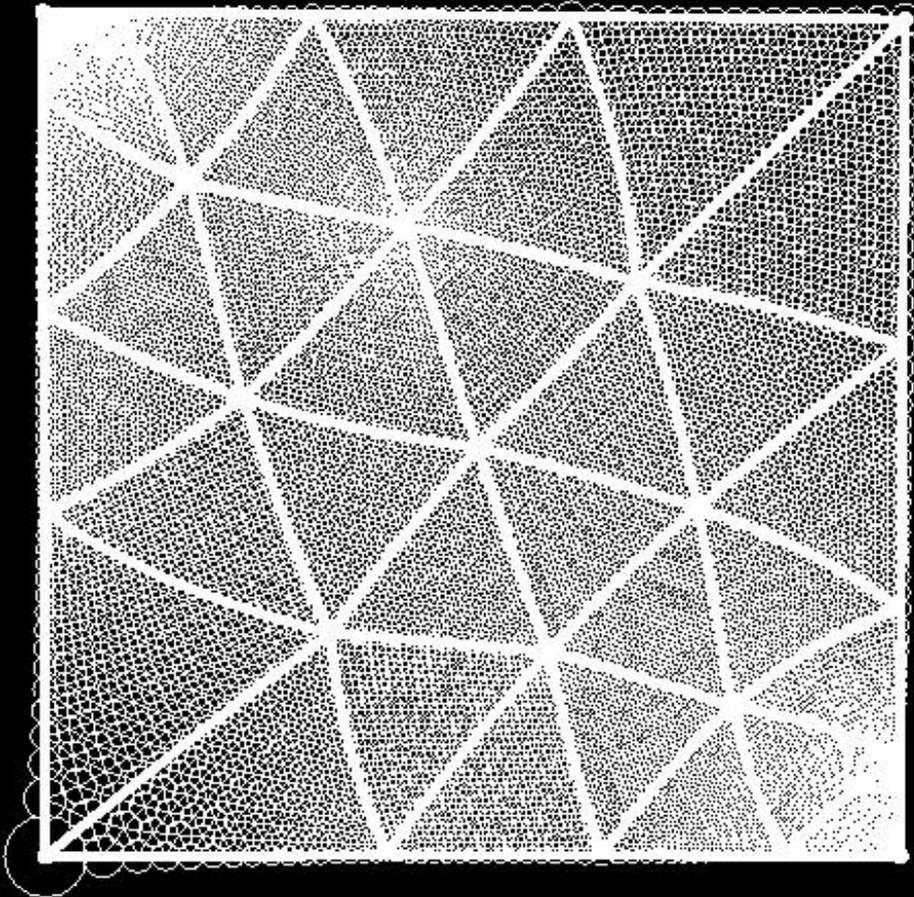


# Overlapping and Disjoint Circles: $R = 3/5$

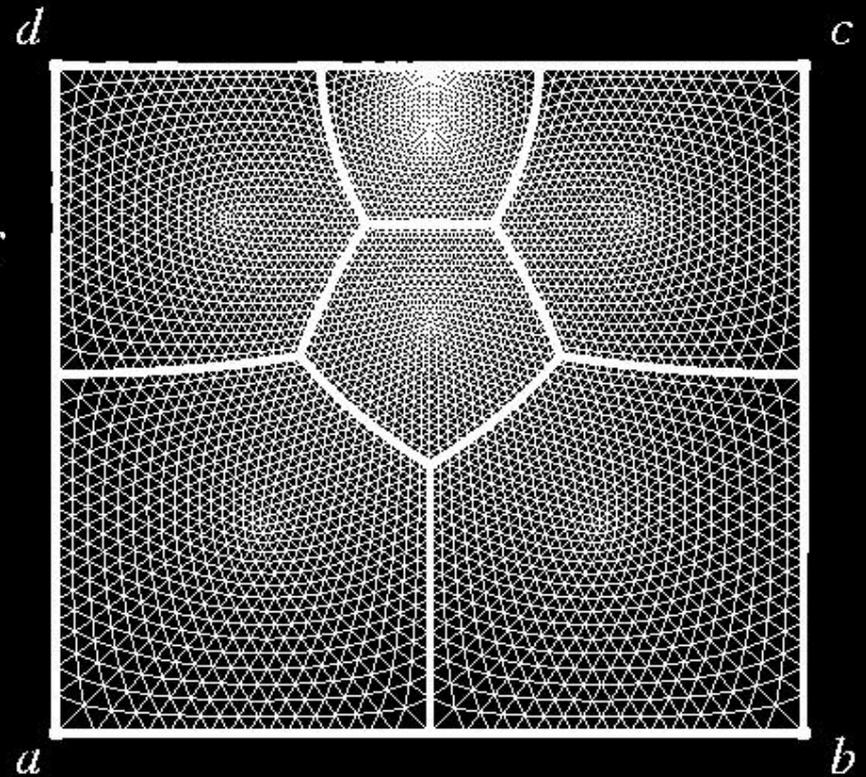
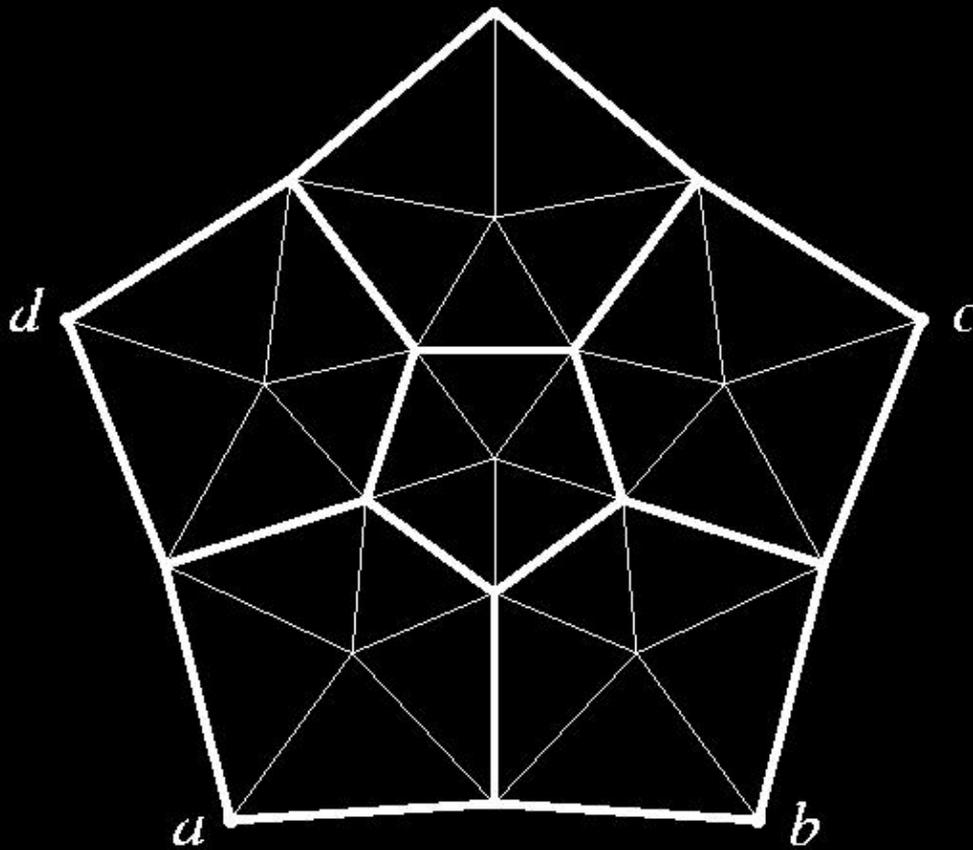


$$\Phi(e\_bold = 1.1, R = 3/5) = 0.6806$$

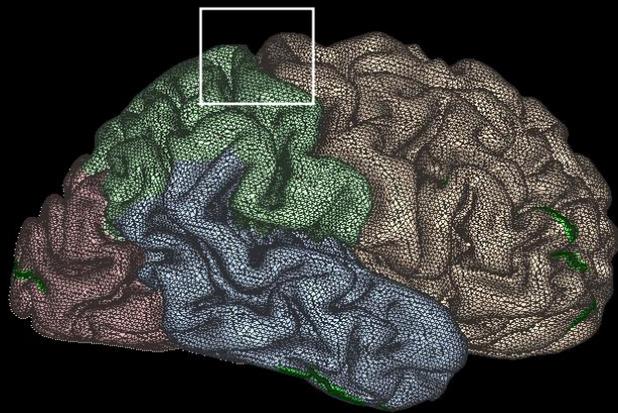
$$\Phi(e\_other = 1.4, R = 3/5) = 1.7222$$



# A Pentagonal Packing and its Reflective Triangulation

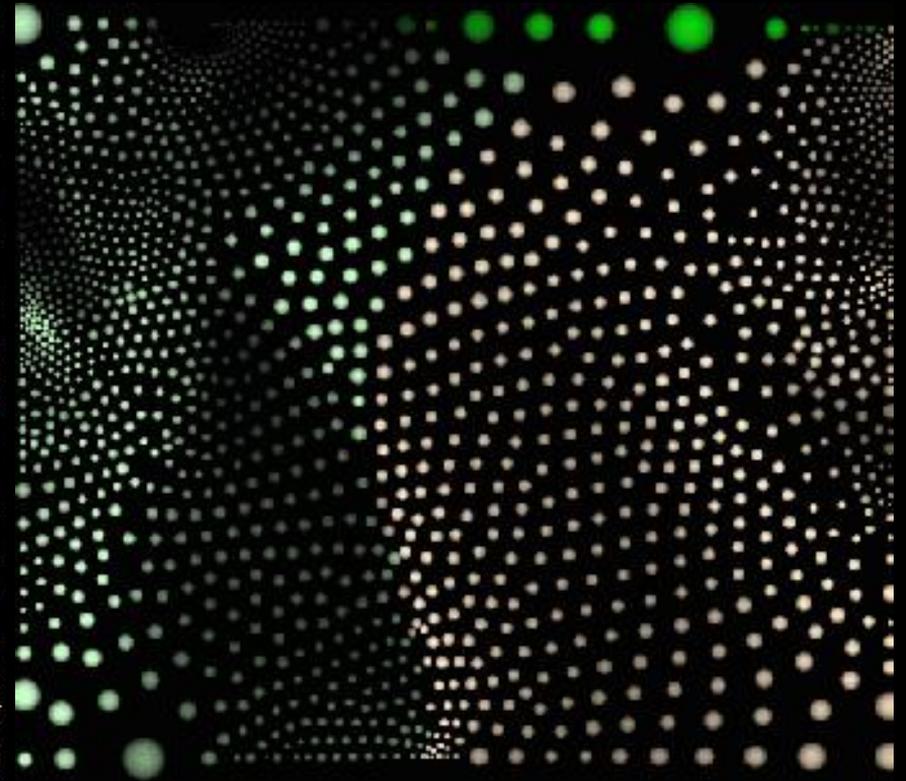
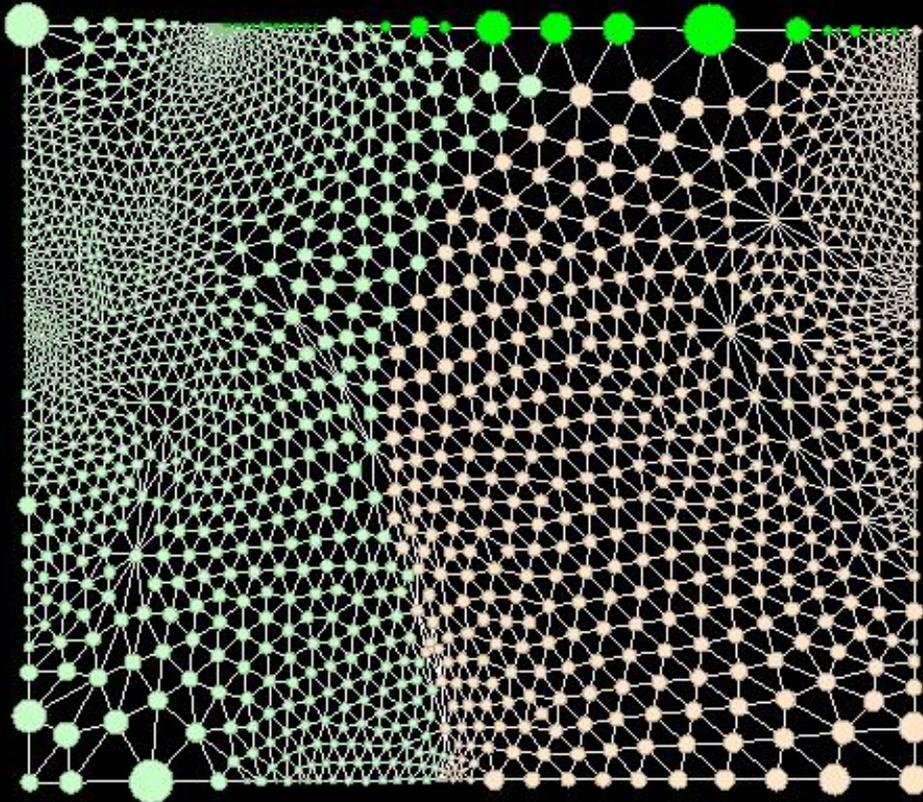


# Quadrilateral Subsurface



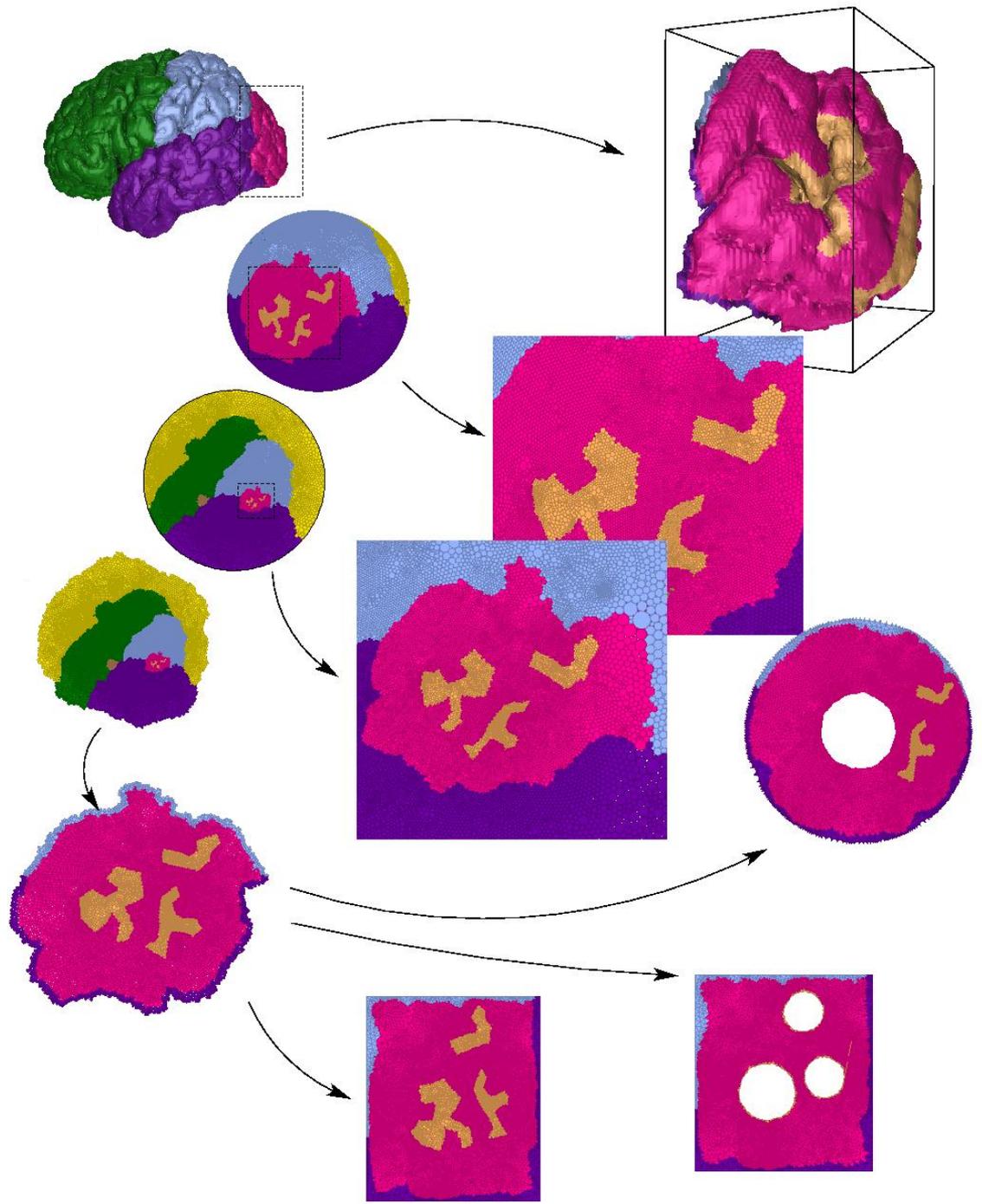


# Inversive Distance Packings



Bump Map Texture

# More Examples of Conformal Maps & Conformal Invariants



# Quasi-Conformal Maps in Neuroscience

*Used in neuroimaging studies of*

- Hippocampus
- Alzheimer's disease
- Schizophrenia
- Cerebellum
- Cortical shape matching
- Hemispheric asymmetry

*Used to model retinotopic mapping of visual cortex*

# Summary

- Circle packings are mathematically unique and converge to the discrete conformal map of a surface in the limit (i.e. through hex refinement) if triangulation is equilateral; otherwise yields an approximation to a discrete conformal map
- Euclidean, hyperbolic, spherical geometries available
- Flexible in terms of conformal mappings to shapes, circle tangency, inversive distance packings
- Some known applications: brain mapping, tilings, Dessins
- Open questions remain regarding existence, uniqueness for inversive distance packings; theory proved for tangency & overlap packings with prescribed angles of overlap

# Future Issues: Conformal Mapping in Neuroscience

- Compare maps between subjects: metrics
- Explore conformal metrics in brain data
- Alignment of different regions
  - align one volume or surface in 3-space to another and then quasi-conformally flat map
  - quasi-conformally flat map 2 different surfaces and then align/morph one to the other (in 2D)
- Analysis of similarities, differences between different map regions
- Experiment with rectangular tangency versus inversive distance maps

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## *More Information on Brain Mapping:*

- URL: <http://www.math.fsu.edu/~mhurdal>
- Email: [mhurdal@math.fsu.edu](mailto:mhurdal@math.fsu.edu)

