

### Families of $\sigma$ -fields.

A set,  $\Omega$ , may have many different  $\sigma$ -fields defined on it. Certainly there is a smallest and a largest. These being  $\{\emptyset, \Omega\}$  and the set of all subsets of  $\Omega$  respectively. One way of thinking

of  $\sigma$ -fields is to regard them as "information".

This information may be rather "coarse" or as "refined" as is possible, where the information may be summarized as "something in  $\Omega$  occurs". This is not altogether enlightening since  $\Omega$  is chosen to represent all possible outcomes in any case.

On the other hand the information may be as detailed as is possible and this may be modeled by the power set of  $\Omega$  — if this is appropriate. In this case all possible out-comes and any combination of them constitutes an event — a piece of information.

In using Probability Theory to model actual situations one usually encounters something (intermediate) between coarse and refined information. Indeed the information usually changes as time progresses. We can model a simple case by considering an increasing sequence of  $\sigma$ -fields  $\mathcal{F}_n, n=0,1,2,$

with  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \mathcal{F}_2 \dots$

Here we regard  $\mathcal{F}_n$  as "the information available at time  $t = n$ ". There is no loss of information as time progresses and so the  $\sigma$ -field at time  $n+1$  is at least as big as the one at time  $n$ .

Example

Let  $\Omega = (0, 1]$ ,  $\mathcal{F}_0 = \{\emptyset, \Omega\}$ ,  $\mathcal{F}_1 = \{\emptyset, \Omega, (0, \frac{1}{2}], (\frac{1}{2}, 1]\}$  and  $\mathcal{F}_n = \{E : E = \bigcup_{k=1}^n J_k \text{ where } 0 < k \leq 2^n \text{ and } J_k \in \{(0, \frac{k}{2^n}], (\frac{k}{2^n}, \frac{(k+1)}{2^n}]\}, \dots, (1-\frac{1}{2^n}, 1]\}$

It is clear, that  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \dots \subseteq \mathcal{F}_n \subseteq \dots$

A natural question arises when we have a system like this: Suppose that we have an increasing family of  $\sigma$ -fields  $(\mathcal{F}_n)$  defined on  $\Omega$  with  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n \subseteq \dots \subseteq \mathcal{F}$ , where  $\mathcal{F}$  is some (large)  $\sigma$ -field on  $\Omega$  and suppose also  $\mathbb{P}$  is a probability measure on  $\mathcal{F}$ . Then  $\mathbb{P}$  is a probability measure on  $\mathcal{F}_n$  too. We think of  $(\Omega, \mathcal{F}, \mathbb{P})$  as being the probability space that governs the situation we are investigating while  $(\Omega, \mathcal{F}_n, \mathbb{P})$  is the probability space "of events known at time  $n$ ". One can think of  $(\Omega, \mathcal{F}_n, \mathbb{P})$  as an "estimate" of  $(\Omega, \mathcal{F}, \mathbb{P})$ . We are interested in the analysis of  $(\Omega, \mathcal{F}_n, \mathbb{P})$  and the ~~the~~ random variables associated with it. But all we know, at time  $n$ , is  $(\Omega, \mathcal{F}_n, \mathbb{P})$ , so we would like to predict things about objects associated with  $(\Omega, \mathcal{F}, \mathbb{P})$  by means of objects associated with  $(\Omega, \mathcal{F}_n, \mathbb{P})$ .

In order to give a mathematically precise idea of prediction we must digress.

Probabilistically Equivalent Random Variables

If  $X$  and  $Y$  are random variables on  $(\Omega, \mathcal{F}, \mathbb{P})$

and  $\mathbb{P}\{\omega: X(\omega) = Y(\omega) = 1\} = 1$  then we say  $X$

and  $Y$  are equivalent or  $\mathbb{P}$ -equivalent. For the

purposes of integration, and much probability theory,  $X$  and  $Y$  are the same random variable. So

from now on, for this section of the course, we

will identify random variables which are  $\mathbb{P}$ -equivalent

NB Precisely we define  $X \sim Y \Leftrightarrow X = Y$   $\mathbb{P}$ -a.s. Then

$\sim$  is an equivalence relation. We regard a random variable and the equivalence class it belongs to as the same thing. Addition of classes, etc are defined as follows, let  $\langle f \rangle$  denote the class of  $f$ .

$$\langle f \rangle + \langle g \rangle = \langle f + g \rangle,$$

$$\langle f \rangle \langle g \rangle = \langle fg \rangle,$$

$$\lambda \langle f \rangle = \langle \lambda f \rangle, \lambda \in \mathbb{R}.$$

END

Let  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  be the set of (equivalence classes of random variables,  $f$ , for which  $\int_{\Omega} |f(\omega)|^2 d\mathbb{P} < \infty$ )

Then, with the operations of addition and scalar multiplication defined above  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  is a

linear space:

norm on  $L^2$ , making it a complete normed

Further,  $\|f\| = \langle f, f \rangle^{1/2} = \left( \int_{\Omega} |f(\omega)|^2 dP \right)^{1/2}$  is a

so  $L^2$  is an inner product space.

Then  $\langle \cdot, \cdot \rangle$  is an inner product on  $L^2$ ,

Define,  $\langle f, g \rangle = \int_{\Omega} f(\omega)g(\omega) dP$   $f, g \in L^2$

In fact  $L^2(\Omega, \mathcal{F}, P)$  has even more structure

whenever  $\int_{\Omega} |f(\omega)|^2 dP < \infty$  and  $\int_{\Omega} |g(\omega)|^2 dP < \infty$ .

$$= 2 \int_{\Omega} |f(\omega)|^2 dP + 2 \int_{\Omega} |g(\omega)|^2 dP < \infty$$

$$= \int_{\Omega} (|f(\omega)+g(\omega)|^2 + |f(\omega)-g(\omega)|^2) dP$$

$$\int_{\Omega} |f(\omega)+g(\omega)|^2 dP \leq \int_{\Omega} |f(\omega)+g(\omega)|^2 dP + \int_{\Omega} |f(\omega)-g(\omega)|^2 dP \quad \textcircled{a}$$

$$\int_{\Omega} |f|^2 dP < \infty \text{ and } \lambda \in \mathbb{R}.$$

$$\int_{\Omega} |\lambda f|^2 dP = |\lambda|^2 \int_{\Omega} |f|^2 dP < \infty \text{ when} \quad \textcircled{b}$$

Insert 1

There is one fact about Hilbert spaces

I want you to learn here and now. It may seem rather curious to you at first but its use will make it sensible.

Let  $f, g \in \mathcal{H}$  a Hilbert space. Then

$$f = g \iff \forall h \in \mathcal{H} \langle f, h \rangle = \langle g, h \rangle.$$

In other words, if the inner products of  $f$  and  $g$  against any  $h$  in  $\mathcal{H}$  always agree they must be equal.

If you have not met norms yet, don't worry, you have met the idea of a metric space.

Now  $d(f, g) = \|f - g\| = \left( \int_{\Omega} |f - g|^2 dP \right)^{1/2}$  is a metric on  $L^2(\Omega, \mathcal{F}, P)$  and  $L^2$  is complete.

Recall that complete means every Cauchy sequence in the metric space converges to an element of the metric space.

For those that have met them,  $L^2(\Omega, \mathcal{F}, P)$  is a Hilbert space - a complete inner product space.

Consider now the two  $L^2$ -spaces  $L^2(\Omega, \mathcal{F}, P)$  and, for some fixed  $n \in \mathbb{N}$ ,  $L^2(\Omega, \mathcal{F}_n, P)$ .

Since  $\mathcal{F}_n \subseteq \mathcal{F}$  any  $\mathcal{F}_n$ -simple random variable is also  $\mathcal{F}$ -simple random variable. Hence

$L^2(\Omega, \mathcal{F}_n, P)$  is a subspace of  $L^2(\Omega, \mathcal{F}, P)$  and, as  $L^2(\Omega, \mathcal{F}_n, P)$  is complete, it is a closed subspace of  $L^2(\Omega, \mathcal{F}, P)$ . This means

simply that  $L^2(\Omega, \mathcal{F}_n, P)$  is a subspace of  $L^2(\Omega, \mathcal{F}, P)$  (as a vector space) and any Cauchy sequence in  $L^2(\Omega, \mathcal{F}_n, P)$  converges to something in  $L^2(\Omega, \mathcal{F}_n, P)$ .

At this point we need to import a result from the theory of Hilbert spaces. It is quite simple to state and easy to visualize and we will accept what it says without proof.

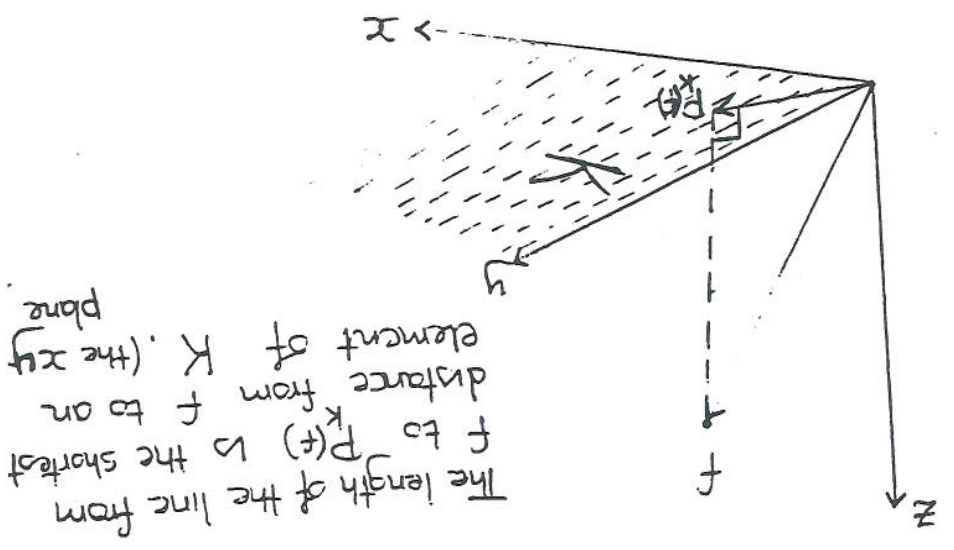
Theorem (H1)

Let  $H$  be a Hilbert space and  $K$  a closed linear subspace of  $H$ . If  $f \in H$  there is a unique element of  $K$ ,  $P^K(f)$  say, such that

$$\|f - P^K(f)\| \leq \|f - k\| \quad \forall k \in K.$$

In other words, there is, in  $K$ , a unique point which is closest to  $f$ .

Remark In  $\mathbb{R}^3$  - a Hilbert space - this amounts to nothing other than orthogonal projection.



The remarkable thing is that this picture holds good in any Hilbert space and hence in  $L^2(\Omega, \mathcal{F}, \mathbb{P})$ .

Returning, briefly, to our ideas of using objects associated with  $(\Omega, \mathcal{F}, \mathbb{P})$  to predict things about objects in  $(\Omega, \mathcal{F}, \mathbb{P})$  we see that if we restrict ourselves to  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  then there is a natural choice

of elements of  $L^2(\Omega, \mathcal{F}, \mathbb{P})$ . We simply take  $\nabla$

the element of  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  which is closest to

$f$ , i.e.  $P(f)$ .

$L^2(\Omega, \mathcal{F}, \mathbb{P})$

As  $f \in \mathcal{H}$  varies the values of  $P(f)$

will vary. There is a fundamental relationship

from which all of the properties of the

map  $f \mapsto P(f)$  follow it is,

$$\langle P(f), k \rangle = \langle f, k \rangle - **$$

for  $f \in \mathcal{H}$  and  $k \in K$ . This now becomes

an assumption of our course.

In the particular case where  $\mathcal{H}$  is

$L^2(\Omega, \mathcal{F}, \mathbb{P})$  and  $K$  is  $L^2(\Omega, \mathcal{G}, \mathbb{P})$ , for

some  $\sigma$ -field,  $\mathcal{G} \subseteq \mathcal{F}$ , the map  $P_K$  is

called the conditional expectation of  $f$

onto  $\mathcal{G}$ . Note that when  $\mathcal{G} \subseteq \mathcal{F}$ ,  $\mathcal{G}$  and  $\mathcal{F}$

$\sigma$ -fields on  $\Omega$  then  $L^2(\Omega, \mathcal{G}, \mathbb{P}) \subseteq L^2(\Omega, \mathcal{F}, \mathbb{P})$ ,

indeed  $L^2(\Omega, \mathcal{G}, \mathbb{P})$  is a subspace of  $L^2(\Omega, \mathcal{F}, \mathbb{P})$

Moreover, it is a closed subspace for

$L^2(\Omega, \mathcal{G}, \mathbb{P})$  is complete as a metric space.

## Properties of the Conditional Expectation

These fall into two parts. There are

those that follow from the fact that



it is the orthogonal projection onto a closed subspace of a Hilbert space, and those that arise from the fact that the Hilbert space is a space of random variables.

Theorem (M1)

Let  $M_g$  denote the orthogonal projection of  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  onto  $L^2(\Omega, \mathcal{G}, \mathbb{P})$ . Then,

(i)  $M_g$  is a linear mapping.

(ii)  $\|M_g(f)\| \leq \|f\|$

(iii) If  $f(\omega) \geq 0$  for  $\omega \in \Omega$  then  $M_g(f) \geq 0$  too.

(iv) If  $f \in \mathbb{C}$  then  $M_g(f) \in \mathbb{C}$  too.

(v)  $M_g(I_\Omega) = I_\Omega$

(vi)  $M_g \circ M_g = M_g$

(vii)  $M_g(fg) = M_g(f) \cdot g$  for  $f \in L^2(\Omega, \mathcal{F}, \mathbb{P})$  and  $g \in L^2(\Omega, \mathcal{G}, \mathbb{P})$ .

bounded  $g \in L^2(\Omega, \mathcal{G}, \mathbb{P})$ .  
 (viii)  $\mathbb{E}(M_g(f)) = \mathbb{E}(f)$ .

Proof

(i) For this situation  $\langle f, k \rangle = \int_\Omega f k d\mathbb{P}$ .

Note that,

$$\langle \alpha f_1 + \beta f_2, k \rangle = \int_\Omega (\alpha f_1 + \beta f_2) k d\mathbb{P} = \alpha \int_\Omega f_1 k d\mathbb{P} + \beta \int_\Omega f_2 k d\mathbb{P}$$

$$= \alpha \langle f_1, k \rangle + \beta \langle f_2, k \rangle$$

Now, from the fact that  $\langle M_g(f), k \rangle = \langle f, k \rangle$

Now this is true for every  $k$  in  $L^2(\Omega, \mathbb{F}, \mathbb{P})$ . This means that  $M_G(\alpha f_1 + \beta f_2) = \alpha M_G(f_1) + \beta M_G(f_2)$ .

In a Hilbert space, if  $\langle x, k \rangle = \langle y, k \rangle$  for all  $k$  then in particular  $\langle x, x-y \rangle = \langle y, x-y \rangle$  i.e.  $\langle x-y, x-y \rangle = 0$  or  $\|x-y\|^2 = 0$  (i.e.  $d(x,y) = 0$ ) so  $x=y$ .

(vi) Recall that  $M_G(f)$  is the element of  $L^2(\Omega, \mathbb{G}, \mathbb{P})$  which is closest to  $f$ . If  $f$  is actually in  $L^2(\Omega, \mathbb{G}, \mathbb{P})$  this must be  $f$  itself, so  $M_G(M_G(f)) = M_G(f)$ .

(v)  $\Omega \in \mathcal{G}$  so  $I_\Omega \in L^2(\Omega, \mathbb{G}, \mathbb{P})$  so  $M_G(I_\Omega) = I_\Omega$  by (vi).

(ii) Observe  $\langle f, k \rangle = \int_{\Omega} f k d\mathbb{P} = \int_{\Omega} k f d\mathbb{P} = \langle k, f \rangle$ .

From the relation,  $**$ ,

$$\langle M_G(f), k \rangle = \langle f, k \rangle$$

We reason that

$$\langle M_G(f), M_G(f) \rangle = \langle f, M_G(f) \rangle = \langle M_G(f), f \rangle$$

Now  $f = M_G(f) + f - M_G(f)$  so,

$$\langle f, f \rangle = \langle M_G(f) + (f - M_G(f)), M_G(f) + (f - M_G(f)) \rangle$$

$$= \langle M_G(f), M_G(f) \rangle + \langle f - M_G(f), f - M_G(f) \rangle$$

$$\langle f - M_G(f), M_G(f) \rangle + \langle f - M_G(f), f - M_G(f) \rangle$$

Now

$$\langle M_g(f), f - M_g(f) \rangle = \langle f - M_g(f), M_g(f) \rangle$$

using the relation  $**$  =  $\langle M_g(f - M_g(f)), M_g(f) \rangle$

$$= \langle M_g(f) - M_g(M_g(f)), M_g(f) \rangle$$

and as  $M_g$  is linear

$$= \langle M_g(f), M_g(f) \rangle - \langle M_g(M_g(f)), M_g(f) \rangle$$

which by (v) is

$$= \langle 0, M_g(f) \rangle$$

$$= 0.$$

$$\text{So } \|f\|^2 = \langle f, f \rangle = \langle M_g(f), M_g(f) \rangle + \langle f - M_g(f), f - M_g(f) \rangle$$

$$= \|M_g(f)\|^2 + \|f - M_g(f)\|^2$$

$$\geq \|M_g(f)\|^2 \text{ proving (ii).}$$

(iii) Let  $g = I_{\{w: M_g(f) < 0\}}$  then as  $f \geq 0$ ,

$$0 \leq \int fg \, dP \text{ and so } 0 \leq \int fg \, dP \text{ but note}$$

that  $\{w: M_g(f) < 0\} \in \mathcal{G}$  so  $g \in L^2(\Omega, \mathcal{G}, P)$

hence,

$$0 \leq \int fg \, dP = \langle f, g \rangle = \langle M_g(f), g \rangle \text{ by } **$$

$$= \int_{M_g(f) < 0} M_g(f) \, dP$$

$$\leq 0 \text{ So } \int_{M_g(f) < 0} M_g(f) \, dP = 0$$