

*L<sub>p</sub> spaces.*

For  $p \geq 1$ , the  $L_p$  spaces  $L_p(\mathbb{R}^k)$  on  $\mathbb{R}^k$  are the spaces of measurable functions  $f$  with  $L_p$ -norm

$$\|f\|_p := \left( \int |f|^p \right)^{\frac{1}{p}} < \infty.$$

*Riemann integrals.*

Our first exposure to integration is the ‘Sixth-Form integral’, taught non-rigorously at school. Mathematics undergraduates are taught a rigorous integral (in their first or second years), the *Riemann integral* [G.B. RIEMANN (1826-1866)] – essentially this is just a rigourization of the school integral. It is much easier to set up than the Lebesgue integral, but much harder to manipulate.

For finite intervals  $[a, b]$ , we quote:

- (i) for any function  $f$  Riemann-integrable on  $[a, b]$ , it is Lebesgue-integrable to the same value (but many more functions are Lebesgue integrable),
- (ii)  $f$  is Riemann-integrable on  $[a, b]$  iff it is continuous a.e. on  $[a, b]$ . Thus the question, “Which functions are Riemann-integrable?” cannot be answered without the language of measure theory – which then gives one the technically superior Lebesgue integral anyway.

*Note.* Integration is like summation (which is why Leibniz gave us the integral sign  $\int$ , as an elongated S). Lebesgue was a very practical man – his father was a tradesman – and used to think about integration in the following way. Think of a shopkeeper totalling up his day’s takings. The Riemann integral is like adding up the takings – notes and coins – *in the order in which they arrived*. By contrast, the Lebesgue integral is like totalling up the takings *in order of size* - from the smallest coins up to the largest notes. This is obviously better! In mathematical effect, it exchanges ‘integrating by  $x$ -values’ (abscissae) with ‘integrating by  $y$ -values (ordinates).

*Lebesgue-Stieltjes integral.*

Suppose that  $F(x)$  is a *non-decreasing* function on  $\mathbb{R}$ :

$$F(x) \leq F(y) \quad \text{if } x \leq y$$

(prime example:  $F$  a probability distribution function). Such functions can have at most countably many discontinuities, which are at worst jumps. We may without loss re-define  $F$  at jumps so as to be *right-continuous*.

We now generalise the starting points above:

(i) *Measure*. We take  $\mu((a, b]) := F(b) - F(a)$ .

(ii) *Integral*. We take  $\int_a^b 1 := F(b) - F(a)$ .

We may now follow through the successive extension procedures used above.

We obtain:

(i) *Lebesgue-Stieltjes measure*  $\mu$ , or  $\mu_F$ ,

(ii) *Lebesgue-Stieltjes integral*  $\int f d\mu$ , or  $\int f d\mu_F$ , or even  $\int f dF$ .

Similarly in higher dimensions; we omit further details.

*Finite variation*.

If instead of being monotone non-decreasing,  $F$  is the *difference* of two such functions,  $F = F_1 - F_2$ , we can define the integrals  $\int f dF_1$ ,  $\int f dF_2$  as above, and then define

$$\int f dF = \int f d(F_1 - F_2) := \int f dF_1 - \int f dF_2.$$

If  $[a, b]$  is a finite interval and  $F$  is defined on  $[a, b]$ , a finite collection of points,  $x_0, x_1, \dots, x_n$  with  $a = x_0 < x_1 < \dots < x_n = b$ , is called a *partition* of  $[a, b]$ ,  $\mathcal{P}$  say. The sum  $\sum_{i=1}^n |F(x_i) - F(x_{i-1})|$  is called the *variation* of  $F$  over the partition. The least upper bound of this over all partitions  $\mathcal{P}$  is called the *variation* of  $F$  over the interval  $[a, b]$ ,  $V_a^b(F)$ :

$$V_a^b(F) := \sup_{\mathcal{P}} \sum |F(x_i) - F(x_{i-1})|.$$

This may be  $+\infty$ ; but if  $V_a^b(F) < \infty$ ,  $F$  is said to be of *finite variation* on  $[a, b]$ ,  $F \in FV_a^b$  (*bounded variation*, BV, is also used). If  $F$  is of finite variation on all finite intervals,  $F$  is said to be *locally of finite variation*,  $F \in FV_{loc}$ ; if  $F$  is of finite variation on the real line,  $F$  is of *finite variation*,  $F \in FV$ .

We quote (*Jordan's theorem*) that the following are equivalent:

(i)  $F$  is locally of finite variation,

(ii)  $F$  can be written as the difference  $F = F_1 - F_2$  of two monotone functions.

So the above procedure defines the integral  $\int f dF$  when the *integrator*  $F$  is of *finite variation*.

### 3 Probability.

#### *Probability spaces.*

The mathematical theory of probability can be traced to 1654, to correspondence between PASCAL (1623-1662) and FERMAT (1601-1665). However, the theory remained both incomplete and non-rigorous till the 20th century. It turns out that the Lebesgue theory of measure and integral sketched above is exactly the machinery needed to construct a rigorous theory of probability adequate for modelling reality (option pricing, etc.) for us. This was realised by the great Russian mathematician and probabilist A.N.KOLMOGOROV (1903-1987), whose classic book of 1933, *Grundbegriffe der Wahrscheinlichkeitsrechnung* [Foundations of probability theory] inaugurated the modern era in probability.

Recall from your first course on probability that, to describe a random experiment mathematically, we begin with the *sample space*  $\Omega$ , the set of all possible outcomes. Each point  $\omega$  of  $\Omega$ , or *sample point*, represents a possible – random – outcome of performing the random experiment. For a set  $A \subseteq \Omega$  of points  $\omega$  we want to know the probability  $P(A)$  (or  $\Pr(A)$ ,  $\text{pr}(A)$ ). We clearly want

1.  $P(\emptyset) = 0$ ,  $P(\Omega) = 1$ ,
2.  $P(A) \geq 0$  for all  $A$ ,
3. If  $A_1, A_2, \dots, A_n$  are disjoint,  $P(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n P(A_i)$  (finite additivity), which, as above we will strengthen to
- 3\*. If  $A_1, A_2 \dots$  (*ad inf.*) are disjoint,

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i) \quad (\text{countable additivity}).$$

4. If  $B \subseteq A$  and  $P(A) = 0$ , then  $P(B) = 0$  (completeness).
- Then by 1 and 3 (with  $A = A_1$ ,  $\Omega \setminus A = A_2$ ),

$$P(A^c) = P(\Omega \setminus A) = 1 - P(A).$$

So the class  $\mathcal{F}$  of subsets of  $\Omega$  whose probabilities  $P(A)$  are defined should be closed under countable, disjoint unions and complements, and contain the empty set  $\emptyset$  and the whole space  $\Omega$ . Such a class is called a  $\sigma$ -*field* of subsets of  $\Omega$  [or sometimes a  $\sigma$ -algebra, which one would write  $\mathcal{A}$ ]. For each  $A \in \mathcal{F}$ ,  $P(A)$  should be defined (and satisfy 1, 2, 3\*, 4 above). So,  $P : \mathcal{F} \rightarrow [0, 1]$  is a set-function,

$$P : A \mapsto P(A) \in [0, 1] \quad (A \in \mathcal{F}).$$

The sets  $A \in \mathcal{F}$  are called *events*. Finally, 4 says that all subsets of null-sets (events) with probability zero (we will call the empty set  $\emptyset$  empty, not null) should be null-sets (completeness). A *probability space*, or *Kolmogorov triple*, is a triple  $(\Omega, \mathcal{F}, P)$  satisfying these *Kolmogorov axioms* 1,2,3\*,4 above. A probability space is a mathematical model of a random experiment.

*Random variables.*

Next, recall random variables  $X$  from your first probability course. Given a random outcome  $\omega$ , you can calculate the value  $X(\omega)$  of  $X$  (a scalar – a real number, say; similarly for vector-valued random variables, or random vectors). So,  $X$  is a function from  $\Omega$  to  $\mathbb{R}$ ,  $X \rightarrow \mathbb{R}$ ,

$$X : \omega \rightarrow X(\omega) \quad (\omega \in \Omega).$$

Recall also that the *distribution function* of  $X$  is defined by

$$F(x), \quad \text{or} \quad F_X(x), \quad := P\left(\{\omega : X(\omega) \leq x\}\right), \quad \text{or} \quad P(X \leq x), \quad (x \in \mathbb{R}).$$

We can only deal with functions  $X$  for which all these probabilities are defined. So, for each  $x$ , we need  $\{\omega : X(\omega) \leq x\} \in \mathcal{F}$ . We summarize this by saying that  $X$  is *measurable* with respect to the  $\sigma$ -field  $\mathcal{F}$  (of events), briefly,  $X$  is  $\mathcal{F}$ -*measurable*. Then,  $X$  is called a *random variable* [non- $\mathcal{F}$ -measurable  $X$  cannot be handled, and so are left out]. So,

- (i) a random variable  $X$  is an  $\mathcal{F}$ -measurable function on  $\Omega$ ,
- (ii) a function on  $\Omega$  is a random variable (is measurable) iff its distribution function is defined.

*Generated  $\sigma$ -fields.*

The smallest  $\sigma$ -field containing all the sets  $\{\omega : X(\omega) \leq x\}$  for all real  $x$  [equivalently,  $\{X < x\}$ ,  $\{X \geq x\}$ ,  $\{X > X\}$ ] is called the  $\sigma$ -field *generated* by  $X$ , written  $\sigma(X)$ . Thus,

$$X \text{ is } \mathcal{F}\text{-measurable [is a random variable] iff } \sigma(X) \subseteq \mathcal{F}.$$

When the (random) value  $X(\omega)$  is *known*, we know *which* of the events in the  $\sigma$ -field generated by  $X$  have happened: these are the events  $\{\omega : X(\omega) \in B\}$ , where  $B$  runs through the Borel  $\sigma$ -field [the  $\sigma$ -field generated by the intervals] on the line.